

Measurement of in-situ optical properties

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Some (personal) background

“There is nothing, absolutely nothing half so much worth doing as simply messing around in boats, or with boats. In 'em, or out of 'em, it doesn't matter.” Rat, Wind in the Willows.



Hawaii w/ JAMSTEC

Simply messing around in boats...

Lac LaBiche, w/
Dave Schindler



Off Miami, w/
U.S.N.



Villefranche-sur-mer
w/ fishermen



Easter Island
w/ LOV



Equatorial Pacific w/
JAMSTEC



Med w/David Antoine



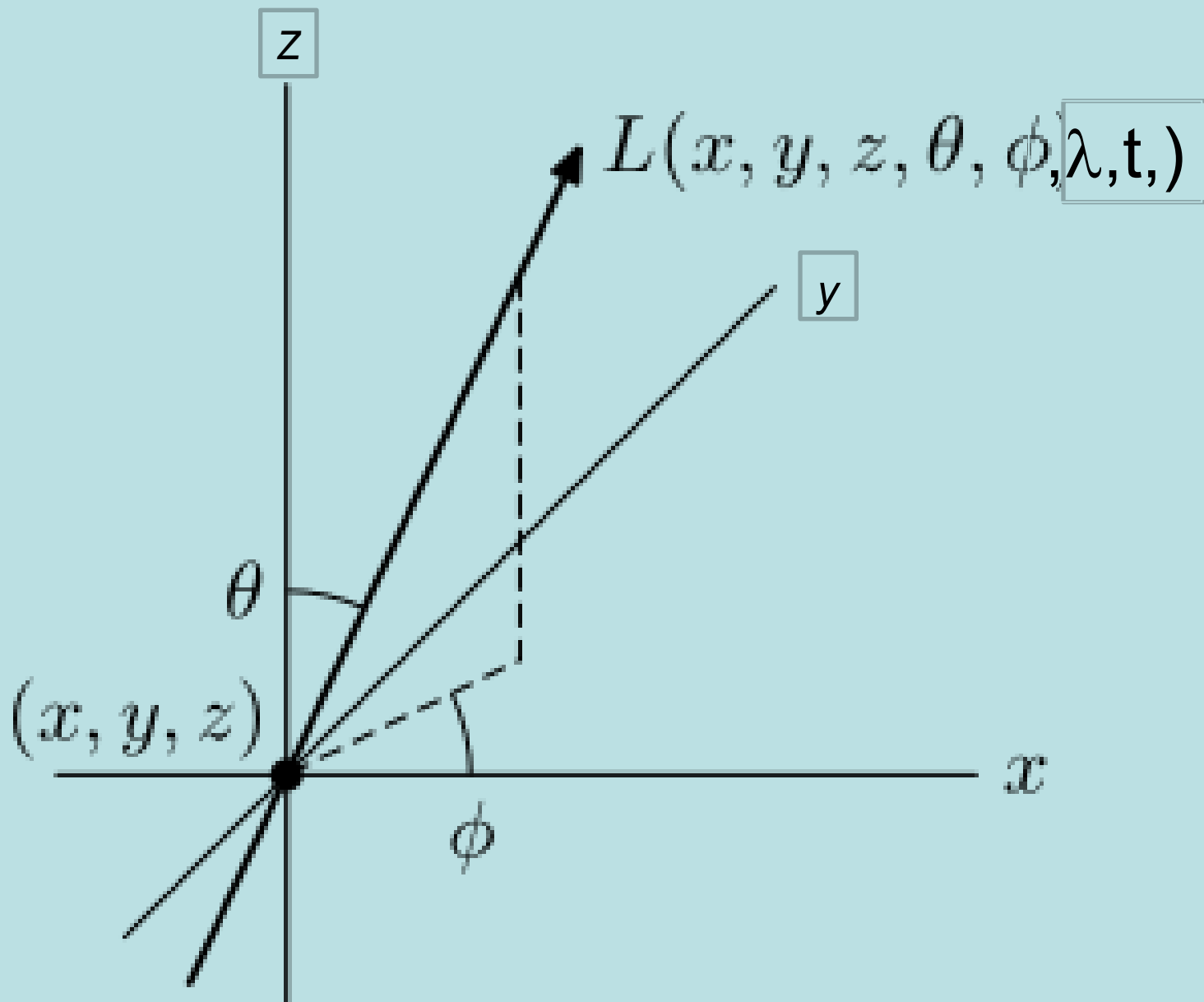
La Have River, w/ my dog.



If the coconuts don't grow,
don't go.

(Scientific) Background

- The fundamental radiometric quantity is the spectral radiance distribution ($L(z,x,y,t,\theta,\varphi,\lambda)$), the radiant flux per unit wavelength or frequency interval per unit solid angle per unit of projected area; the usual unit is watt per nanometer per steradian per square meter.
- *“Spectral radiance is the fundamental quantity of interest in hydrologic optics....all other radiometric quantities can be derived from (this)” Mobley, 1994*



Background

- In principle, all of the apparent and inherent optical properties as well can be derived from a measurement of the radiance field and its gradient in the upper ocean.

Background

Another good reason for focusing on radiance: Modelling the dynamic radiance distribution is what makes *Avatar* possible (Weta Digital)



Do Radiance Right

And if you need another good reason...



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Background

Solution – measure the radiance distribution in x , y , z , t , all angles, all wavelengths, and all polarization components.

A caveat: Life consists of trade-offs.

Background (2)

- The radiance field in the ocean is set first at the surface by that of sun & sky, and by the nature of the air-sea interface.
- In the ocean interior, the radiance field is further modified by the inherent optical properties (the absorption coefficient, the volume scattering function), various “inelastic scattering” processes (e.g. Raman, fluorescence), and internal sources (e.g. bioluminescence).

Gains due to photons scattering in.
(involves radiance distribution,
and VSF). Also, may be other
sources, e.g. Raman, Flu.

$L(z, \theta, \phi)$

θ', ϕ'

θ, ϕ

$\cos dr = dz$

dr

Losses due to absorption &
scattering ($c=a+b$).

$$\cos \theta \frac{dL(z, \theta, \phi)}{dz} = -cL(z, \theta, \phi) + \int_{\Xi} \beta(\theta', \phi' \rightarrow \theta, \phi) L(z, \theta', \phi') d\Omega' + \text{Other Sources}$$

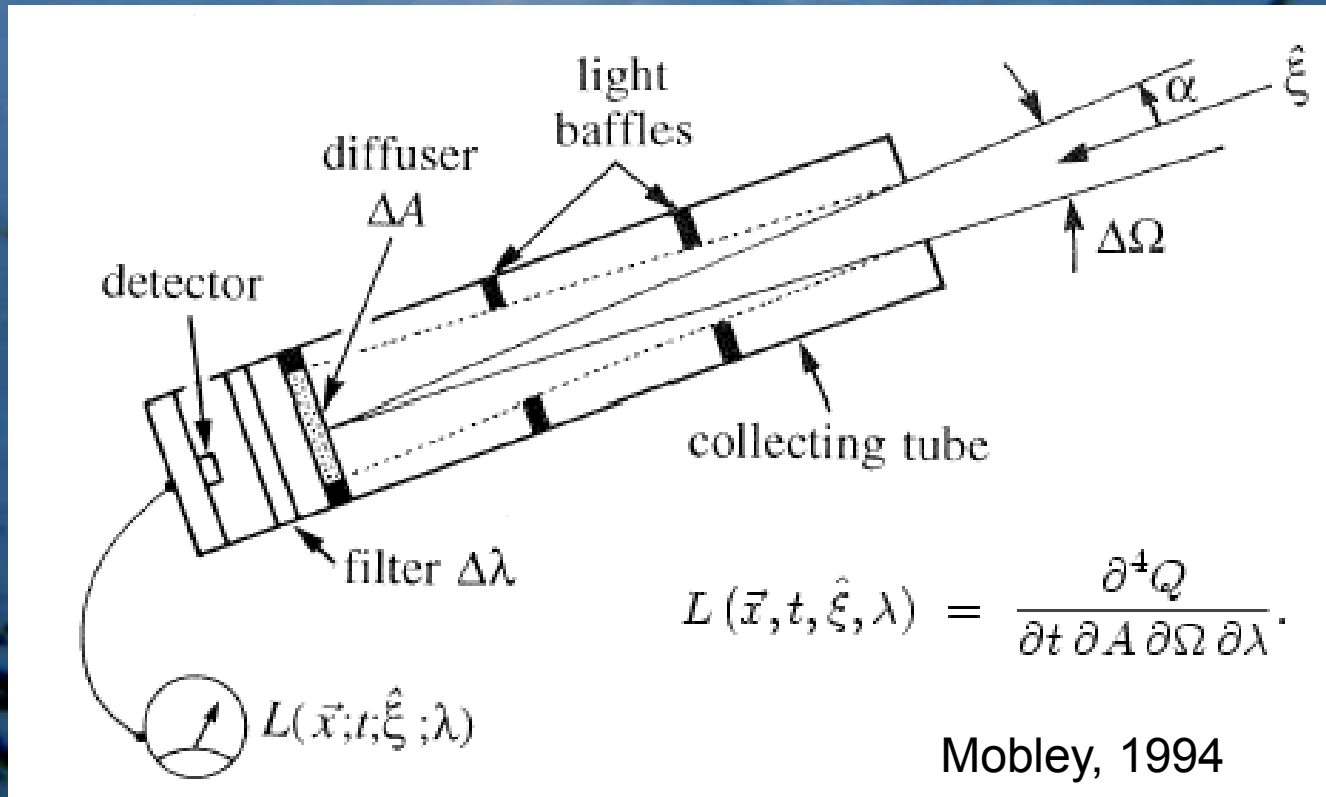
Some good reasons for measuring variability in the full radiance field,

