

Inexpensive but robust approaches for determining optical and biogeochemical properties

Mike Twardowski and Wayne Slade

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The problem: sensors are too expensive to be deployed at large quantities on the scales of interest to coastal populations (e.g. resolve tides, weather and beaches, be deployed in the developing world).

=> limits significantly the relevant and available data.

Why is it so?

1. Pressure-resistant housing (most in-situ sensors are rated to 600m).
2. Accuracy requirement (e.g. to trace deep water masses).
3. Limited market.
4. Limited resources for some research groups and communities.

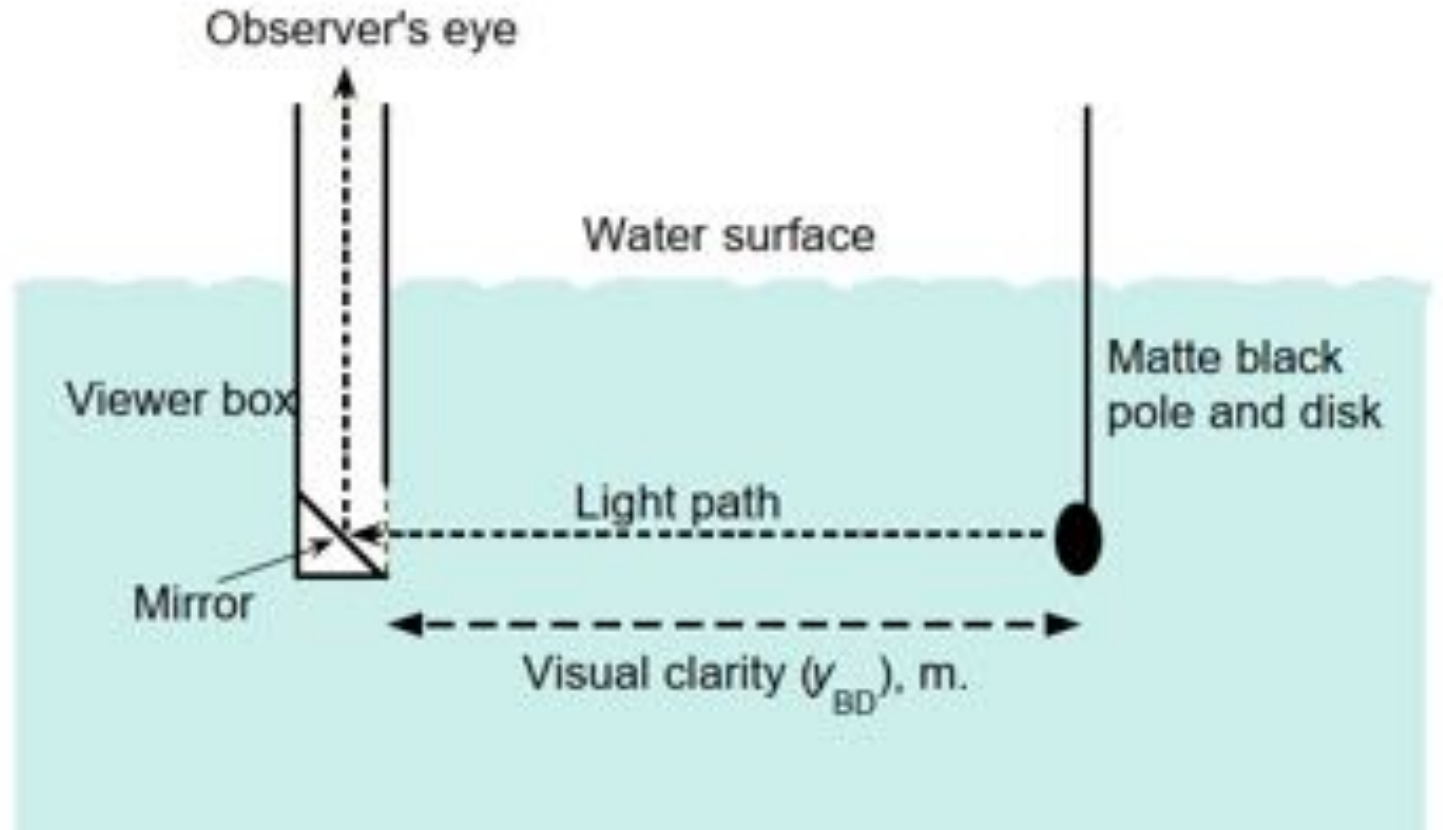
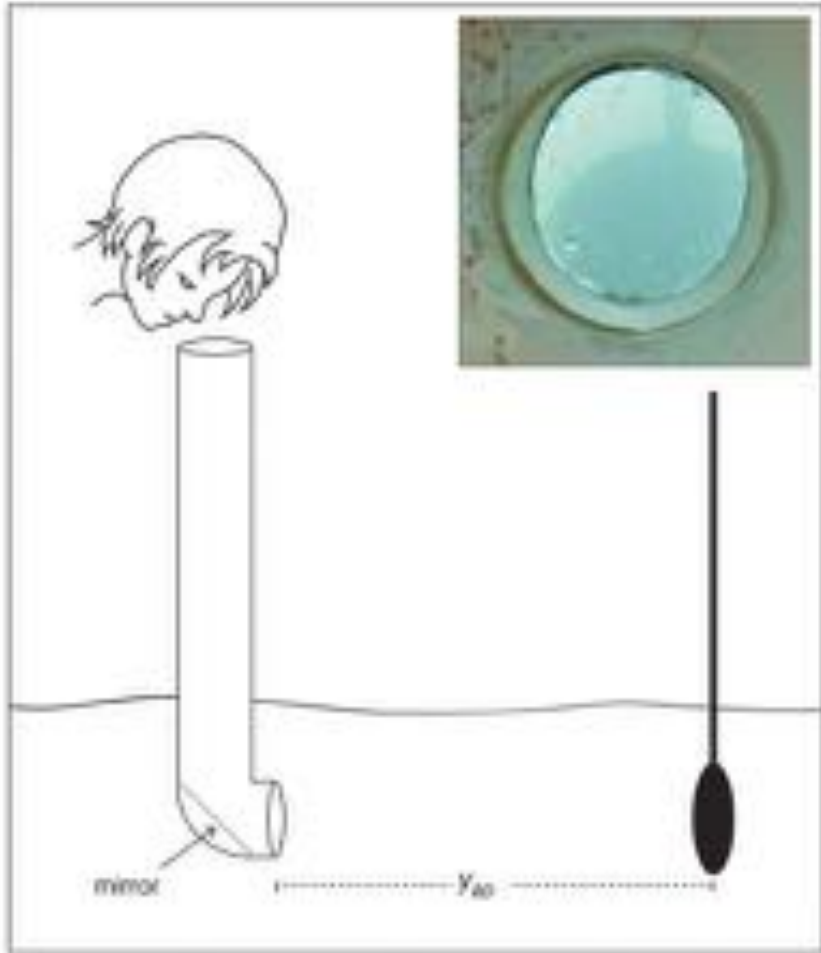
What can we do to change this situation?

1. Much of the data of interest is near surface.
2. Near the surface natural variability is large.
3. Bringing in industry (aquaculture, fisheries, tourism) creates a much larger market than science.
4. There are inexpensive but robust alternatives in some cases.

Additionally, a revolution is going on → cheap electronics processors, communication and sharing.

1. Cheap microprocessors such as Arduino and Raspberry Pi have made building a sensor and/or a sensing platform a Lego-like activity.
2. Communication via cell-phone, Wi-Fi and sat-com, provide near-real time data (e.g. for QC and adaptive sampling and incorporation to forecast).
3. Sharing of 'recipes' and ideas within/across communities allow for fast evolution and bug fixes (e.g. GitHub, instructables, Make magazine).
4. However, it is critical that uncertainties be associated with all measurements. Better to have **no** measurements than **bad** ones.
5. Full sensor characterizations essential for any custom device.

Attenuation (c) from horizontal vis with a black disk



Equipment list

Black disc method



tape measure



black disc viewer



black disc pole

Zaneveld and Pegau (2003)

$$V = 4.8/\alpha$$

α = photopic attenuation

$$\alpha = c_{pg}(532)*0.9 + 0.081$$

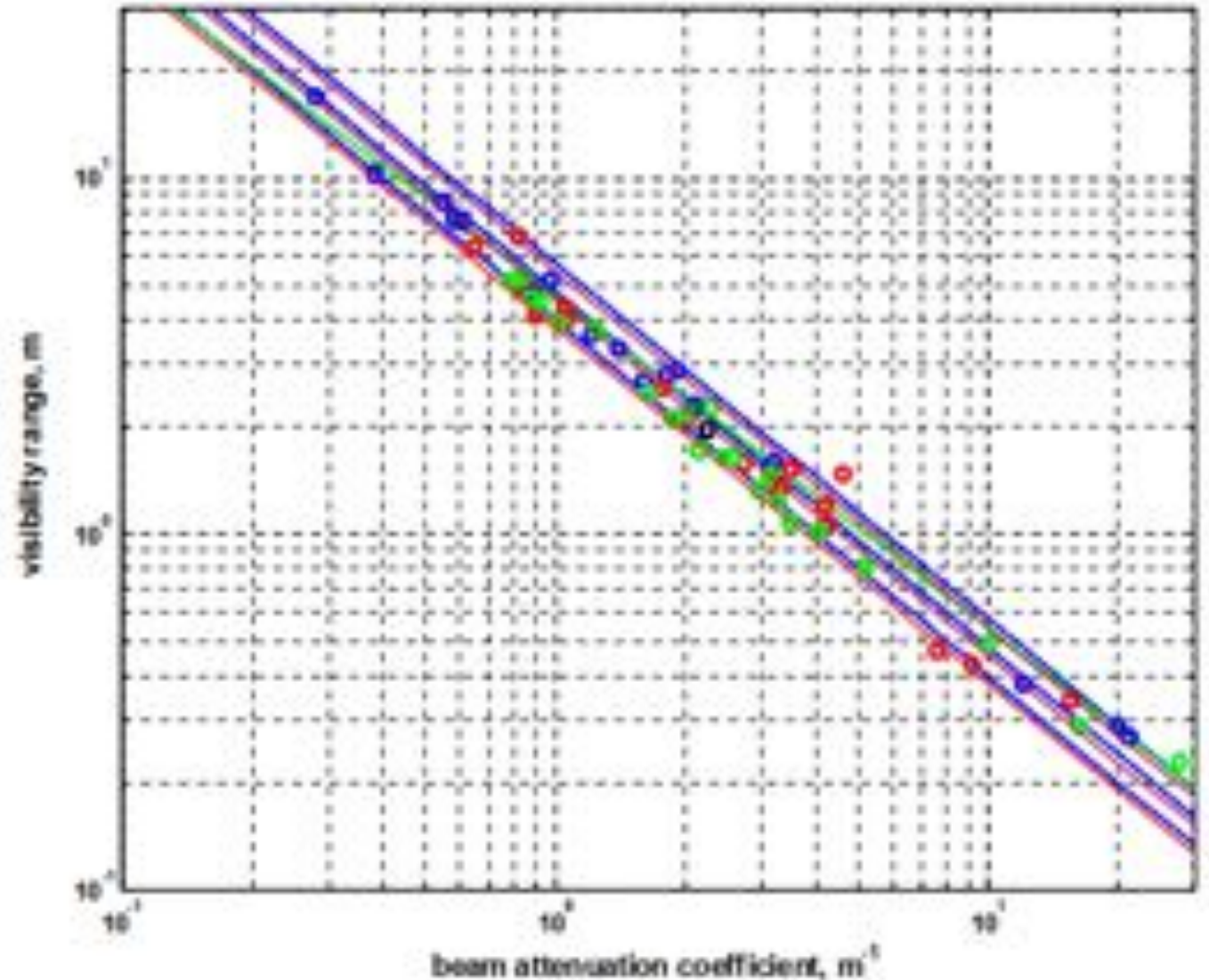


Fig. 3. Horizontal visibility of a 200 mm diameter black target. Blue points, Davies-Colley, "green" c-meter; red points, Zaneveld, $c_{pg}(532)*0.9+0.081$; black point, Twardowski $c_{pg}(532)*0.9+0.081$; green points, Pegau, $c_{pg}(532)*0.9+0.081$; blue lines vis. range = $y = 4.8/x$ and $\pm 20\%$ lines; green line vis. range = $y = (5.207 - 0.568 \ln x)/x$; red lines vis. range = $y = 4.55/x$ and $\pm 20\%$ lines; $r^2 = 0.983$.