- Many of the measurements currently made, such as planar and scalar irradiance, angle-dependent Q factor etc., could be made by various integration operations on the measured radiance field rather than with mechanical diffusers.
- The potential interferences of various deployment platforms (e.g. shading, reflectances by ships, buoys and towers) could be measured directly rather than inferred based on inaccurate assumptions about the underwater radiance distribution.
- A direct confirmation of the asymptotic radiance distribution can be made.
- Finally, high quality quantitative (and radiometrically calibrated) measurements of the radiance distribution, and their time and depth (path) derivatives, can in principle (but not yet in practice) be used to estimate all the inherent optical properties (both absorption and volume scattering coefficient) and as well the nature of the air-sea interface.

Measurement of the Radiance Distribution.

- Despite the fundamental importance of the radiance distribution, it is perhaps surprising that, while this received a great deal of interest in the 50's and early 60's, there have been few direct observations in more recent years.

Measurement of Radiance



The Gershun Tube

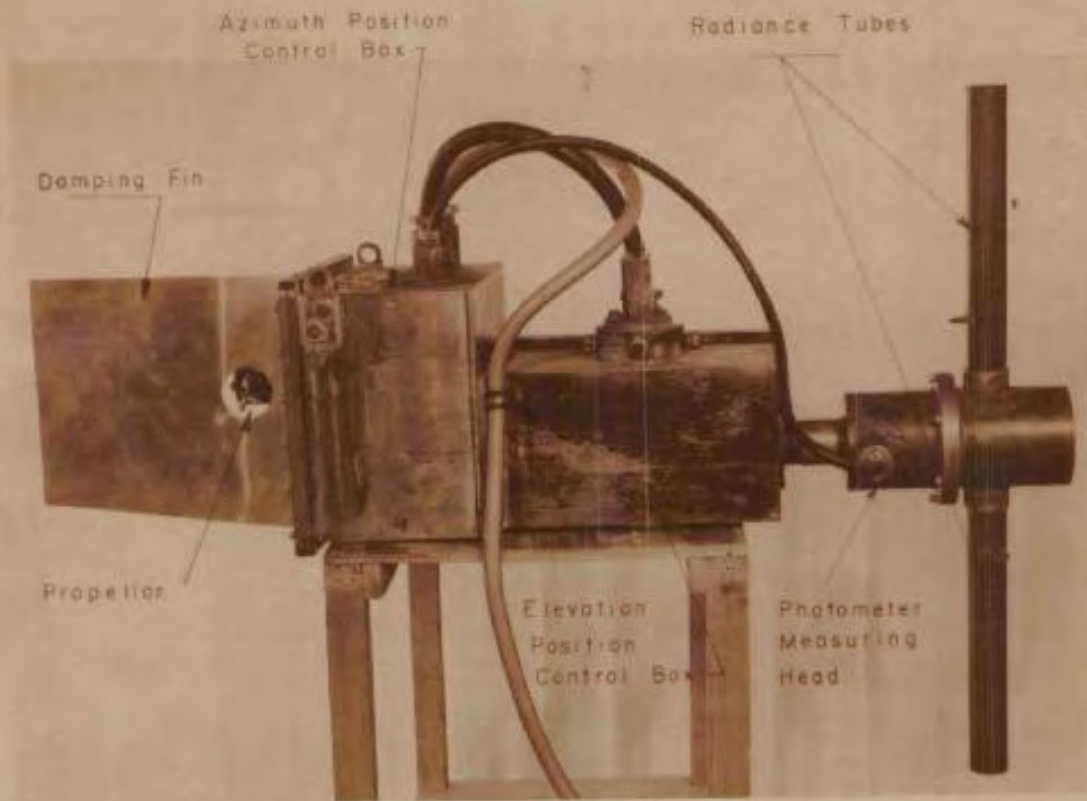


Figure 2

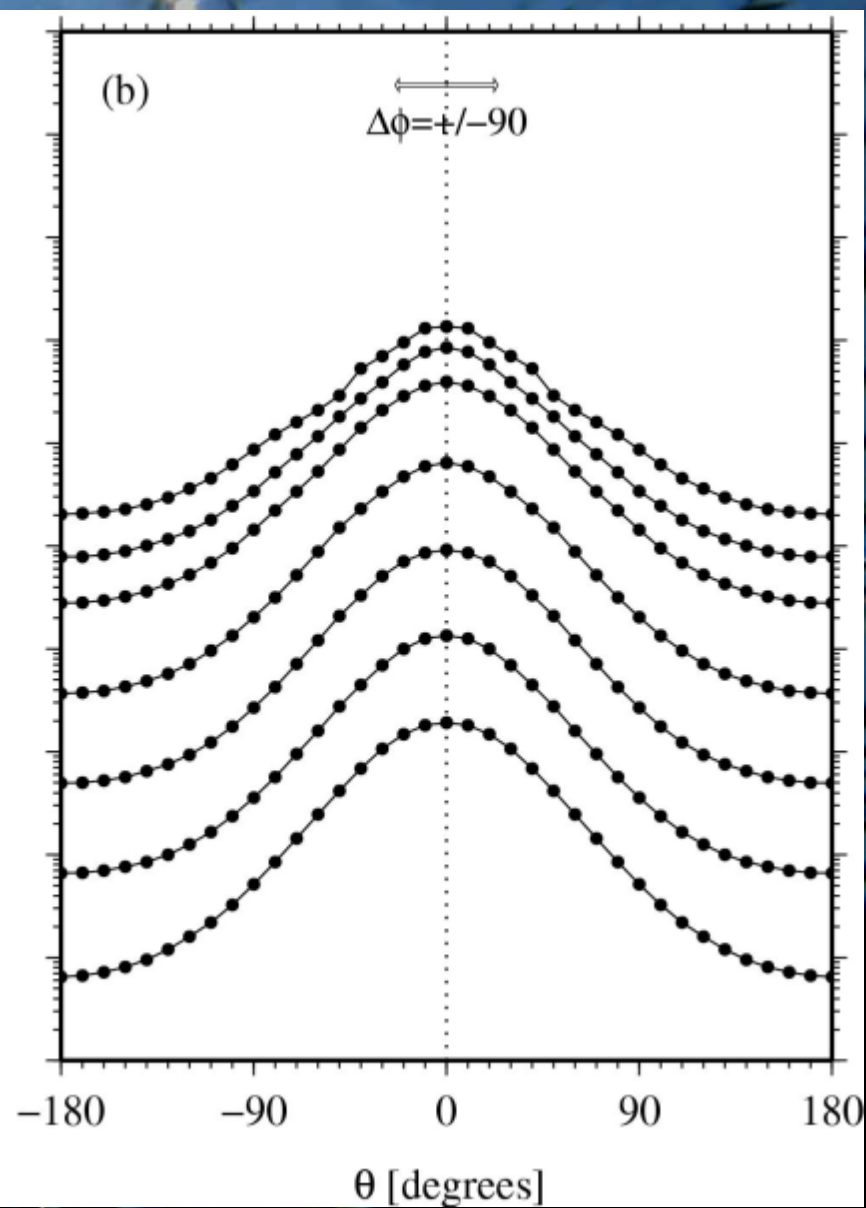
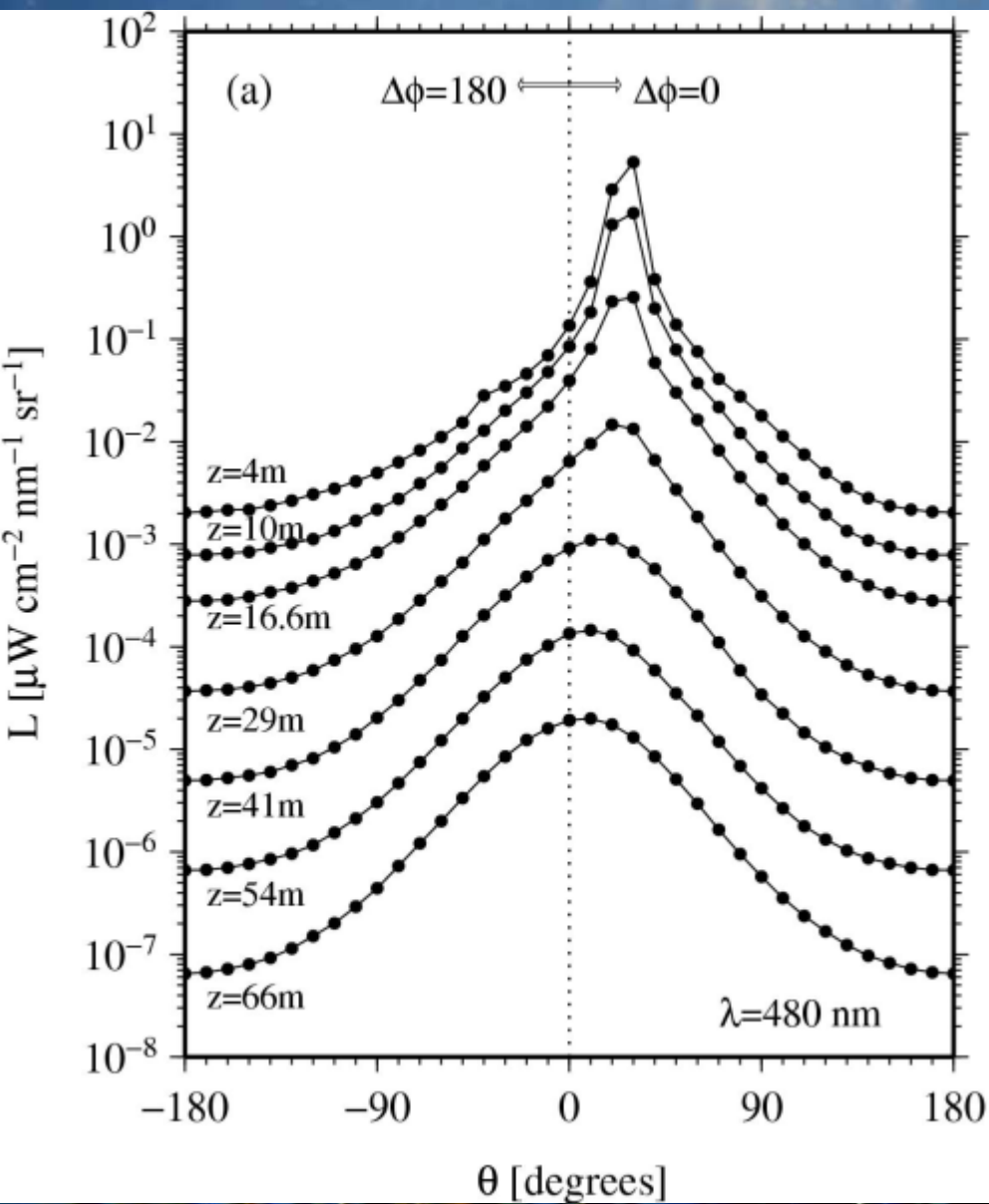
Underwater Photometer