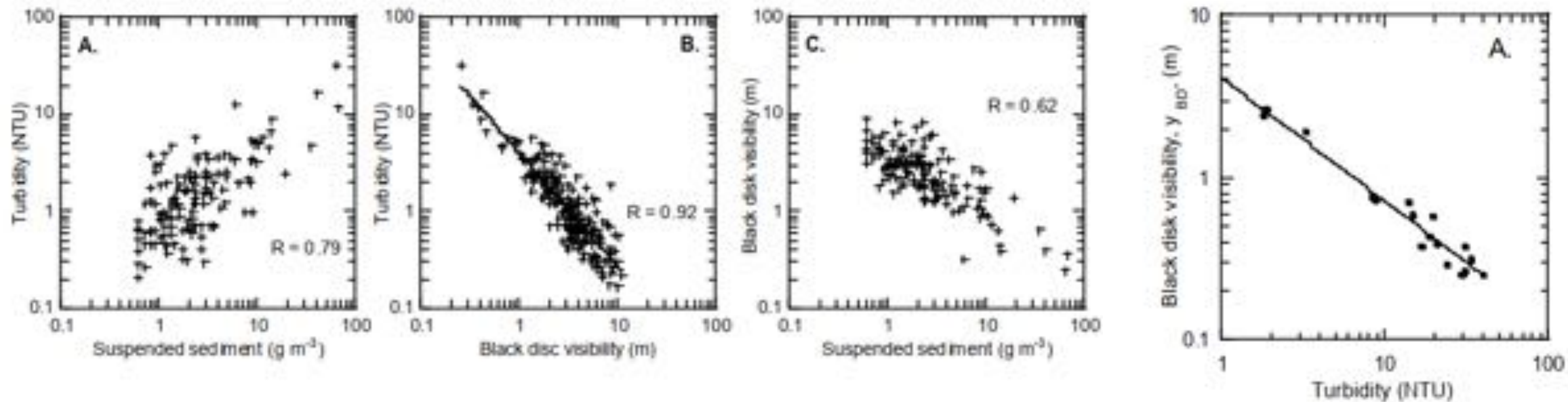
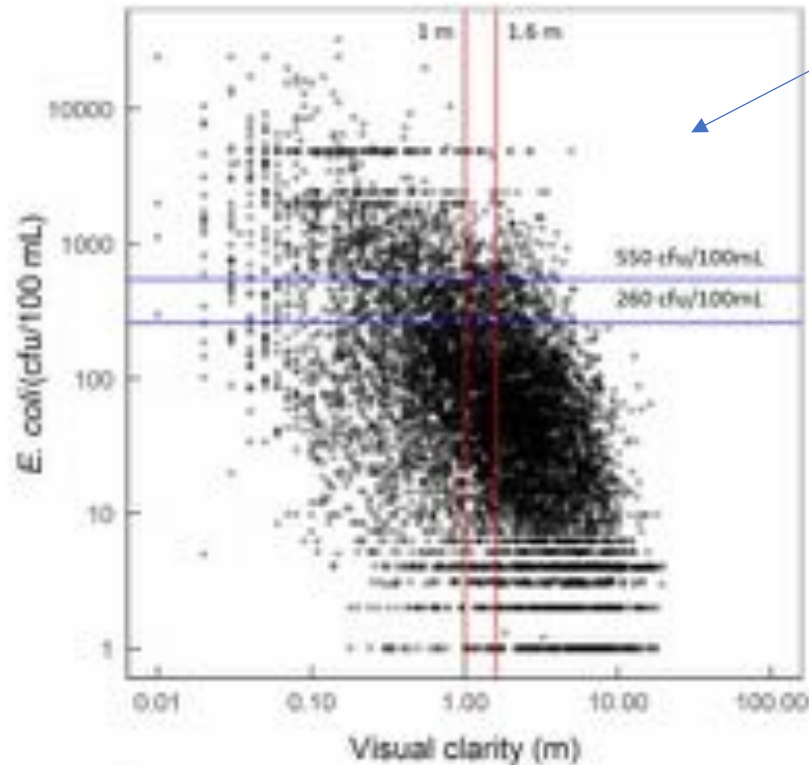


Figure 2. Mutual relationships of visual clarity, turbidity (Hach 2100A) and suspended sediment concentration in 97 New Zealand rivers (each river site sampled up to three times— $n = 274$ in total). Panel A. turbidity versus suspended sediment, B. turbidity versus black disc visibility, C. black disc visibility versus SSC. (Figure 3 of Davies-Colley and Close, 1990—used with permission)

Faecal contamination and visual clarity in New Zealand rivers: correlation of key variables affecting swimming suitability

Rob Davies-Colley, Amanda Valois and Juliet Milne

Journal of Water and Health
2018



<1% samples fall in high E. coli, high vis quadrant

action alert

<1.6 horizontal vis has been official Ministry for the Environment criteria for safe to swim in NZ since 1994

<https://environment.govt.nz/assets/Publications/Files/microbiological-quality-jun03.pdf>

Figure 4 | E. coli vs visual clarity at 64 river sites in the NWQCR, 2006–2015, in relation to existing guidelines for swimming water quality in NZ. The horizontal lines represent ALERT (260 cfu/100 mL) and ACTION (550 cfu/100 mL) levels for E. coli from MfE/MoH (2003); the vertical lines represent guidelines for visual clarity (1.6 m is from MfE (1994) and 1.0 m an indicative – informal – guideline for visual degradation of water appearance). Only about 1% of points fall into the top-right sector representing relatively high microbial risk (> 550 cfu/100 mL) when water is relatively clear (> 1.6 m).

Tube with black disk

Depending on arm length, one person can take a clarity tube reading (far right), or it may be easier with two people.



Ministry for the Environment 1994. "Water Quality Guidelines No. 2: Guidelines for the Management of water colour and clarity". Ministry for the Environment, Wellington, N.Z

Equipment list

Clarity tube method



bucket



clarity tube



magnets







50

AQUA MEDIC



Fig. 1 SHMAK clarity tube for measuring water clarity. (Photo: Helen Ricketts.)

$$y_{BD} = 7.28 \times 10^{[y_{CT} / 62.5]}$$

NZ safe to swim: >1 m vis with black disk in tube

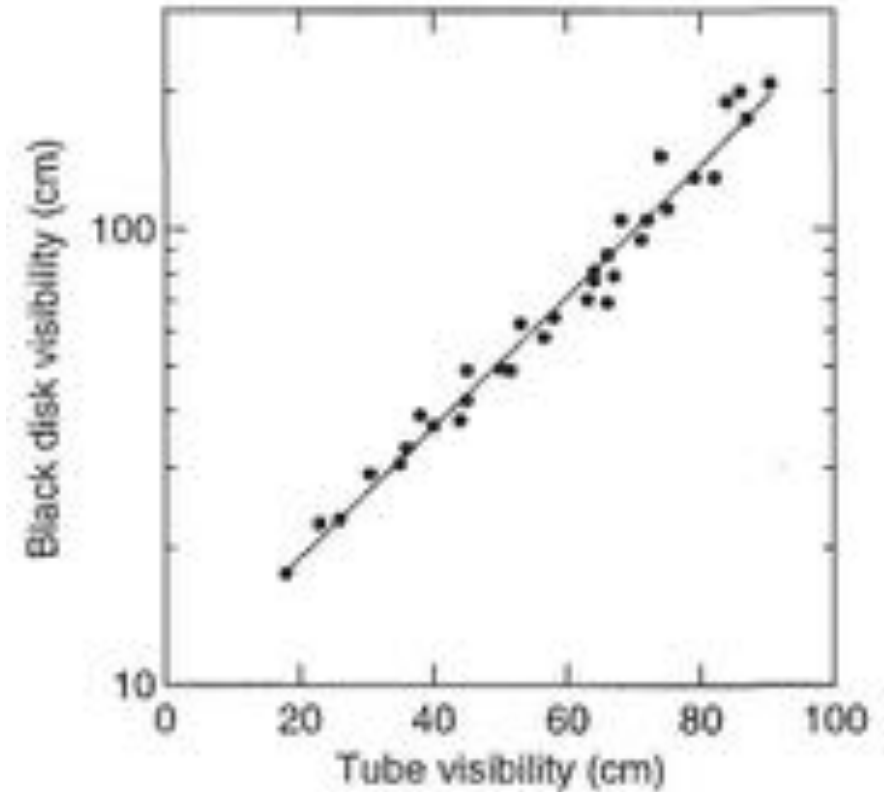


Fig. 4 Black disk readings (logarithmic scale) versus clarity tube readings (y_{BD} versus y_{CT}) (black background).

Secchi disk depth: theory

Contrast reduction theory for detecting target for any direction:

$$\frac{C_r(\theta, \phi, r)}{C_0(\theta, \phi, 0)} = \exp[-cr + K(\theta, \phi, z) r \cos(\theta)]$$

Diagram illustrating the components of the equation:

- $C_r(\theta, \phi, r)$: apparent contrast of target
- $C_0(\theta, \phi, 0)$: inherent contrast of target
- c : attenuation coefficient
- r : range
- $K(\theta, \phi, z)$: diffuse attenuation coefficient
- θ : viewing angle relative to straight up



Parameters are for *photopic* spectral response

Preisendorfer (1963), Duntley (1976) but work originated in 1940's; extensively validated

Secchi disk depth: theory

Contrast reduction theory for detecting target for any direction:

$$\frac{C_r(\theta, \phi, z)}{C_0(\theta, \phi, z_T)} = \exp[-cr + K(\theta, \phi, z) r \cos(\theta)]$$

At some range, contrast between a target and background will no longer be discernible, i.e., the limiting contrast threshold will have been reached:

$$C_L \equiv \frac{C_r(\theta, \phi, z)}{C_0(\theta, \phi, z_T)}, \text{ and}$$

$$V = -\ln(C_L) / [c - K(\theta, \phi, z) \cos(\theta)]$$

For Secchi disk: $Z_{SD} = -\ln(C_L) / [c + K]$



Issues

$$\textit{For Secchi disk: } Z_{SD} = -\ln(C_L) / [c + K]$$

- When Z_{SD} , c , and K are determined, large range observed in $-\ln(C_L)$
- White vs black vs black/white quadrants
- Size of disk
- Reflectivity of disk
- Shady side vs sunny side (i.e., glint)
- Cloudy vs sunny
- Wavy surface
- Sun elevation
- Scattering albedo (b/c)
- Eye adaptation to ambient lighting
- Observing altitude above water

$-\ln(C_L)$ typically varies from ~5-10 (Bukata 2005)





All noted by Secchi in 19th century (Pitarch 2020)



Article

A Printable Device for Measuring Clarity and Colour in Lake and Nearshore Waters

Robert J. W. Brewin ^{1,2,*,†} , Thomas G. Brewin ^{3,†}, Joseph Phillips ^{3,4}, Sophie Rose ^{3,4}, Anas Abdulaziz ⁵ , Werenfrid Wimmer ⁶, Shubha Sathyendranath ^{1,2} and Trevor Platt ¹

Using a view box

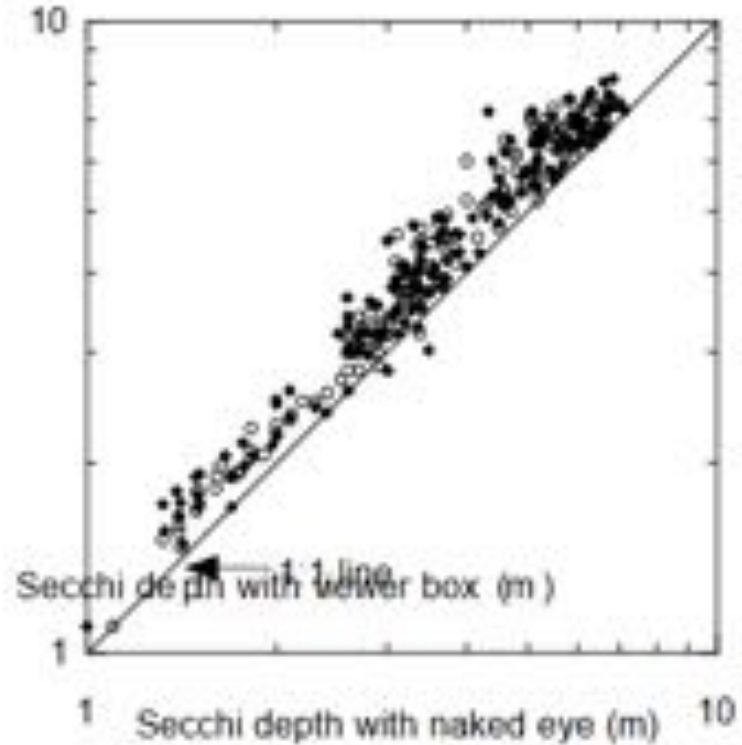


Figure 1. Relationship between Secchi depth measurements made with the aid of a viewer box and the naked eye. The open and closed symbols refer to measurements made on the sunny and shady side of the boat, respectively.



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Secchi disk depth: A new theory and mechanistic model for underwater visibility




ZhongPing Lee ^{a,*}, Shaoling Shang ^{b,*}, Chuanmin Hu ^c, Keping Du ^d, Alan Weidemann ^e, Weilin Hou ^e, Junfang Lin ^a, Gong Lin ^b

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ASLO

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Resolving the long-standing puzzles about the observed Secchi depth relationships

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A new theory for Secchi depths

For 150 years, oceanographers have assessed water clarity using a simple, robust method first devised by an Italian priest. Until recently, however, researchers have struggled to match field observations made using these 'Secchi disks' to theoretical models. Through dedicated research, Dr ZhongPing Lee at the University of Massachusetts, Boston, and colleagues from other institutes in China and the USA, have revolutionised the theory and model regarding this depth, and obtained results consistent with nearly a century of past observations. The methods have become

Covering roughly 71% of our planet's surface, the water contained in oceans and lakes underpins the survival of many different ecosystems, both marine and land based. Yet increasingly, human activities are altering several key characteristics of aquatic environments worldwide – including their temperatures and populations of microscopic organisms – each of which are inflicting various levels of damage on the ecosystems. To determine the influence of these changes, researchers have developed a wide variety of techniques to assess water quality.

Among the most popular and important probes for the quality of water is its



Some controversy....

Lee et al. (2015)

Secchi disk depth: A new theory and mechanistic model for underwater visibility



ZhongPing Lee ^{a,*}, Shaoling Shang ^{b,*}, Chuanmin Hu ^c, Keping Du ^d, Alan Weidemann ^e, Weilin Hou ^e, Junfang Lin ^a, Gong Lin ^b

1. Questions path radiance being same over target vs adjacent background
 - Background path radiance will be brighter directly adjacent to a white disk target, but this effect diminishes to nil near secchi disk depth
 - Makes an exception for horizontal viewing: “This may occur because most of the surrounding light over the target and the background are strong radiances in the horizontal directions as demonstrated with field observations (Zaneveld and Pegau, 2003).”
2. Questions contrast definition as $[L_T - L_B] / L_B$
 - This is Weber contrast definition that has been validated extensively throughout many disciplines
 - Suggests we should be using absolute radiance differences only

Justification given as size of disk relative to spatial resolving capability of human eye

- “Due to this extremely fine resolution of the human eye, the relationship between the pixel size of the collected image and the size of a target will depend on the distance (z) and the size of the target”
 - This is spatial frequency (Hou et al. 2007)
 - But doesn't obviously explain reasoning for 1+2 (at least for me)

Visibility ranges from modulation transfer function (MTF) imaging theory

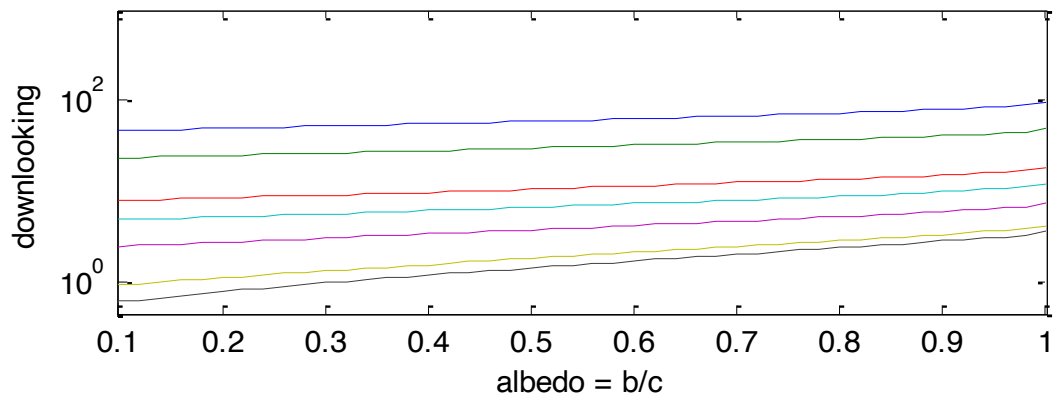
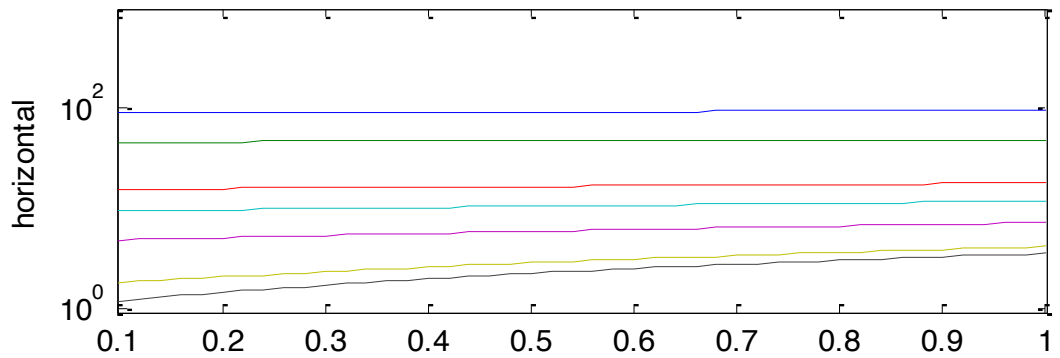
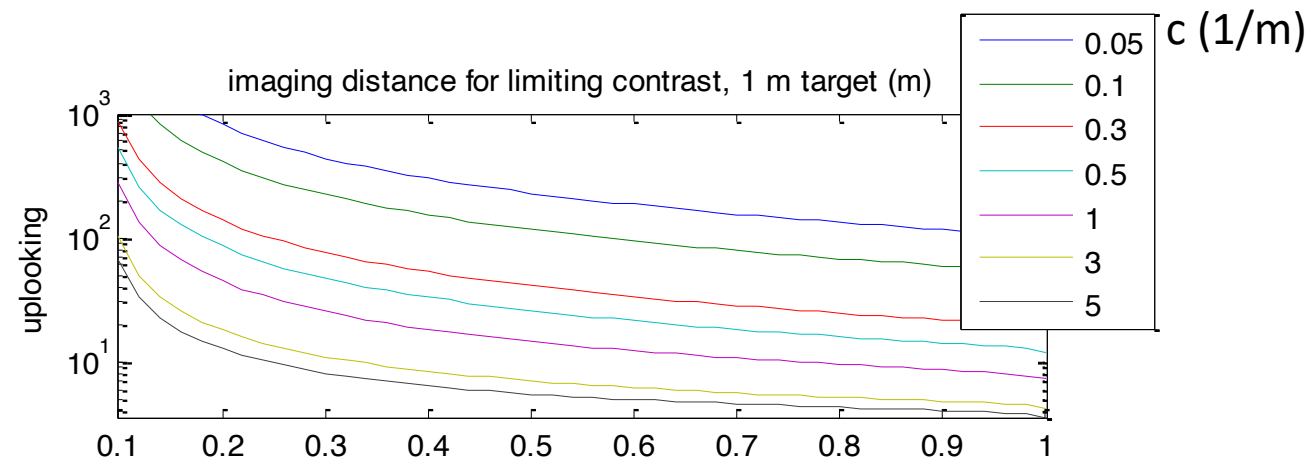
Using relationships from Hou, Lee, Weidemann (2007), the following can be derived:

$$V = \frac{1}{c - \cos(\theta_v)K} \left[-\ln \left(\frac{C_L}{2M_0} \right) + \frac{bd}{4\pi\theta_0} \right]$$

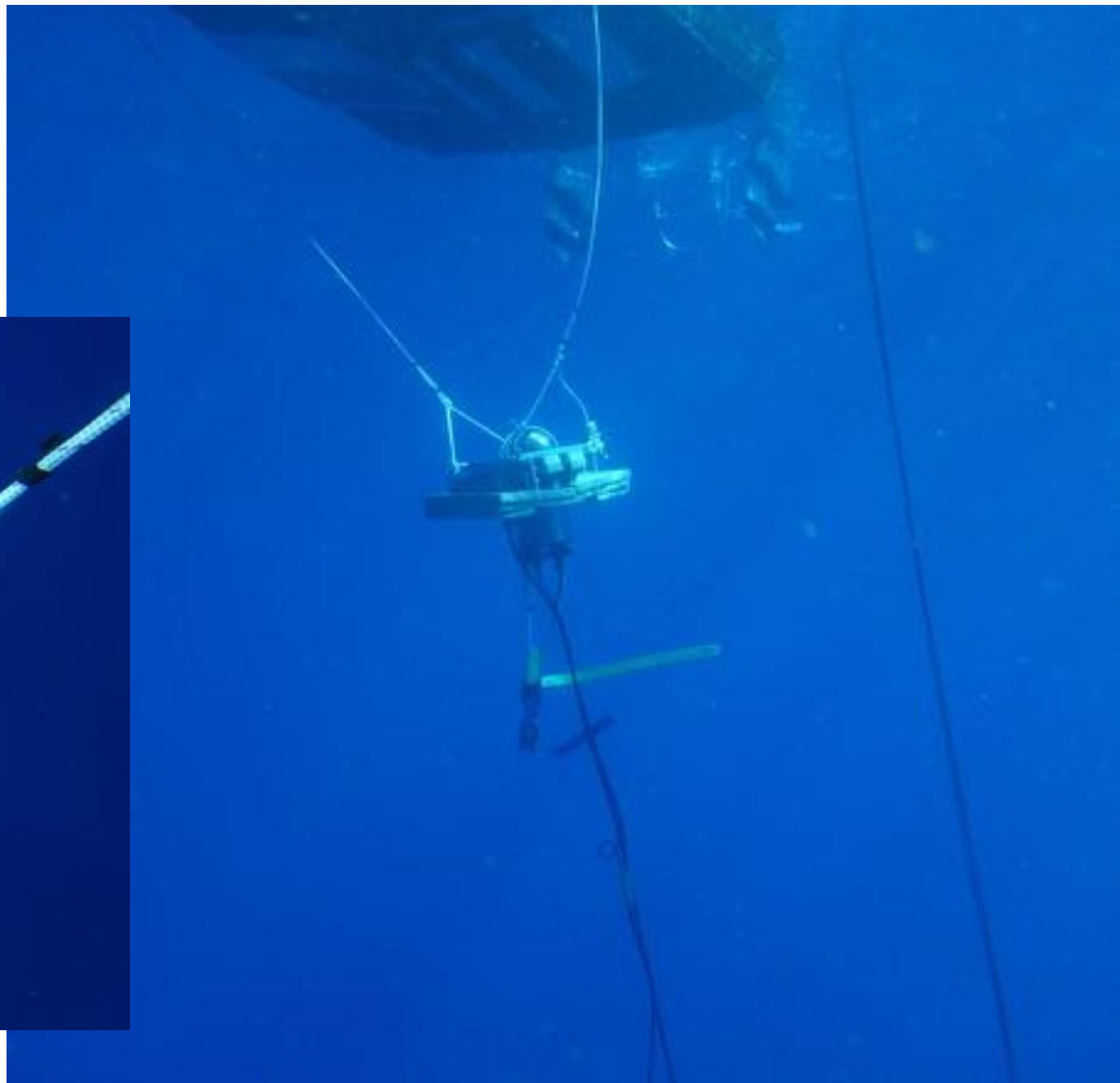
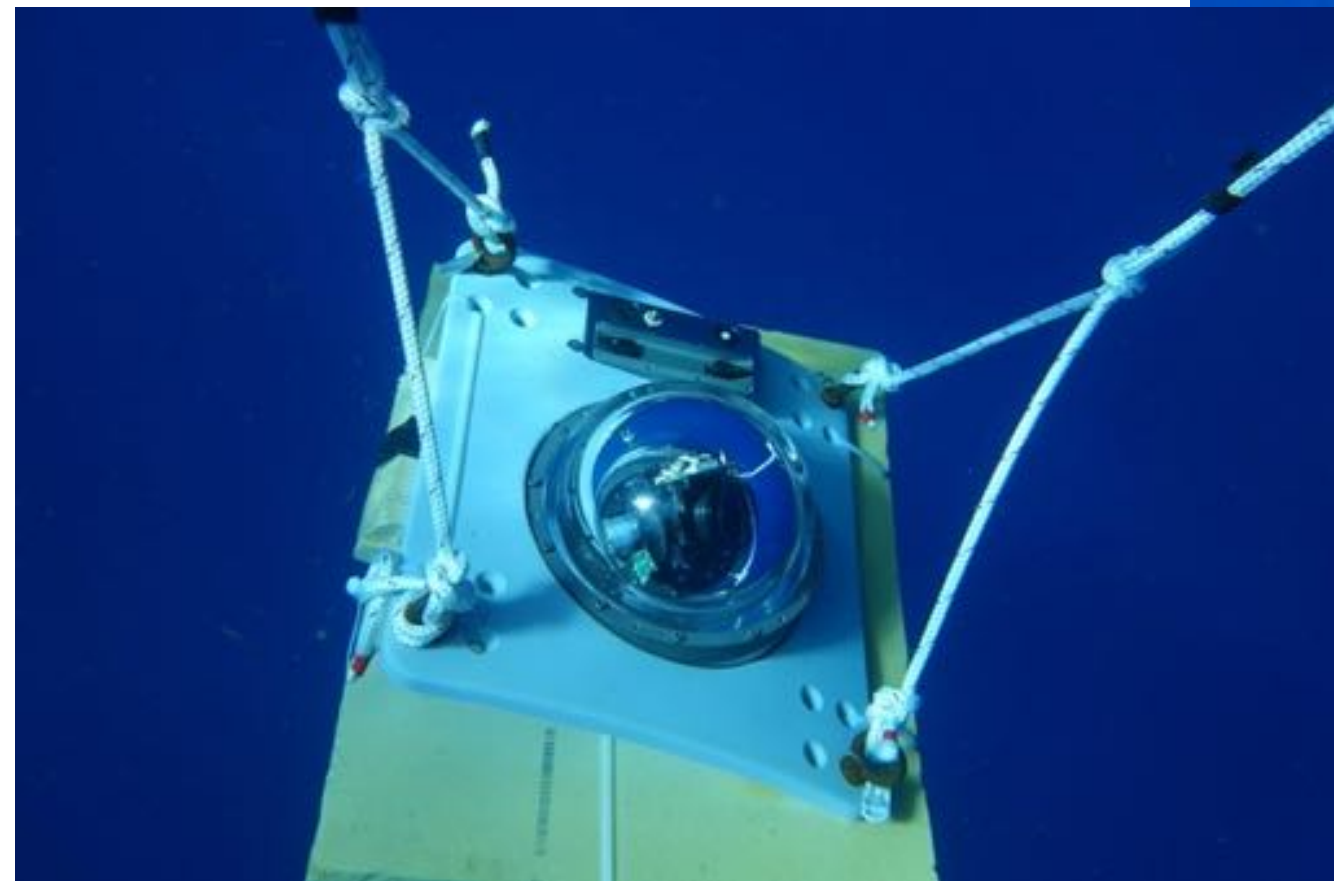
Limiting contrast of detector (~0.02 for human eye) $\rightarrow C_L$
 total scattering $\rightarrow b$
 disk size $\rightarrow d$
 Looking up: $\theta_v = 0$ deg $\rightarrow \cos(\theta_v)$
 Looking horizontal: $\theta_v = 90$ deg $\rightarrow \cos(\theta_v)$
 Looking down (Secchi): $\theta_v = 180$ deg $\rightarrow \cos(\theta_v)$
 Source modulation (contrast) Equal to 1 for black/white $\rightarrow M_0$
 term for near forward scattering $\rightarrow \frac{bd}{4\pi\theta_0}$

Note:
 $a = K\bar{\mu}$ (Gershun's Eq)
 and
 $c = a + b$

Consistent with Contrast Reduction Theory but includes terms for disk contrast and size



It works



Forel-Ule color scale

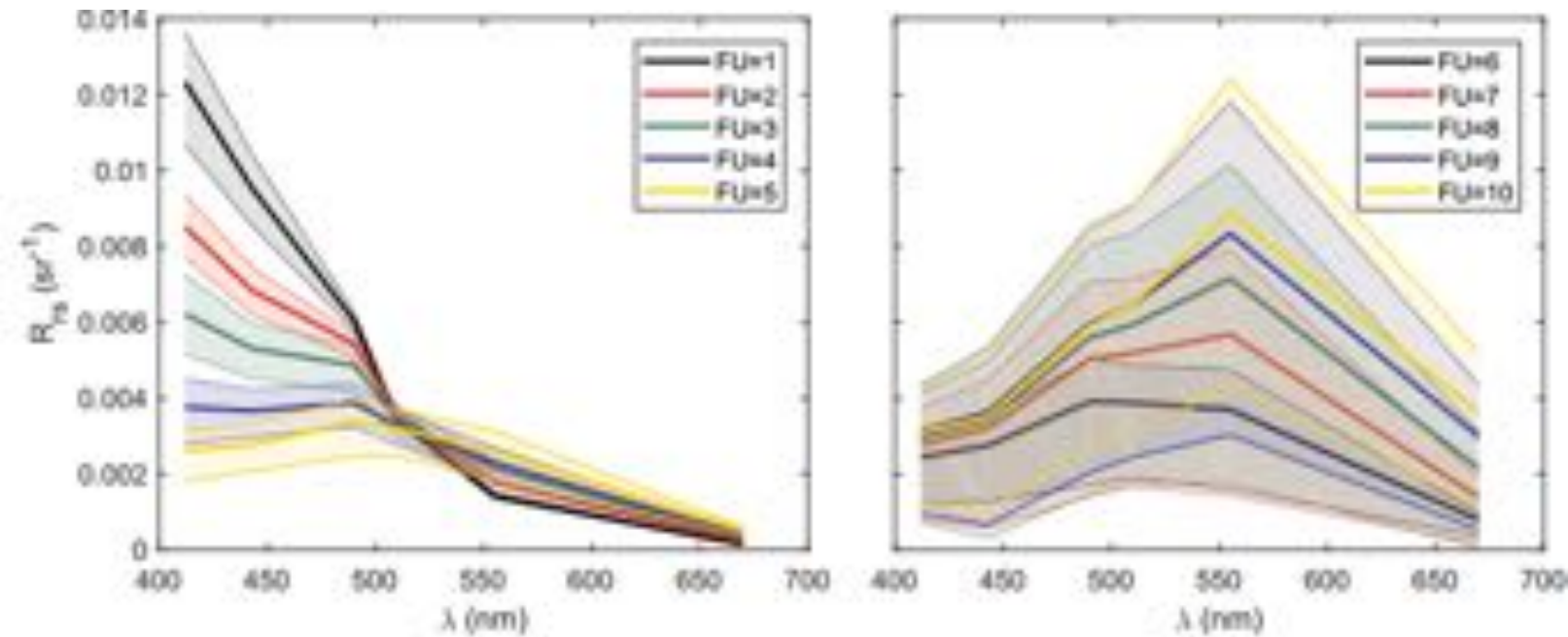
- Pitarch et al. (2019)
 - Can derive K_d
 - Other parameters with increasing errors...