Duntley, Tyler

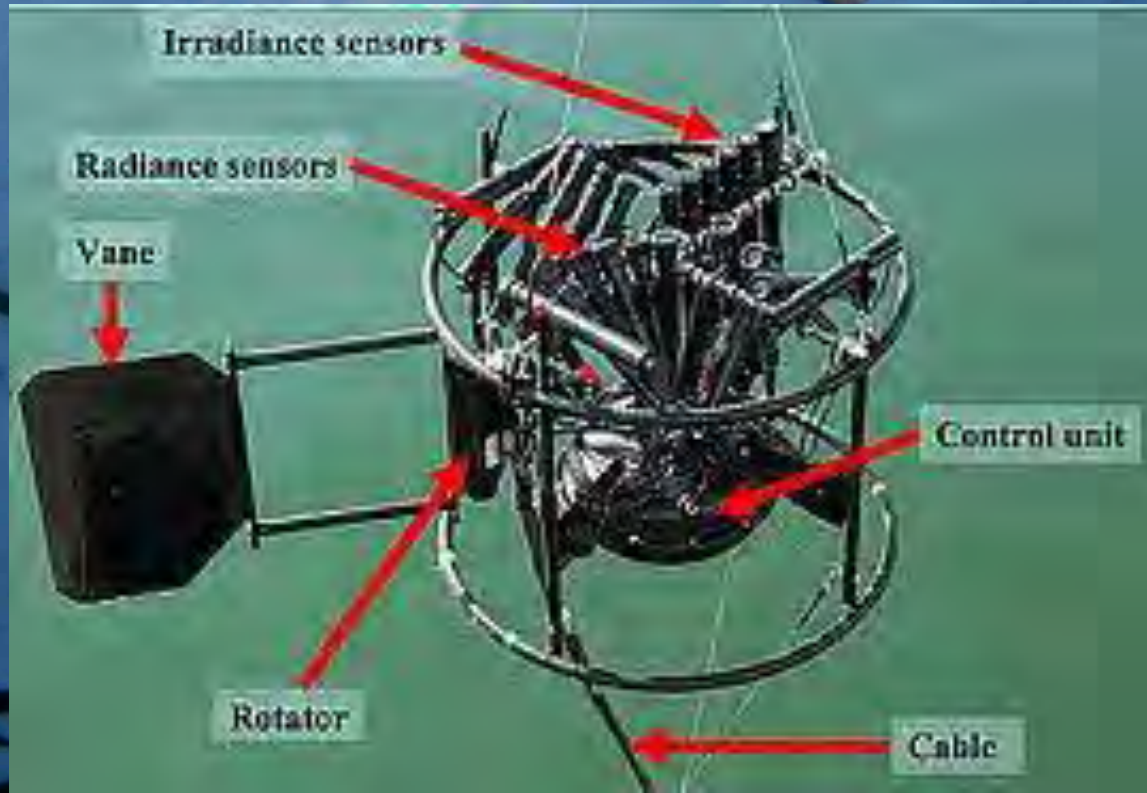
* Measuring Head and Positioning Equipment

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Data from Tyler



Porcupine



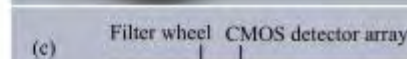
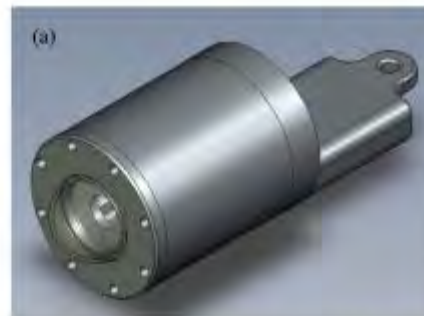
Mirosław Darecki

Radiance Camera: a hard problem!

First approach was by Ray Smith and John Tyler – a photographic camera with a fisheye lens.

Subsequent solid-state (CCD) versions developed by Voss.

Two recent manifestations using CMOS arrays are the RADCAM (Satlantic) and the camera built by LOV



RADCAM

- RAD-CAM takes advantage of recent advances in CMOS imaging technology to provide operational instrumentation for investigation of the underwater radiance field.
- Downwelling field in particular is very challenging, as it can result in a requirement for a scene dynamic range $\sim 10^6$ - 10^7 .