Deploy over white Secchi disk

Pitarch et al. (2019) RSE



Bold traces outlining gray areas are 25%-75% of cases

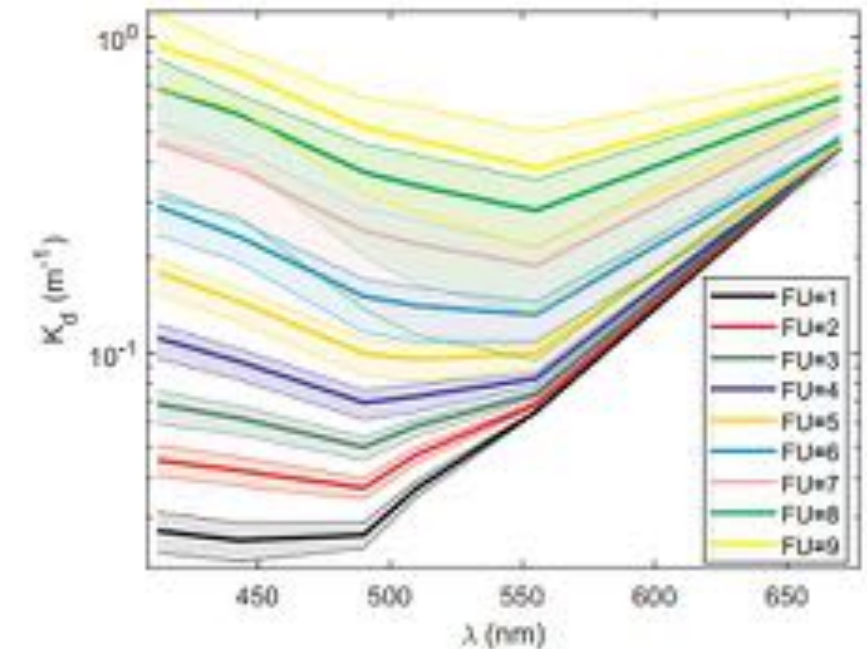


Fig. 9. Diffuse attenuation coefficient of downwelling irradiance of the first 9 FU classes, representing the median in bold line and the interval between the 25th and 75th percentiles in shaded band. For a complete description, the reader is referred to Table A2.

As an example, can derive light profiles for PAR with reasonable accuracy

Recap - derived optical parameters

can potentially solve for:

- Attenuation c
- Diffuse attenuation K_d
- Absorption a
- biogeochemical properties via proxies (or measure directly...)

Note:

$$a = K\bar{\mu} \text{ (Gershun's Eq)}$$

$$c = a + b$$

$$K_d \sim a + b_b$$

[Published: October 2003](#)

Horizontal sighting range and Secchi depth as estimators of underwater PAR attenuation in a coastal lagoon

[Martín A. Montes-Hugo](#), [Saúl Alvarez-Borrego](#)  & [Alma D. Giles-Guzmán](#)

[Estuaries](#) **26**, 1302–1309 (2003) | [Cite this article](#)

159 Accesses | **10** Citations | [Metrics](#)

Abstract

Attenuation of photosynthetically available radiation (PAR) measured using a light meter, was related to Secchi disk, horizontal black disk and horizontal sighting ranges observed in a coastal lagoon of the Southern California Current System. Vertical attenuation coefficient (K_{PAR}) was calculated from radiometric PAR profiles. Vertical (Z_D) and horizontal (HS) sighting ranges were measured with white (Secchi depth or Z_{SD} , HS_W) and black (Z_{BD} , HS_B) targets. Empirical power models for the K_{PAR} - Z_{SD} ($K_{PAR}=1.47 Z_{SD}^{-1.13}$), K_{PAR} - Z_{BD} ($K_{PAR}=0.98 Z_{BD}^{-1.26}$), K_{PAR} - HS_W ($K_{PAR}=1.22 HS_W^{-1.14}$) and K_{PAR} - HS_B ($K_{PAR}=0.73 HS_B^{-1.07}$) relationships were developed. The parameters of these models may not apply to other water

Inexpensive digital sensors

An ongoing revolution in inexpensive electronic and optical components, and 3D printing provides new opportunities to develop inexpensive, robust sensors.

For example:

AOPs, IOPs, turbidity, fluorescence, micro-imaging

Moorings/buoys, underway systems, citizen science

Much of the concept and content inspired by or borrowed from Emmanuel Boss

KduPRO low-cost DIY moored instrument for Kd

ORIGINAL RESEARCH article

 **frontiers** | Frontiers in [Marine Science](#)

Front. Mar. Sci., 16 December 2022

Sec. Ocean Observation

Volume 9 - 2022 | <https://doi.org/10.3389/fmars.2022.1004159>

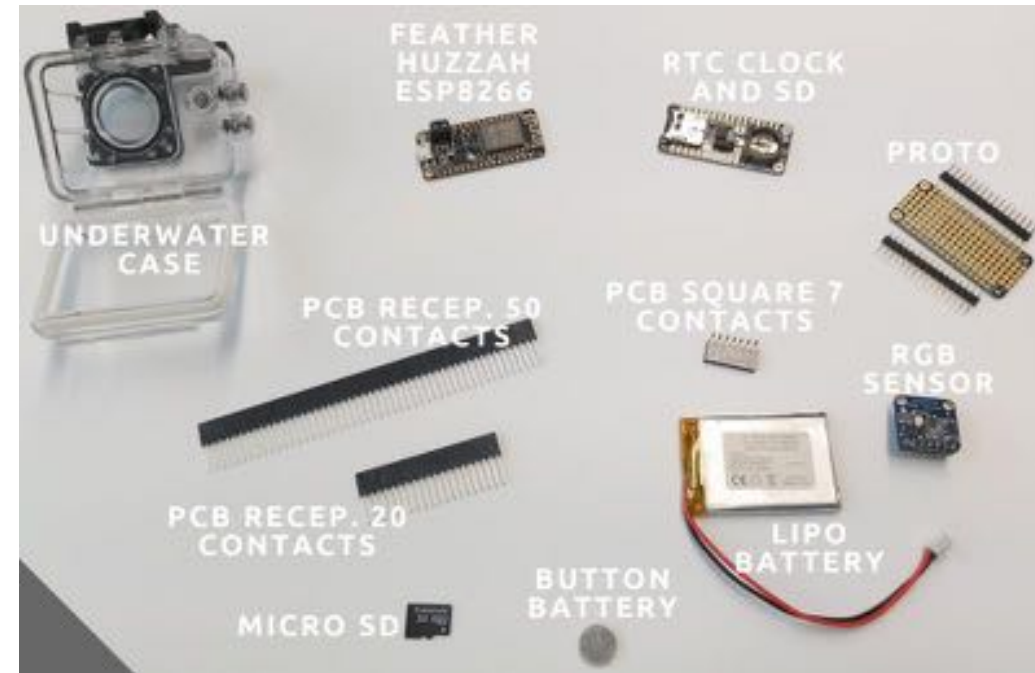
Operational monitoring of water quality with a Do-It-Yourself modular instrument

 Carlos Rodero^{1*}  Raul Bardaji²  Estrella Olmedo³  Jaume Piera¹

¹ Environmental and Sustainability Participatory Information Systems (EMBIMOS) Research Group, Department of Physical and Technological Oceanography, Institute of Marine Sciences, Spanish National Research Council (CSIC), Barcelona, Spain

² Marine Technology Unit, Spanish National Research Council (CSIC), Barcelona, Spain

³ Department of Physical and Technological Oceanography, Barcelona Expert Center, Institute of Marine Sciences, Spanish National Research Council (CSIC), Barcelona, Spain



~100 EUR parts per irradiance instrument

<https://git.csic.es/kduino/kdupro>

<https://www.icm.csic.es/en/staff/carlos-rodero-garcia-1860>



1 TCS34725 RGB Sensor with IR filter

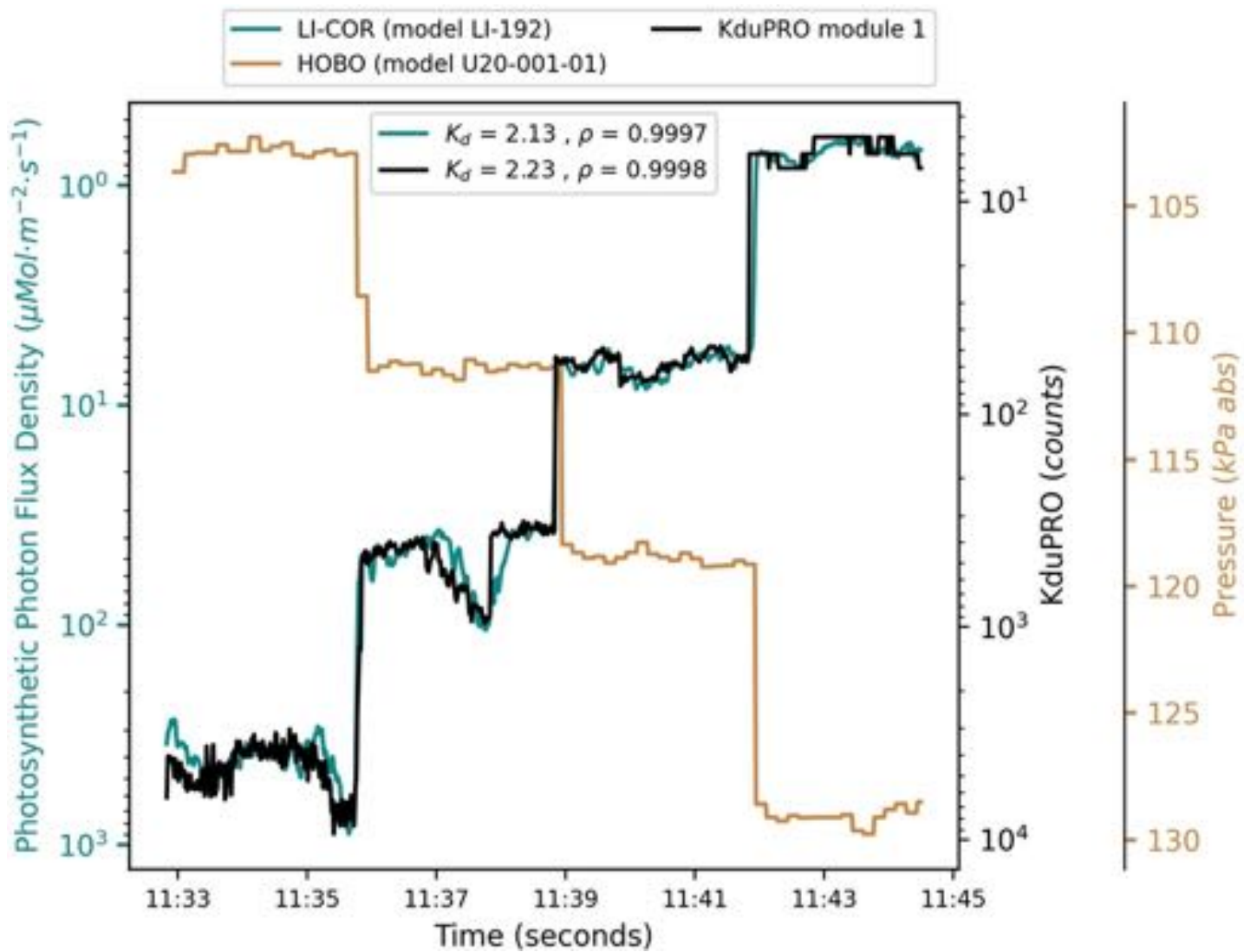
2 Foam black
30 mm x 30 mm,
with square hole of
20 mm x 20 mm

3 Foam black
30 mm x 30 mm,
with circular hole of
16 mm diameter

4 PTFE (polytetrafluoroethylene) tape
20 mm x 60 mm

5 Transparent glass methacrylate plate
28 mm x 20 mm





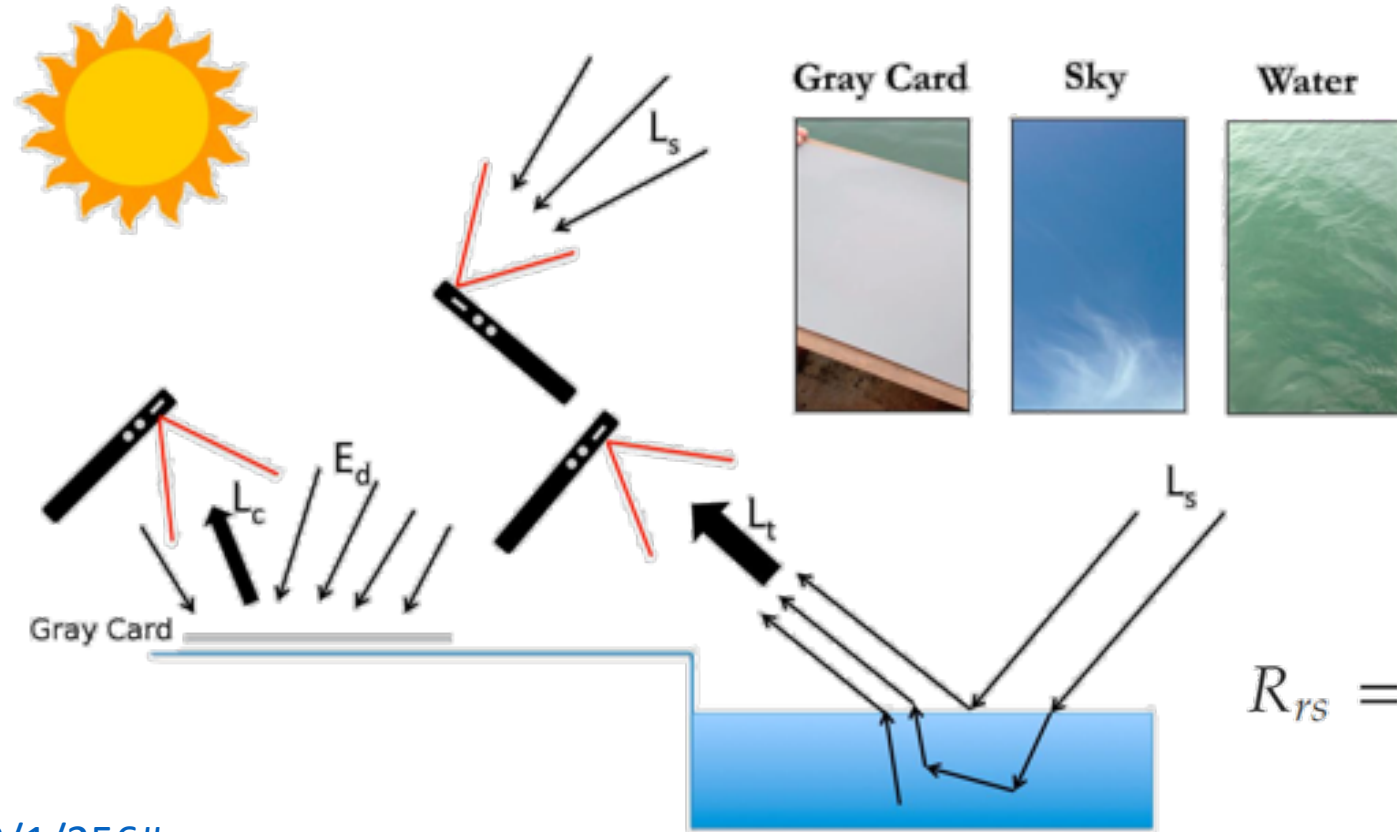
Comparison of instrument against LI-COR

Can use as profiling instrument or deploy in a customizable array

Article

The HydroColor App: Above Water Measurements of Remote Sensing Reflectance and Turbidity Using a Smartphone Camera

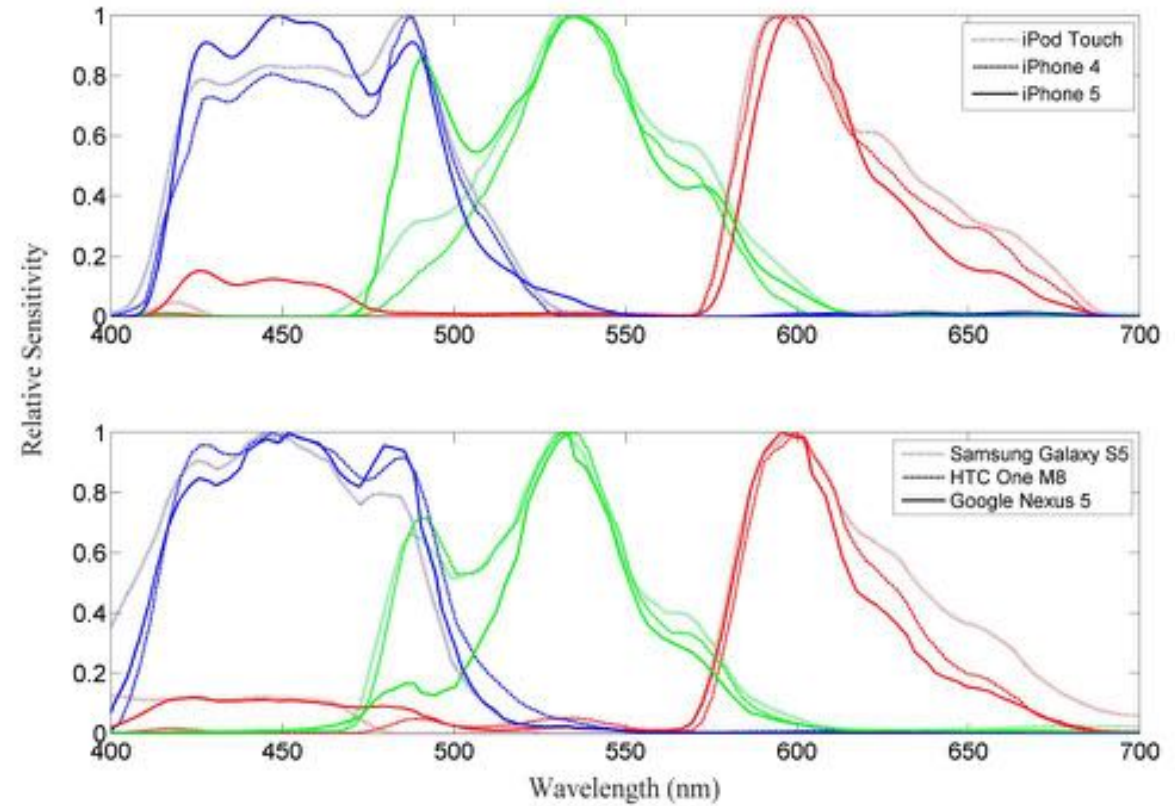
Thomas Leeuw ^{1,*} and Emmanuel Boss ²



$$R_{rs} = \frac{L_t - \rho L_s}{\frac{\pi}{R_{ref}} L_c}$$



Characterization of phone cameras

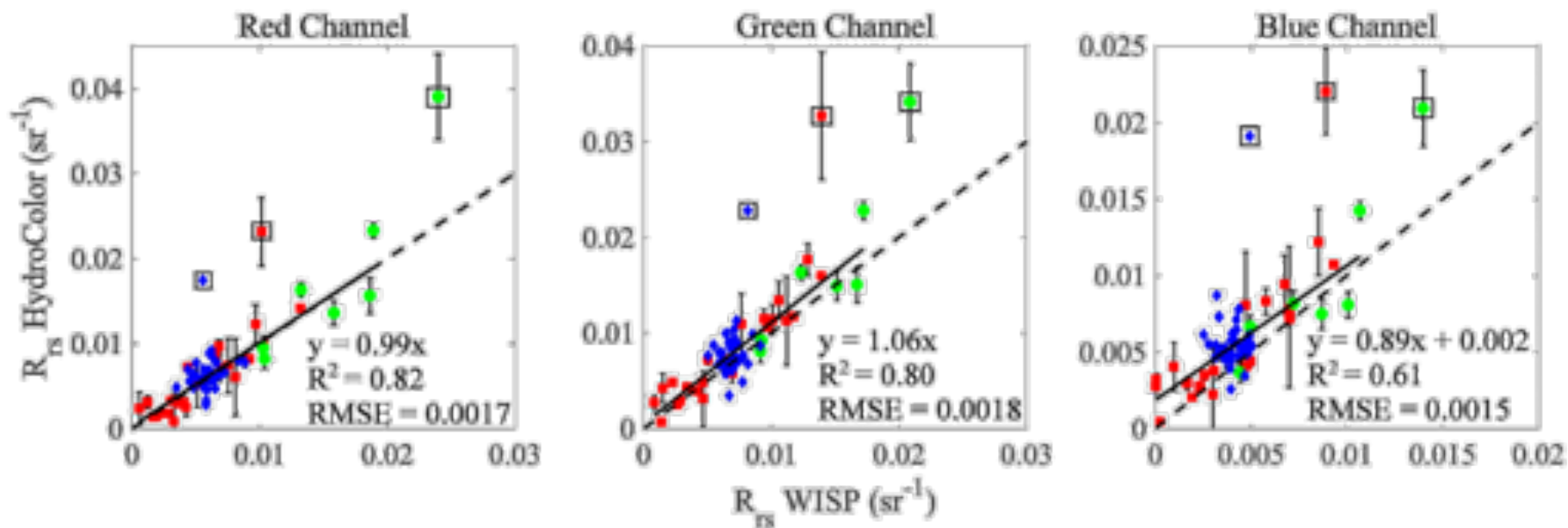


HydroColor

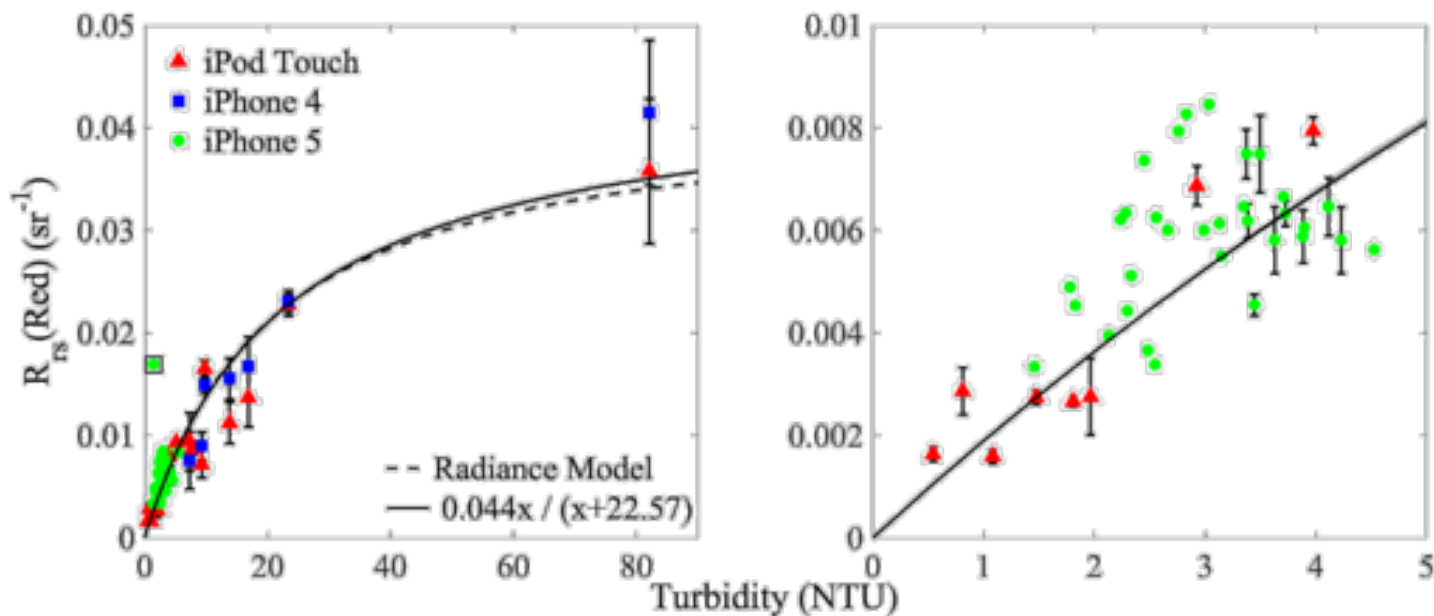


<https://play.google.com/store/apps/details?id=com.h2optics.hydrocolor>
<https://apps.apple.com/us/app/hydrocolor-water-quality-app/id816427169>

Comparison of HydroColor Rrs with WISP Rrs



Relationship between turbidity and HydroColor Rrs(red)





Article

Is Ocean Reflectance Acquired by Citizen Scientists Robust for Science Applications?