Off Hawaii



Joys of being a graduate student



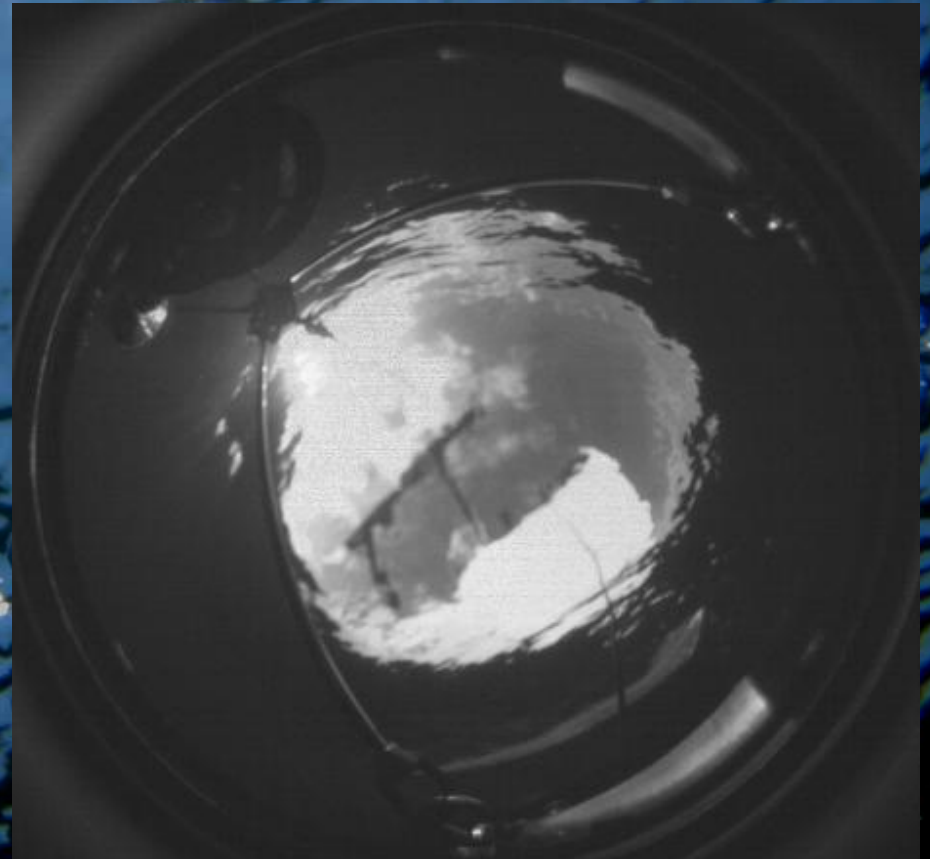
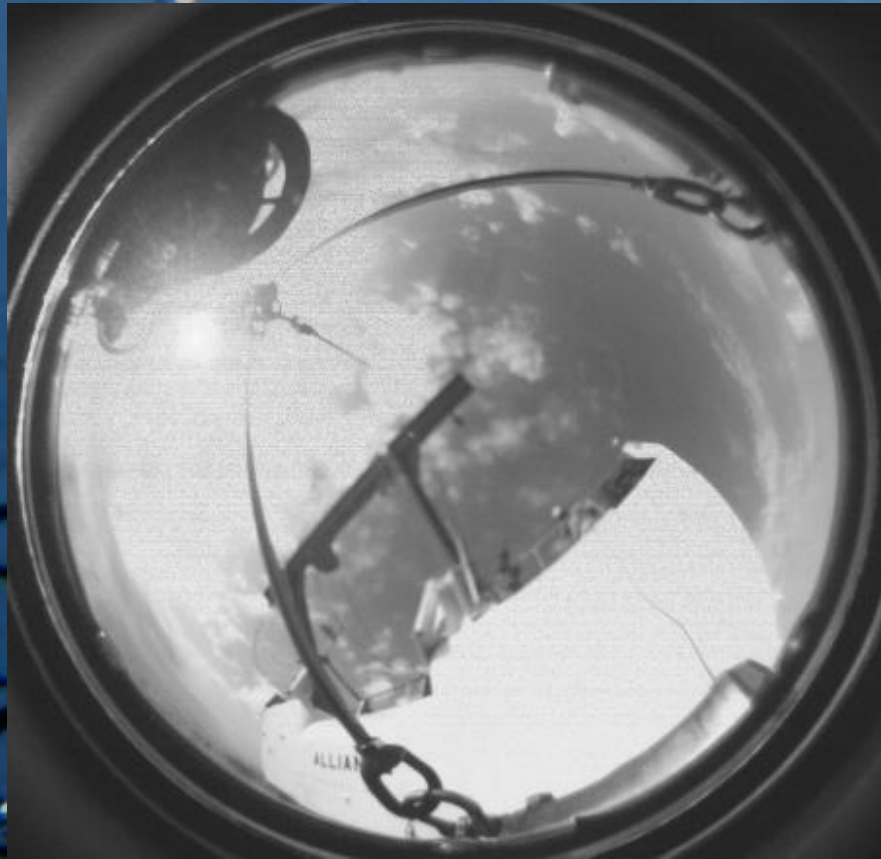
R/V Kilo Moana