Yuyan Yang ^{1,*}, Laura L.E. Cowen ¹  and Maycira Costa ²

Mounted Hyper-SAS on BC ferry, compared against HydroColor data from trained and untrained users

“The main findings show that the HydroColor citizen data are accurate compared with hyperspectral instrument data for most bands and band ratios; however, citizen level of training and environmental conditions play a role in the data quality.”

pySAS

AUTONOMOUS SOLAR TRACKING SYSTEM FOR SURFACE WATER RADIOMETRIC MEASUREMENTS

By Nils Haëntjens, Kyle Forsythe, Bradley Denholm, James Loftin, and Emmanuel Boss

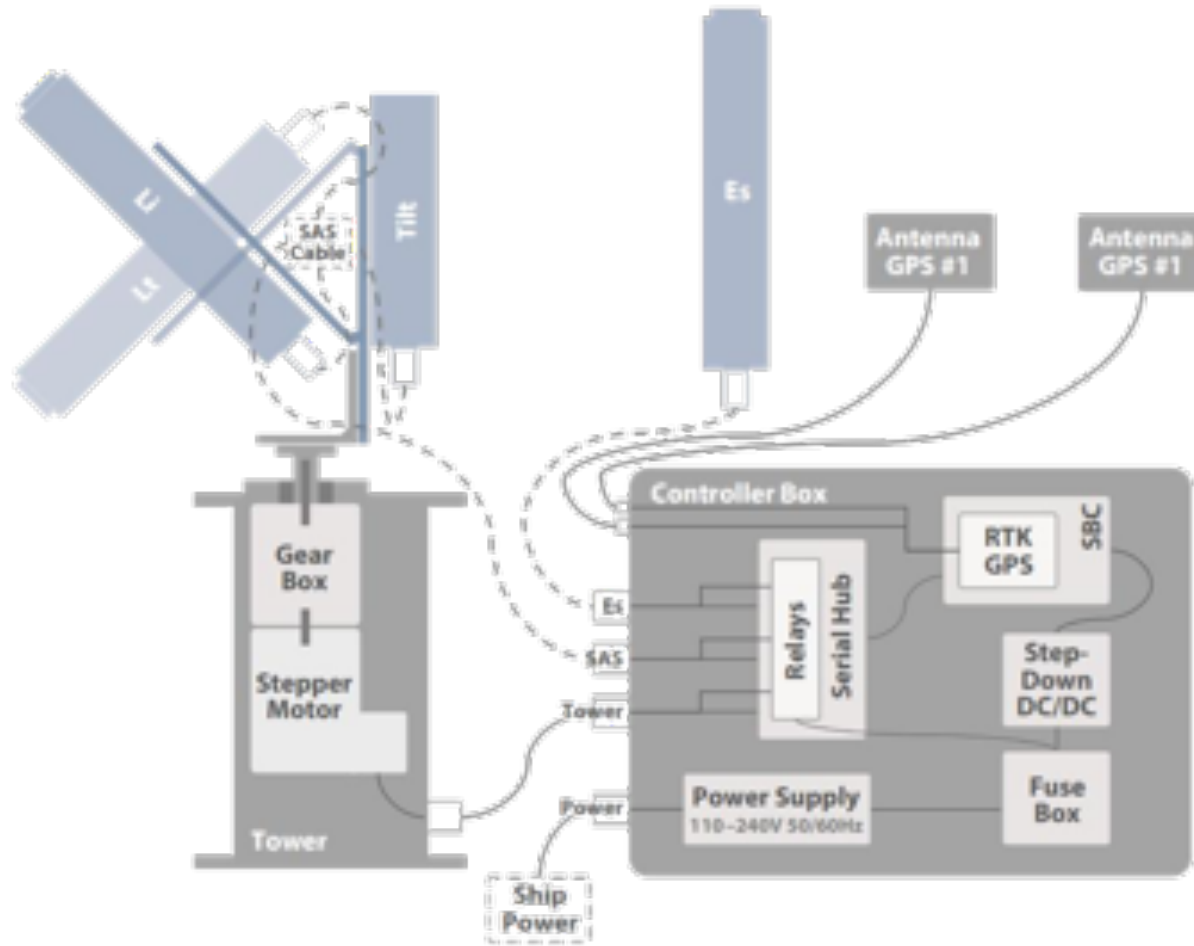


FIGURE 1. Schematic of pySAS hardware, not to scale. The Sea-Bird Scientific HyperSAS radiometers, tilt sensor, support (colored in blue), and cables (dashed) are not included in the pySAS materials list.

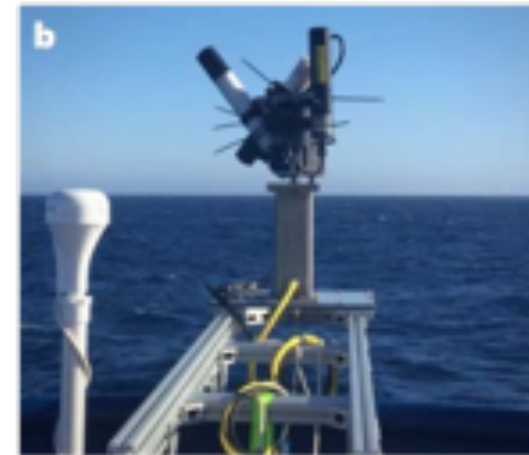
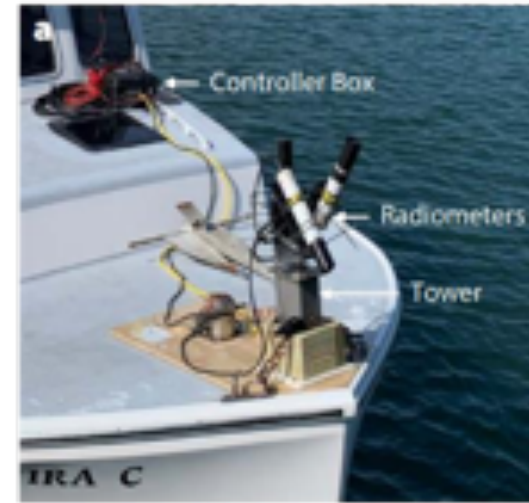


FIGURE 2. pySAS was mounted on the bows of (a) R/V Ira C and (b) R/V Roger Revelle.



<https://doi.org/10.5670/oceanog.2022.210>

<https://github.com/OceanOptics/pySAS>

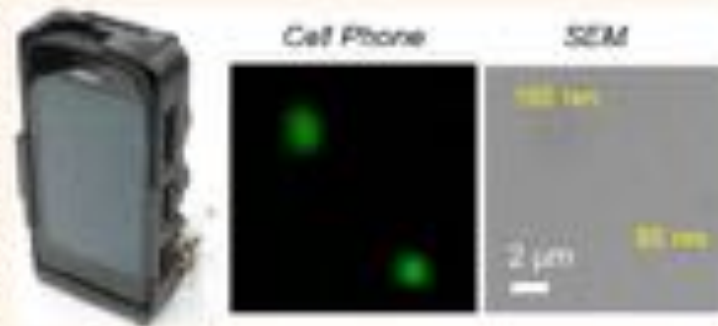
Fluorescent Imaging of Single Nanoparticles and Viruses on a Smart Phone

<https://research.seas.ucla.edu/ozcan/>

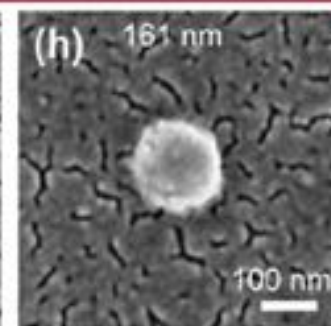
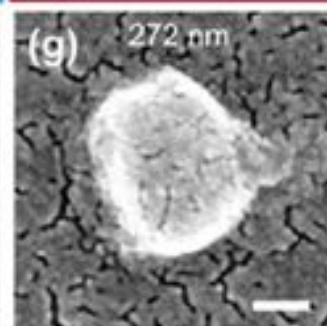
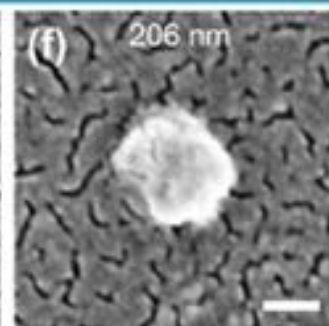
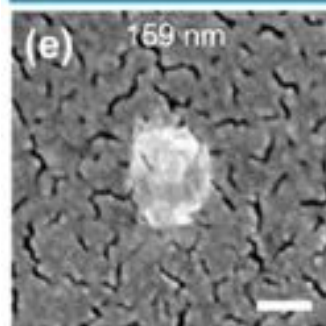
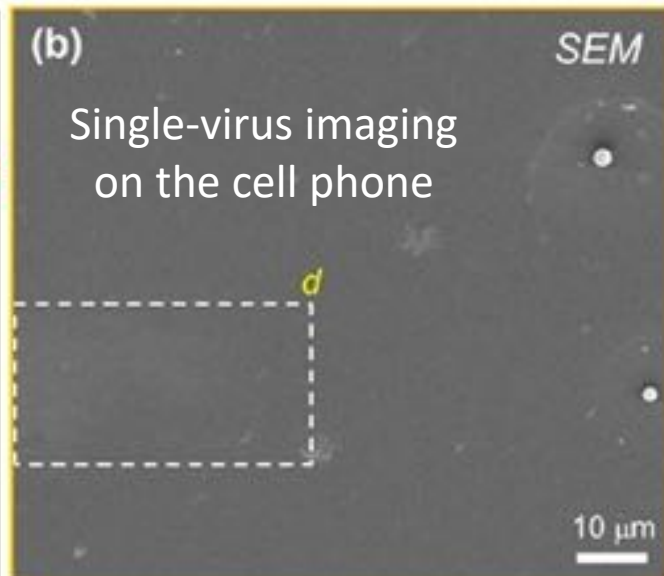
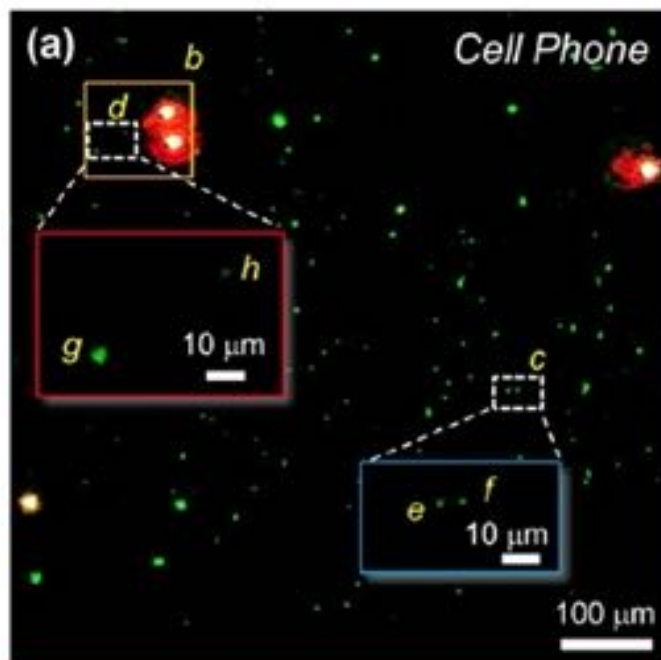
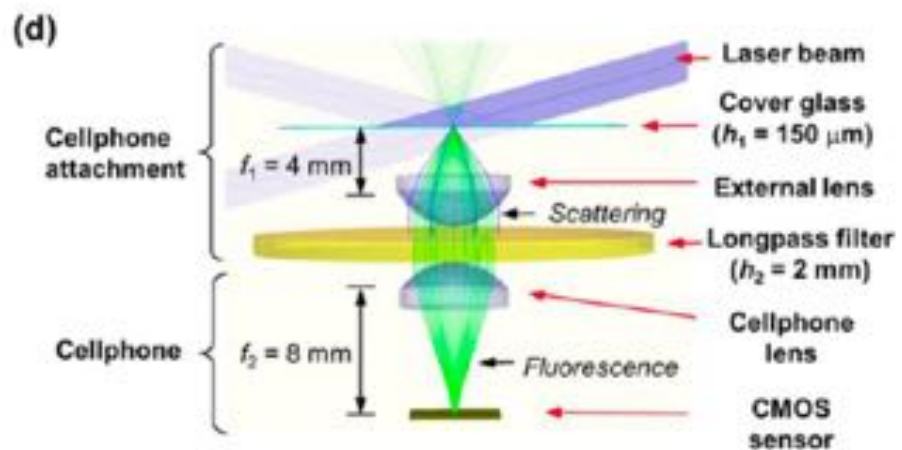
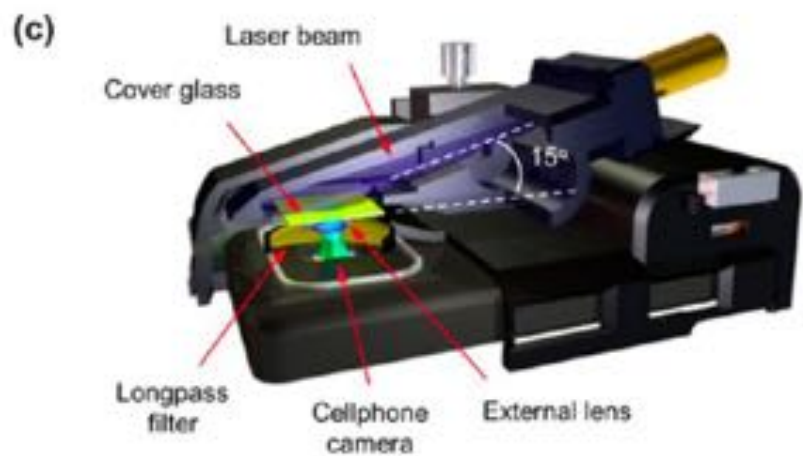
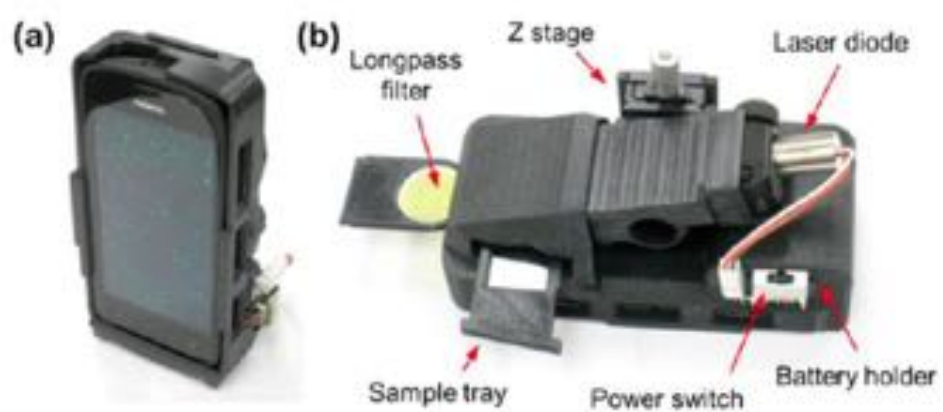
Qingshan Wei,^{1,4,5} Hangfei Qi,¹ Wei Luo,¹ Derek Tseng,¹ So Jung Ki,² Zhe Wan,¹ Zoltán Göröcs,^{1,4} Laurent A. Bentolila,^{3,1} Ting-Ting Wu,¹ Ren Sun,^{3,1} and Aydogan Ozcan^{1,4,5,*}

¹Electrical Engineering Department, ²Bioengineering Department, ³California NanoSystems Institute (CNSI), ⁴Department of Molecular and Medical Pharmacology, and ⁵Department of Chemistry and Biochemistry, University of California, Los Angeles (UCLA), California 90095, United States

ABSTRACT Optical imaging of nanoscale objects, whether it is based on scattering or fluorescence, is a challenging task due to reduced detection signal-to-noise ratio and contrast at subwavelength dimensions. Here, we report a field-portable fluorescence microscopy platform installed on a smart phone for imaging of individual nanoparticles as well as viruses using a lightweight and compact opto-mechanical attachment to the existing camera module of the cell phone. This hand-held fluorescent imaging device utilizes (i) a compact 450 nm laser diode that creates oblique excitation on the sample plane with an incidence angle of $\sim 75^\circ$, (ii) a long pass thin film interference filter to reject the scattered excitation light, (iii) an external lens creating $2\times$ optical magnification, and (iv) a translation stage for focus adjustment. We tested the imaging performance of this smart-phone-enabled microscopy platform by detecting isolated 100 nm fluorescent particles as well as individual human cytomegaloviruses that are fluorescently labeled. The size of each detected nano-object on the cell phone platform was validated using scanning electron microscopy images of the same samples. This field-portable fluorescence microscopy attachment to the cell phone, weighing only ~ 186 g, could be used for specific and sensitive imaging of subwavelength objects including various bacteria and viruses and, therefore, could provide a valuable platform for the practice of nanotechnology in field settings and for conducting viral load measurements and other biomedical tests even in remote and resource-limited environments.



ACS Nano (2003)
<https://doi.org/10.1021/nn4037706>

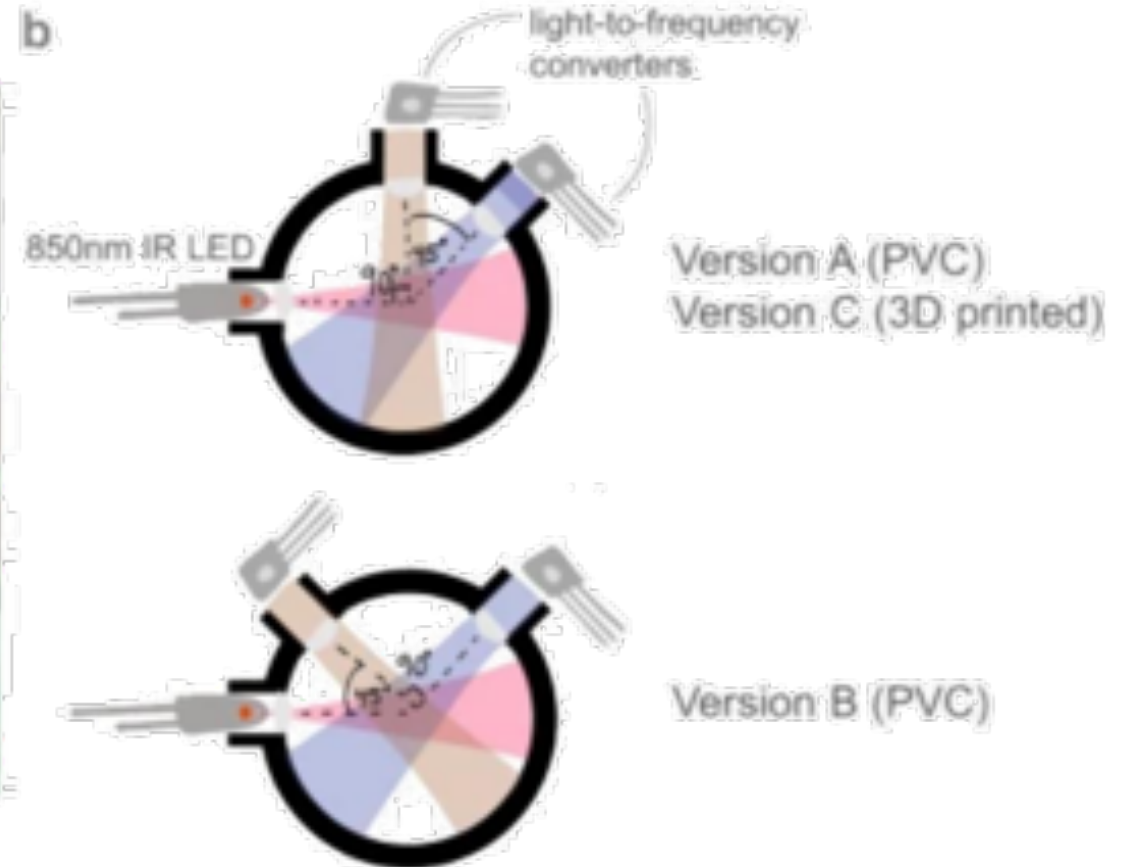


Open-source, low-cost, in-situ turbidity sensor for river network monitoring

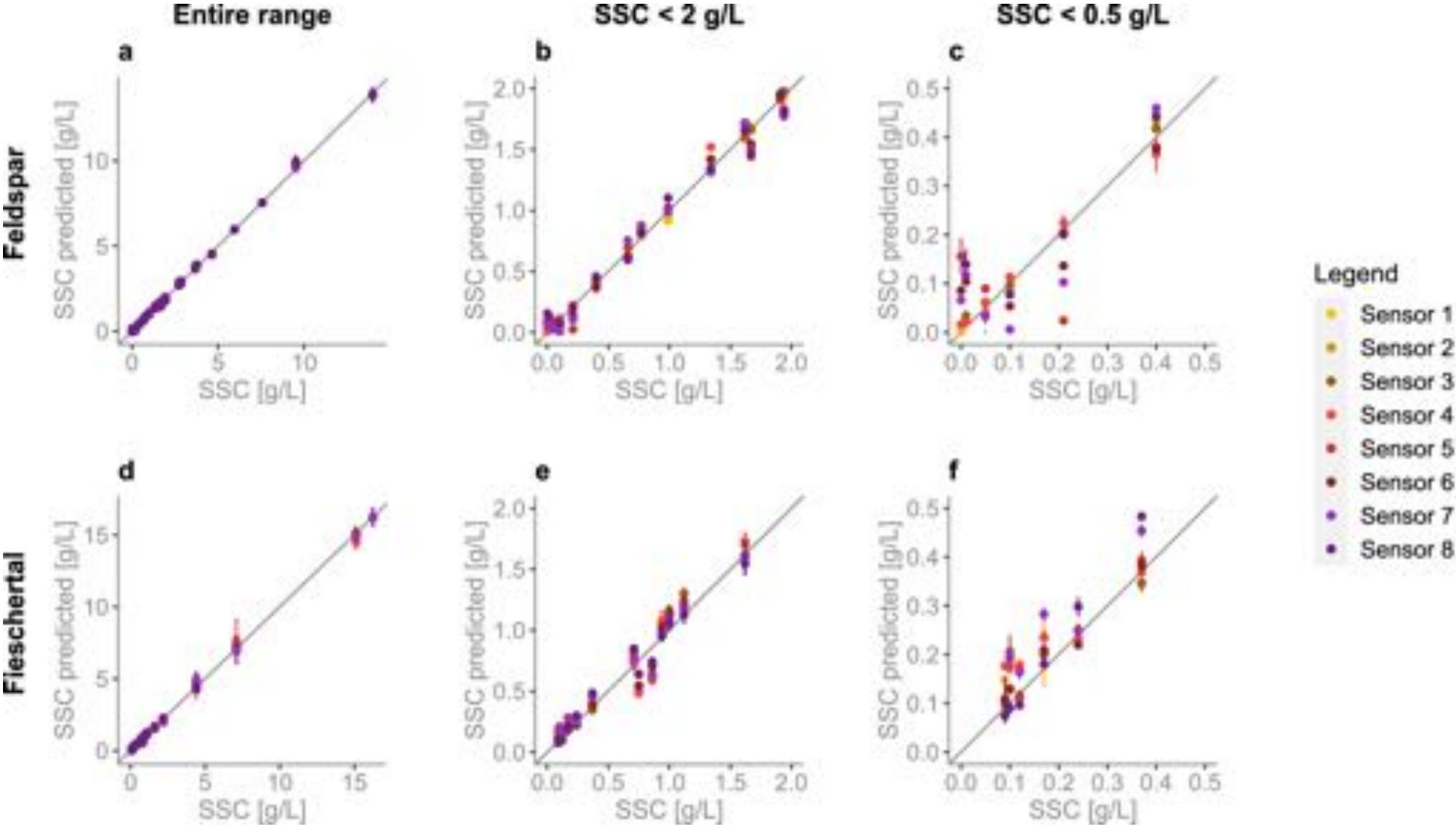
Scientific Reports (2022)

<https://doi.org/10.1038/s41598-022-14228-4>

[Jessica Droujko](#) ✉ & [Peter Molnar](#)



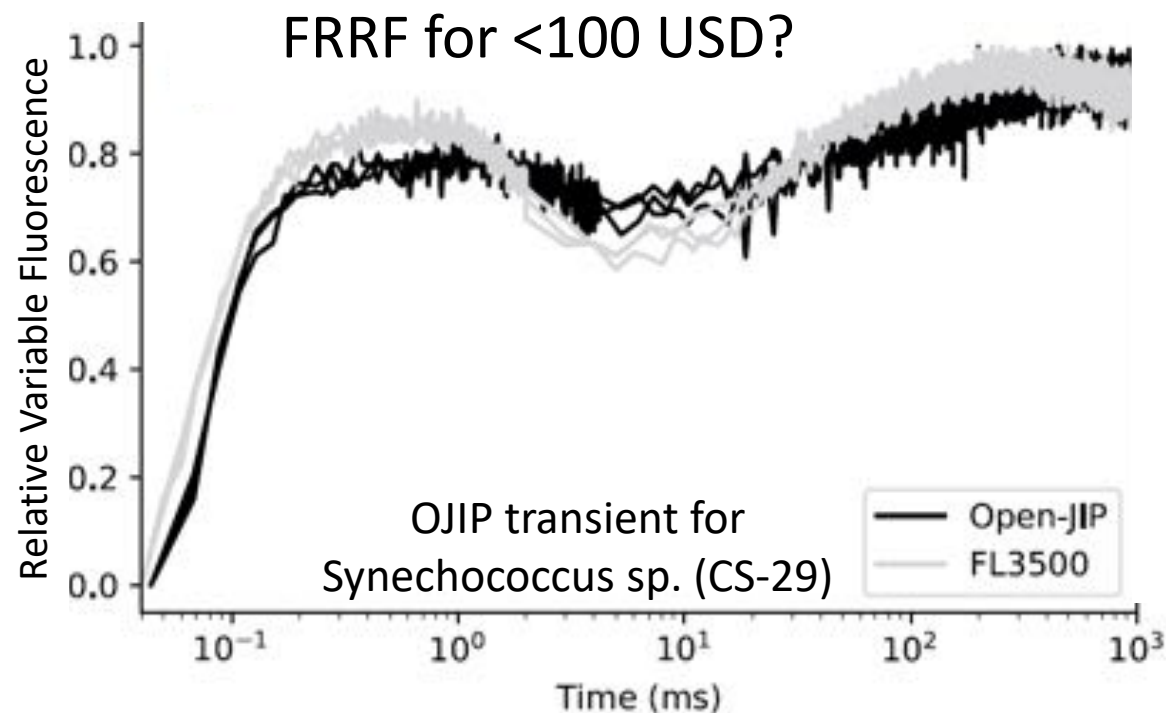
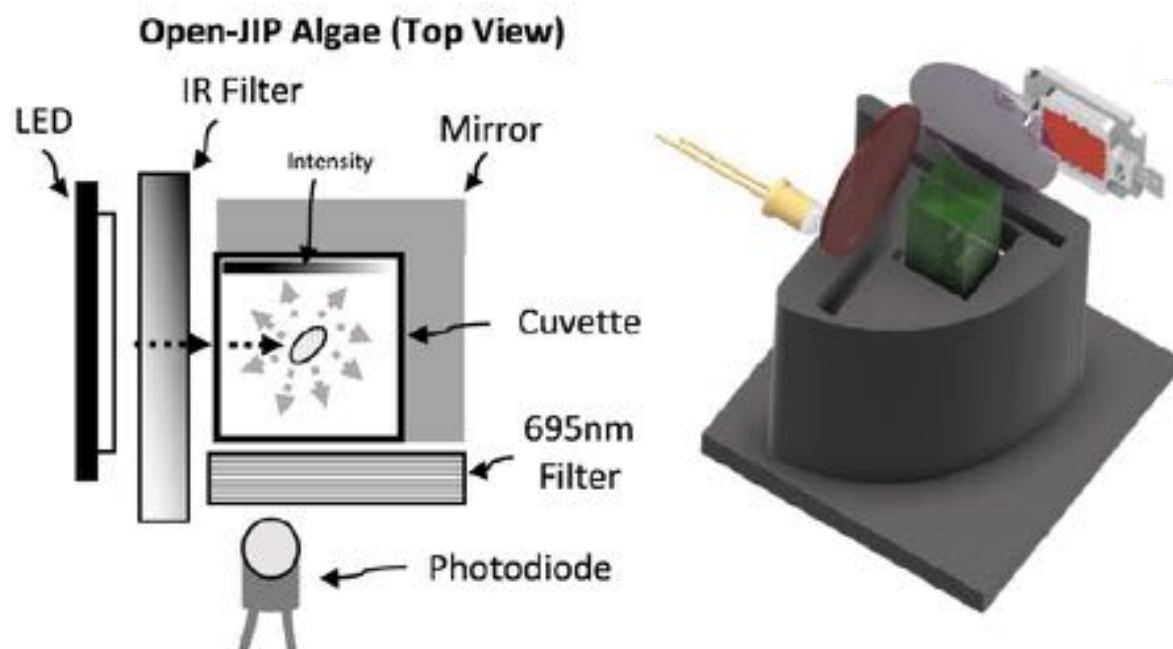
SSC measured vs. predicted for Feldspar (a–c) and Fieschertal (d–f) sediments (fourth order multiple linear regression SSC models)