Free-falling



Above and below surface downward radiance field

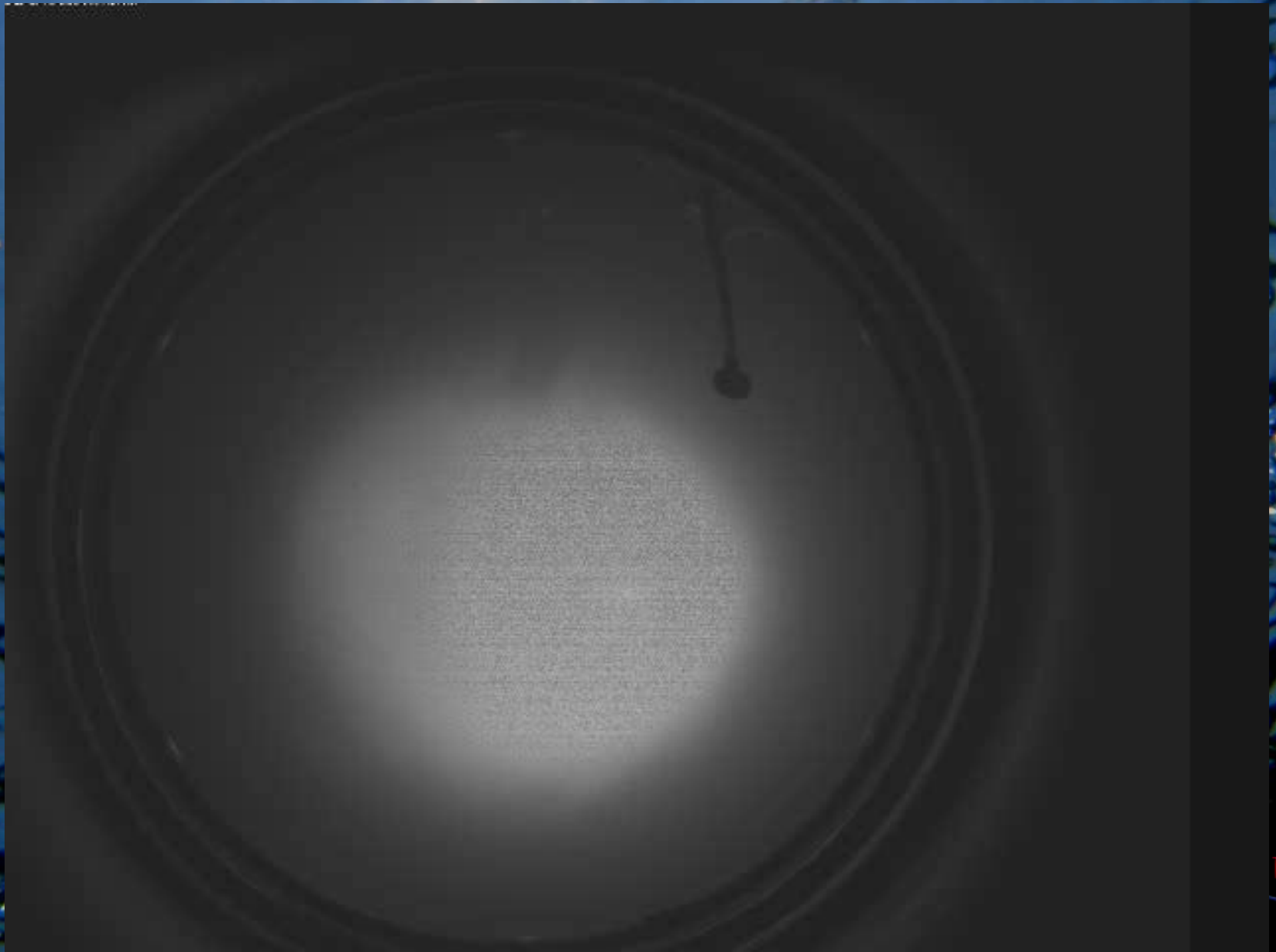


Optical manhole

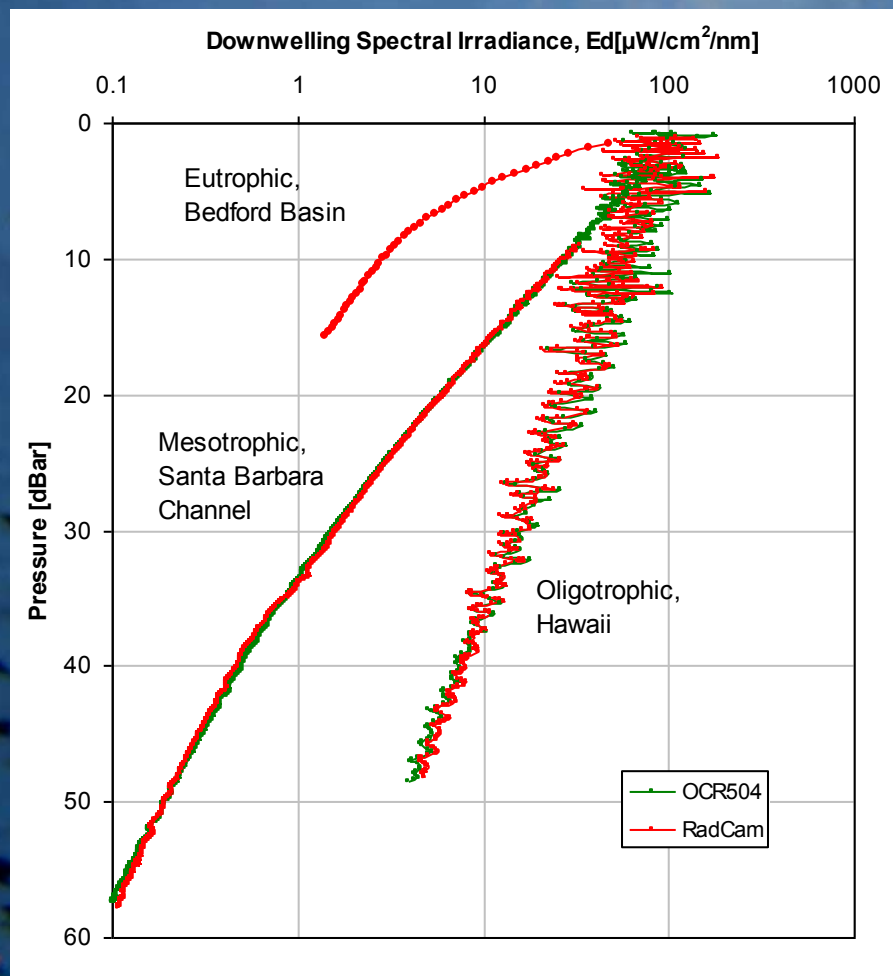




Surface and Dive



Three primary deployments for the measurement of variability in the underwater radiance distribution



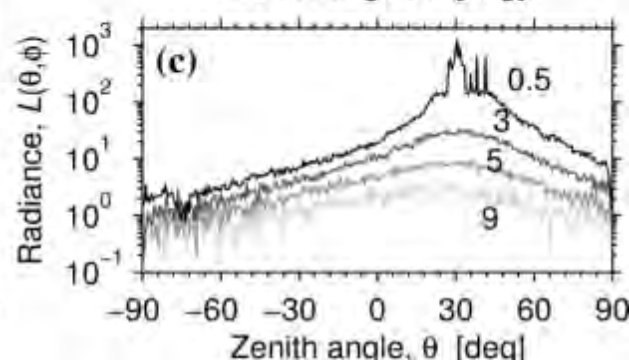
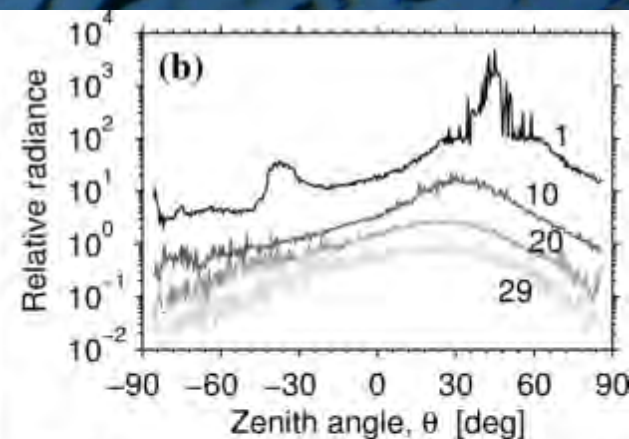
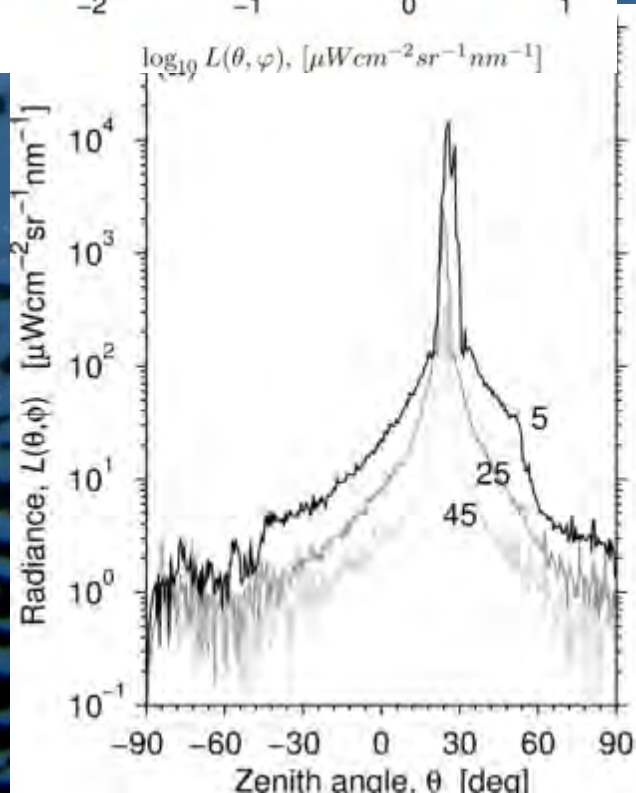
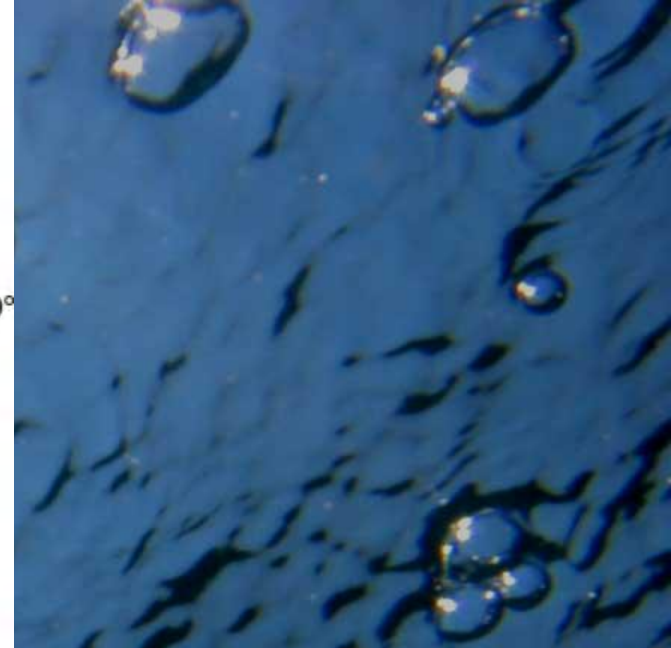
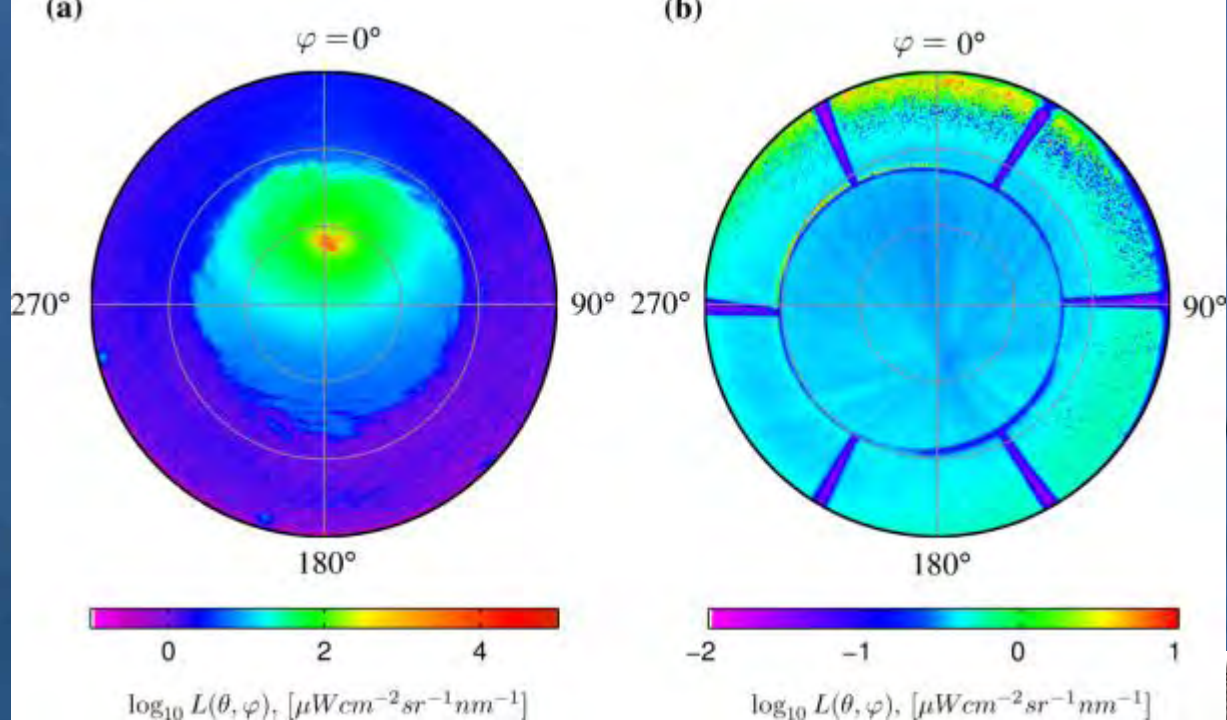
Hawaii,
Oligotrophic,
Large Waves



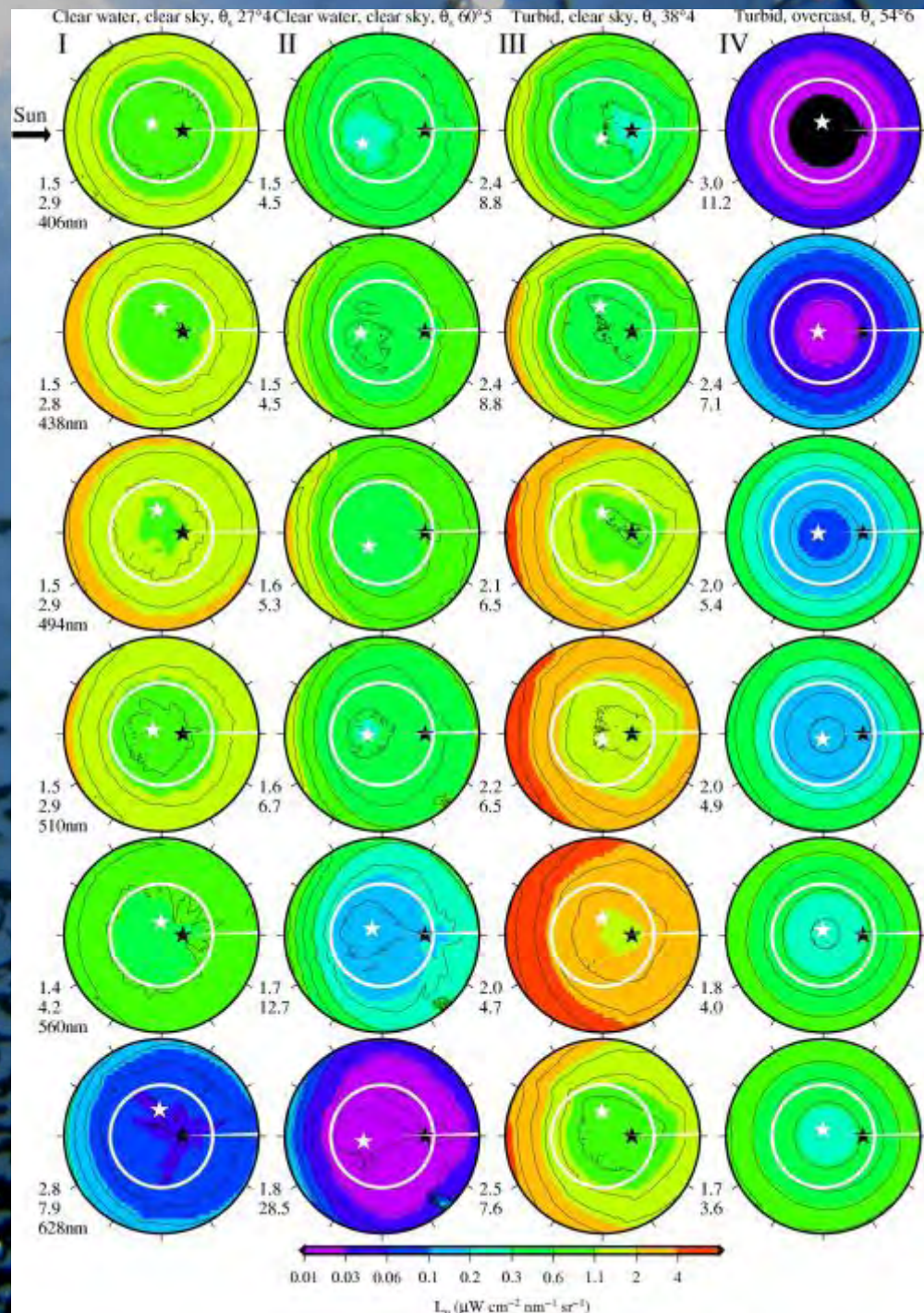
Santa Barbara,
Mesotrophic,
Small Waves



Bedford Basin,
Eutrophic,
Calm

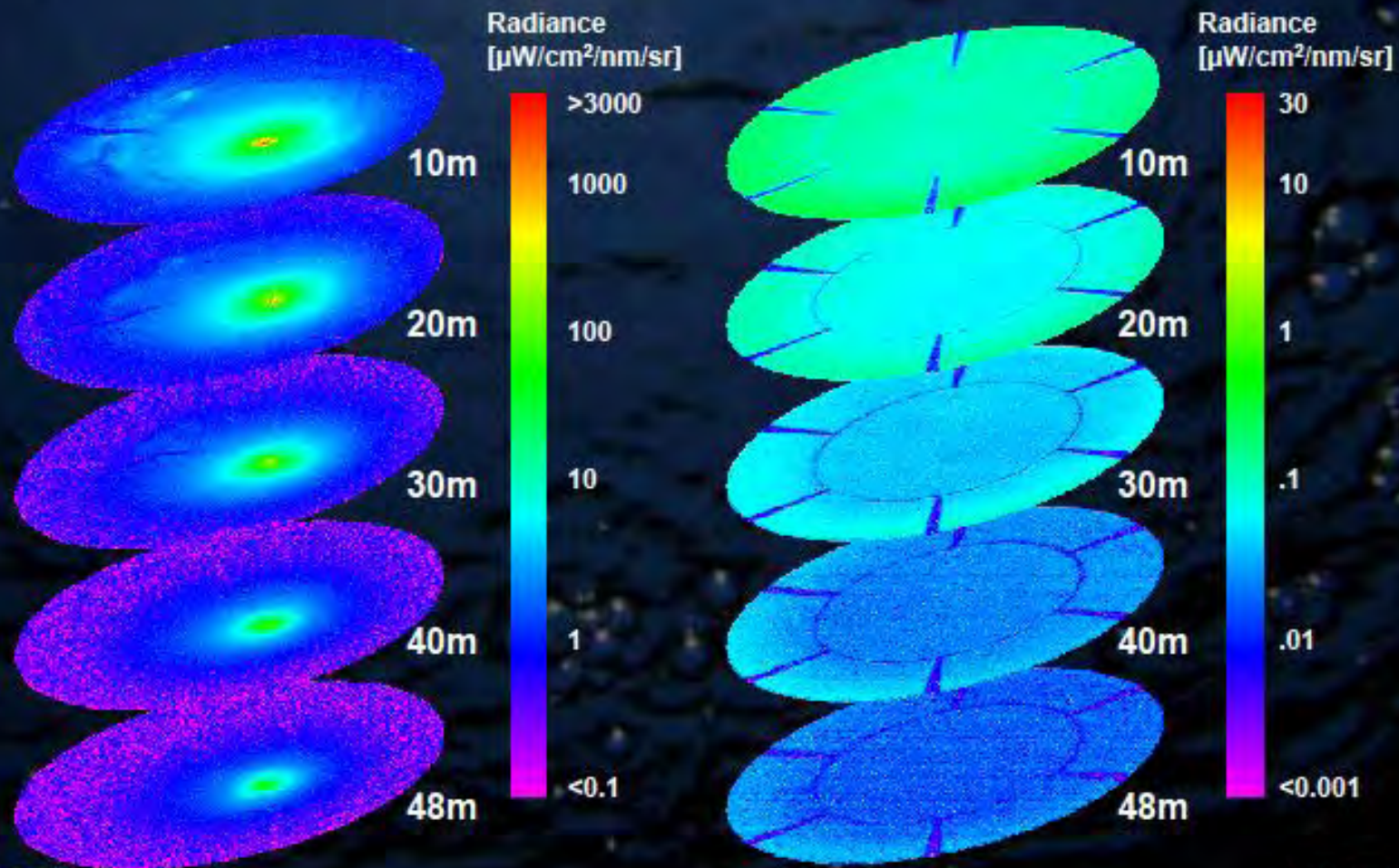


Upwelling spectral radiance distributions, 4 environments (Antoine et al. 2012)