A guide to Open-JIP, a low-cost open-source chlorophyll fluorometer

Harvey Bates¹ · Alonso Zavafer¹  · Milán Szabó^{1,2} · Peter J. Ralph¹



Sensors **2013**, *13*, 7872-7883; doi:10.3390/s130607872

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sensors

ISSN 1424-8220

www.mdpi.com/journal/sensors

Article

Simple in situ fluorometer in
an OtterBox, ~150 USD

***In situ* Measurements of Phytoplankton Fluorescence Using Low Cost Electronics**

Thomas Leeuw ^{*}, Emmanuel S. Boss and Dana L. Wright

Sensors **2014**, *14*, 7142-7155; doi:10.3390/s140407142

OPEN ACCESS

sensors

ISSN 1424-8220

www.mdpi.com/journal/sensors

Handheld turbidity
instrument in 3D printed
case, <50 USD

Article

An Affordable Open-Source Turbidimeter

Christopher D. Kelley ^{1*}, Alexander Krolick ², Logan Brunner ¹, Alison Burklund ¹,
Daniel Kahn ¹, William P. Ball ¹ and Monroe Weber-Shirk ³

ARTICLE

Open Access

A deep learning-enabled portable imaging flow cytometer for cost-effective, high-throughput, and label-free analysis of natural water samples

Zoltán Göröcs^{1,2,3}, Miu Tamamitsu^{1,2,3}, Vittorio Bianco¹, Patrick Wolf¹, Shounak Roy¹, Koyoshi Shindo¹, Kyrollos Yanny², Yichen Wu^{1,2,3}, Hatice Ceylan Koydemir^{1,2,3}, Yair Rivenson^{1,2,3} and Aydogan Ozcan^{1,2,3}

Patent pending, but cost of parts for instrument could be <2500 USD

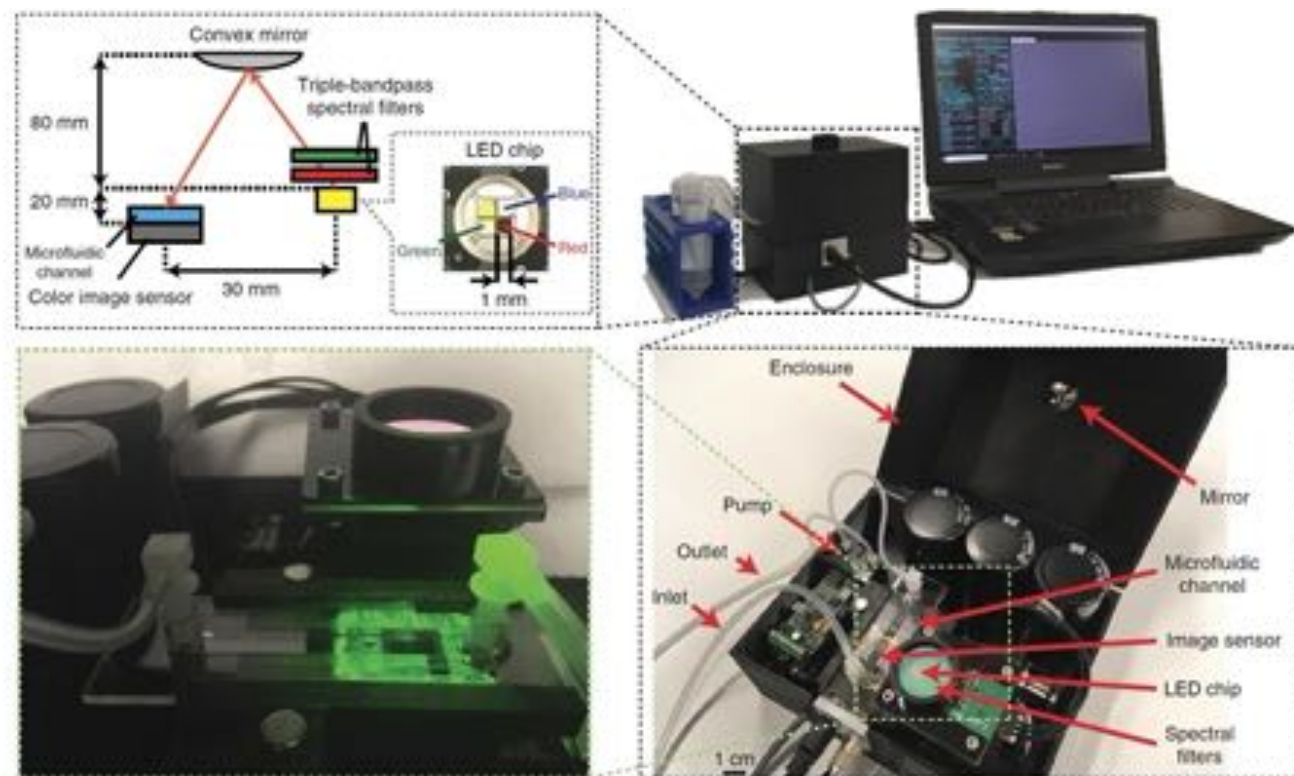


Fig. 1 Photos and schematic of the imaging flow cytometer device. The water sample is constantly pumped through the microfluidic channel at a rate of 100 mL/h during imaging. The illumination is emitted simultaneously from red, green, and blue LEDs in 120- μ s pulses and triggered by the camera. Two triple-bandpass filters are positioned above the LEDs, and the angle of incidence of the light on the filters is adjusted to create a <12 nm bandpass in each wavelength to achieve adequate temporal coherence. The light is reflected from a convex mirror before reaching the sample to increase its spatial coherence while allowing a compact and lightweight optical setup

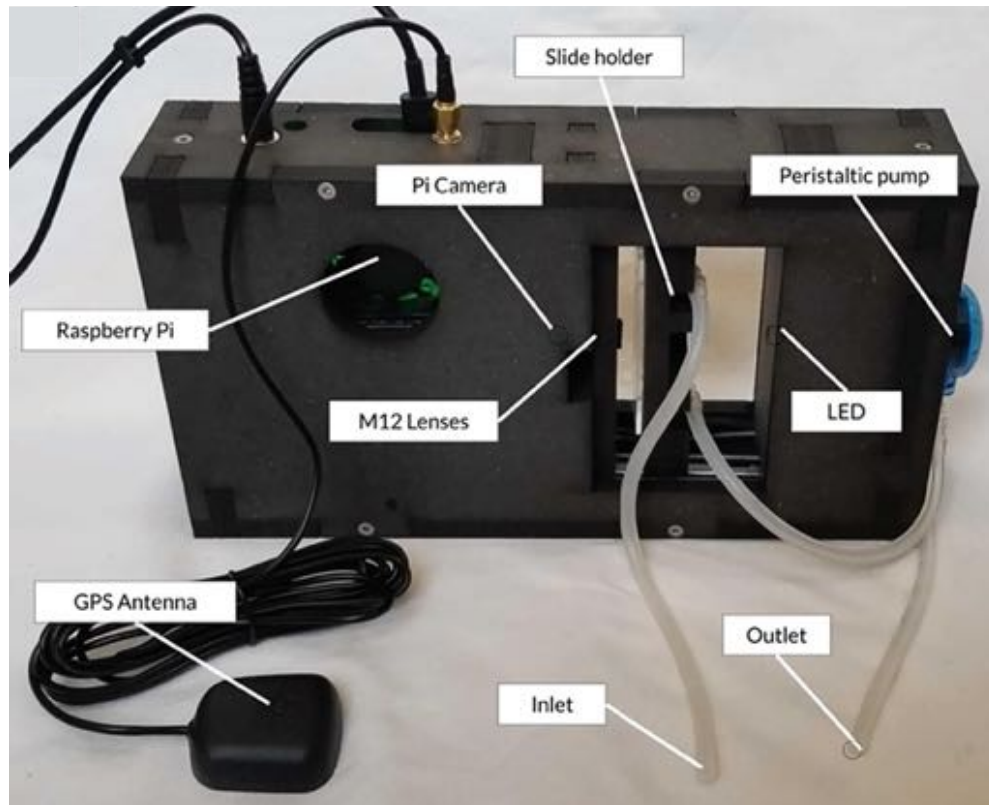


PlanktoScope: Affordable Modular Quantitative Imaging Platform for Citizen Oceanography

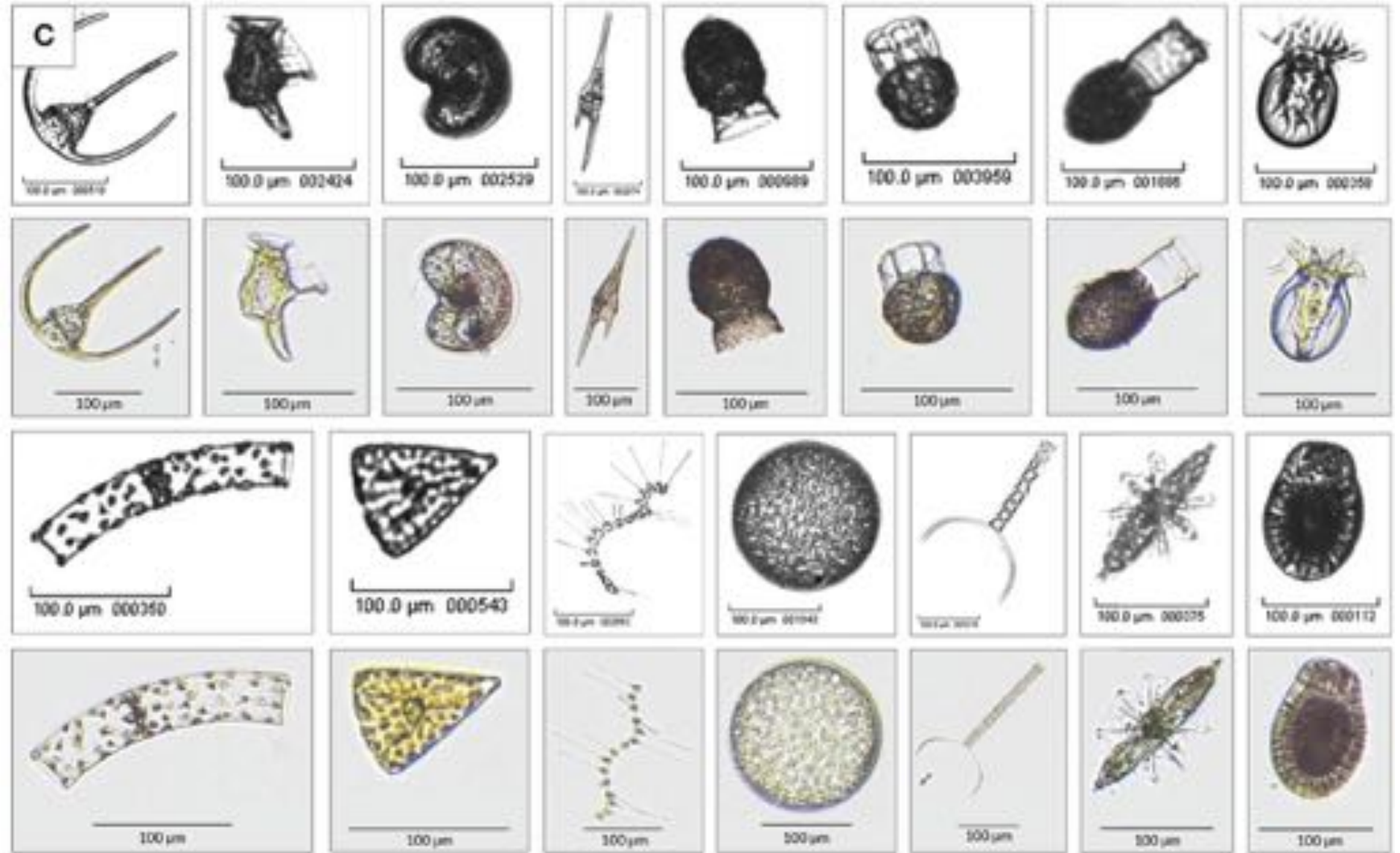
Thibaut Pollina^{1,2†}, Adam G. Larson^{1,2†}, Fabien Lombard^{2,3,4,5}, Hongquan Li¹, David Le Guen², Sébastien Colin^{2,6}, Colomban de Vargas^{2,3,7*} and Manu Prakash^{1,2*}

<https://github.com/PlanktoScope/PlanktoScope>

<https://www.planktoscope.org/>



Benchmarking
PlanktoScope against
commercial FlowCam



Color images: PlanktoScope
Mono images: FlowCam



Inlinino

A MODULAR SOFTWARE DATA LOGGER FOR OCEANOGRAPHY

Oceanography (2020)
DIY-Oceanography

<https://inlinino.readthedocs.io/en/latest/>

By Nils Haëntjens and Emmanuel Boss



Using IoT tools to broadcast data
to phones/tablets

Software based datalogger.

Time stamps and logs data from analog and
digital sensors

Graphical interface – real time data

Works on PCs, Macs and Linux

Used to log: AC-S, LISST, Eco-bb3, Seapoint
fluorometer, Hyper-bb, CTD... All simultaneously
on the same computer.



Contents lists available at ScienceDirect

Aquacultural Engineering

journal homepage: www.elsevier.com/locate/aque



Buoy system using chains
of compact, off-the-shelf
Hobo loggers

Design and operation of a low-cost and compact autonomous buoy system
for use in coastal aquaculture and water quality monitoring



Wiebke Schmidt^{a,b,c}, David Raymond^b, David Parish^b, Ian G.C. Ashton^{a,b}, Peter I. Miller^c,
Carlos J.A. Campos^d, Jamie D. Shutler^a

Hindawi Publishing Corporation
Journal of Sensors
Volume 2015, Article ID 920168, 23 pages
<http://dx.doi.org/10.1155/2015/920168>

Research Article



Oceanographic Multisensor Buoy Based on Low Cost Sensors for Posidonia Meadows Monitoring in Mediterranean Sea

Homegrown
sensors...

Sandra Sendra, Lorena Parra, Jaime Lloret, and José Miguel Jiménez

Final Thoughts

These are only a few examples... Expect to see many more disruptive developments in ocean optics and ocean sciences in places like GitHub in the future!

An ongoing revolution in inexpensive electronic and optical components and 3D printing provides new opportunities to develop inexpensive, robust sensors

Robust analog methods exist for potentially determining c and K ... a , b , b_b may also be potentially derived

Validation and closure between methods is highly desirable to quantify uncertainties

Analog methods are useful if expensive optical sensors are not available for research, but can also be very useful metrics as a gut check on highest quality measurements

Many applications relating to water quality and imaging can accommodate larger uncertainties associated with many of these methods