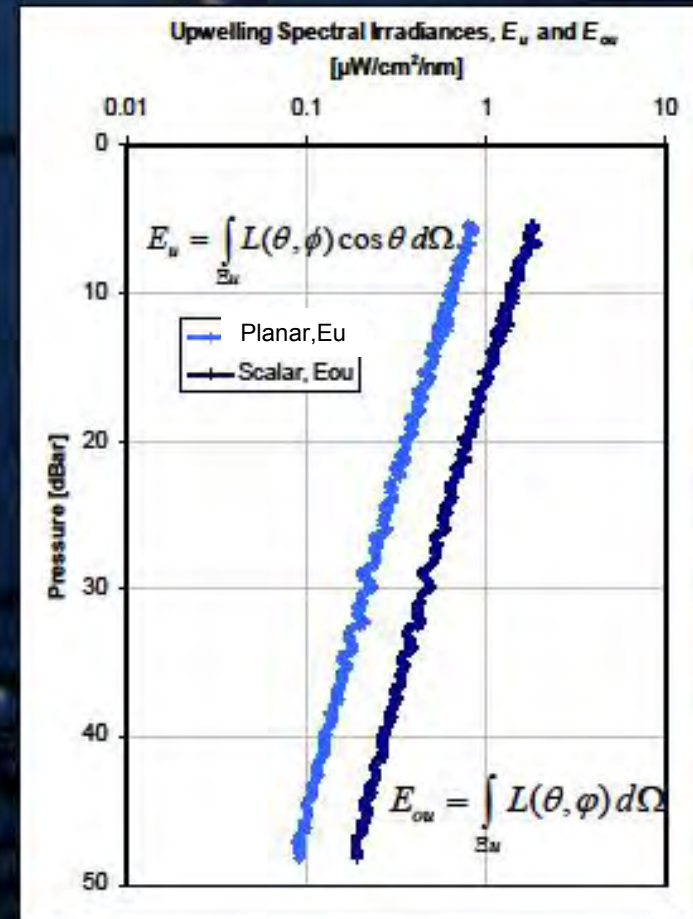
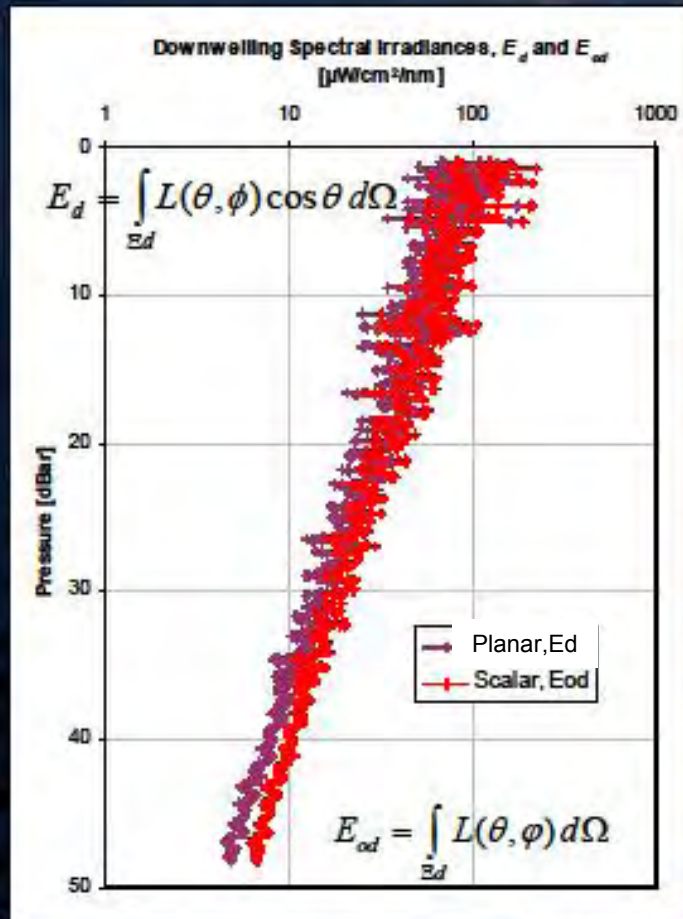


Oligotropic Environment

Hawaii - Clear Sky

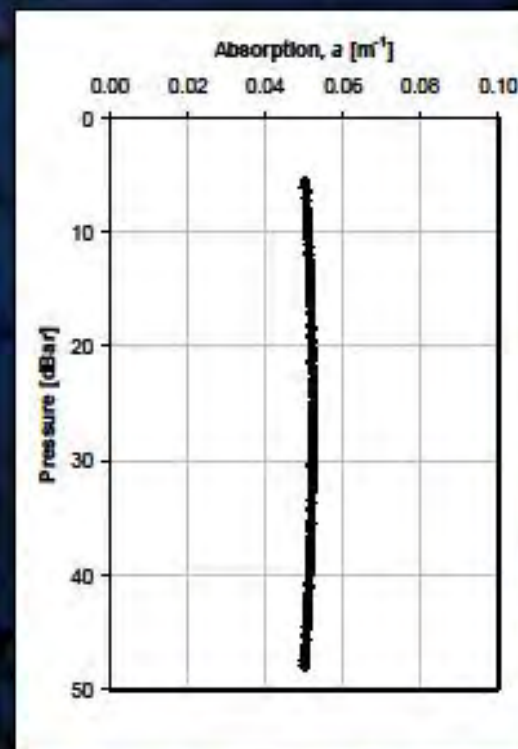
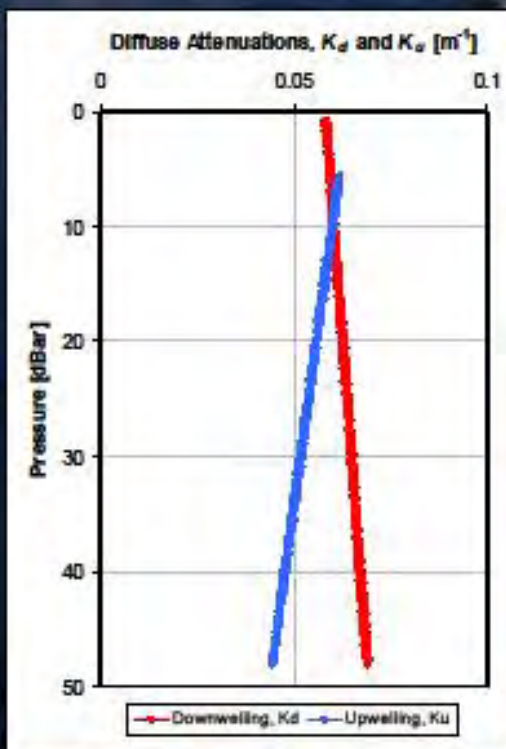
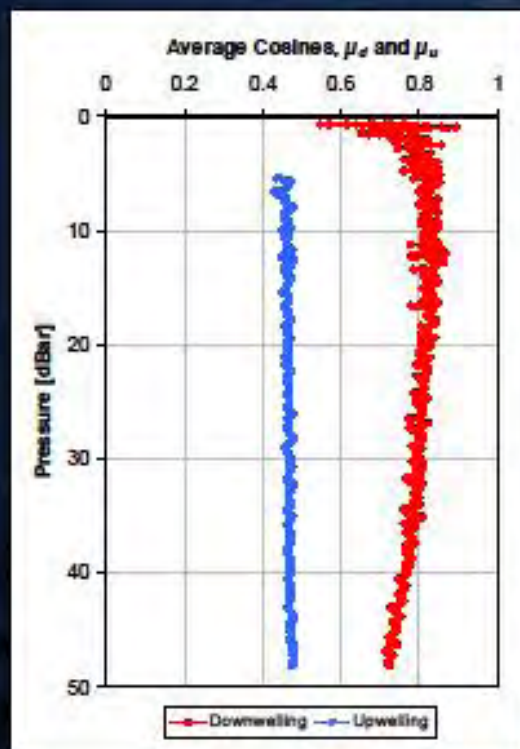


Oligotropic Environment



Irradiances found by integrating radiance fields

Oligotrophic Environment



$$\bar{\mu}_d = \frac{E_d}{E_{od}} = \frac{\int_{\Omega_d} L(\theta, \phi) \cos \theta d\Omega}{\int_{\Omega_d} L(\theta, \phi) d\Omega}$$

$$\frac{1}{E_n(z)} \frac{d(E_n(z))}{dz} = -K_n(z)$$

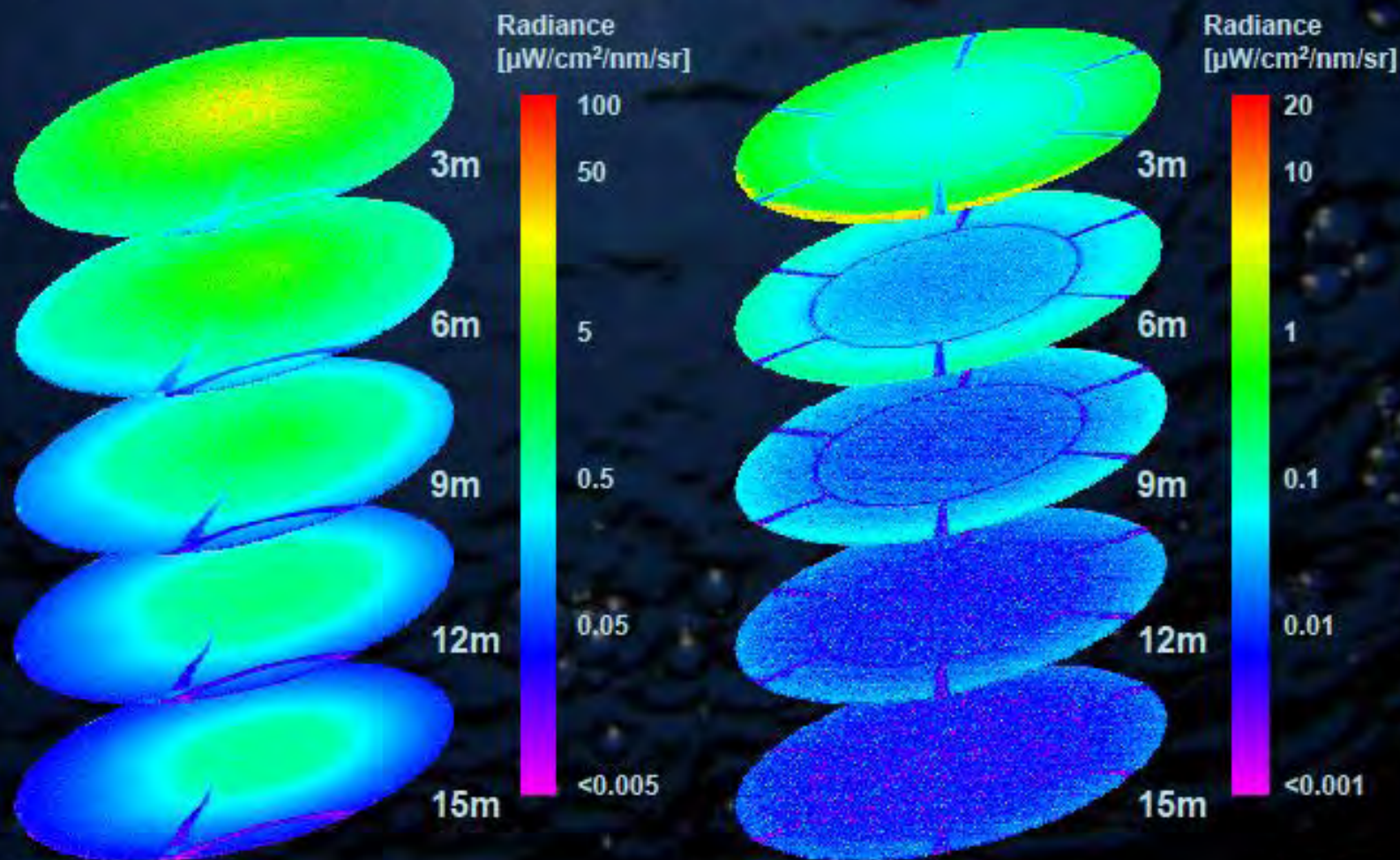
$$\nabla \cdot \mathbf{E} = -aE_o + Sources$$

All quantities calculated
from radiance fields

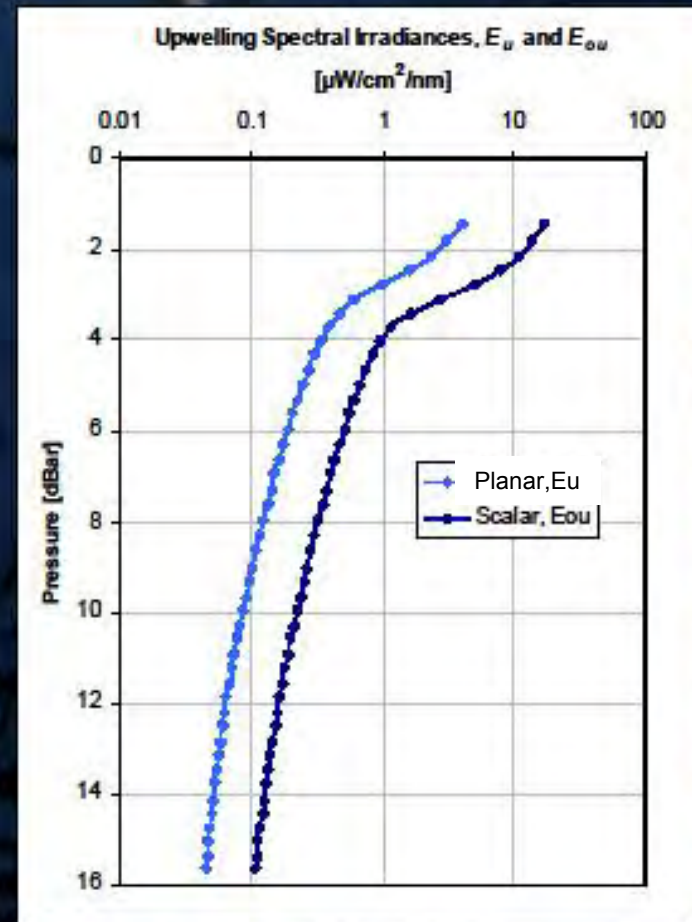
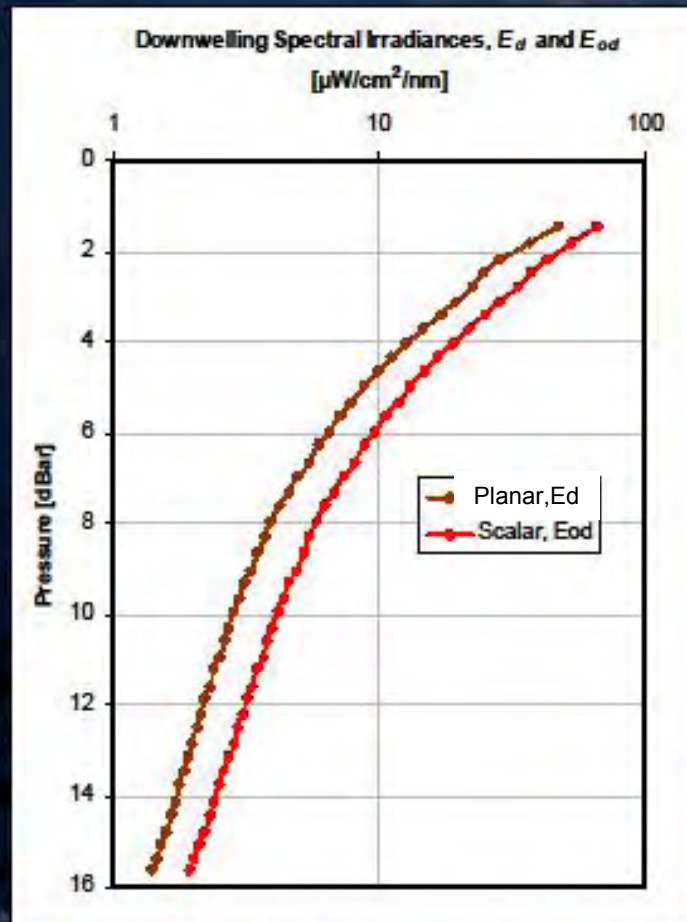


Eutrophic Environment

Bedford Basin, Nova Scotia

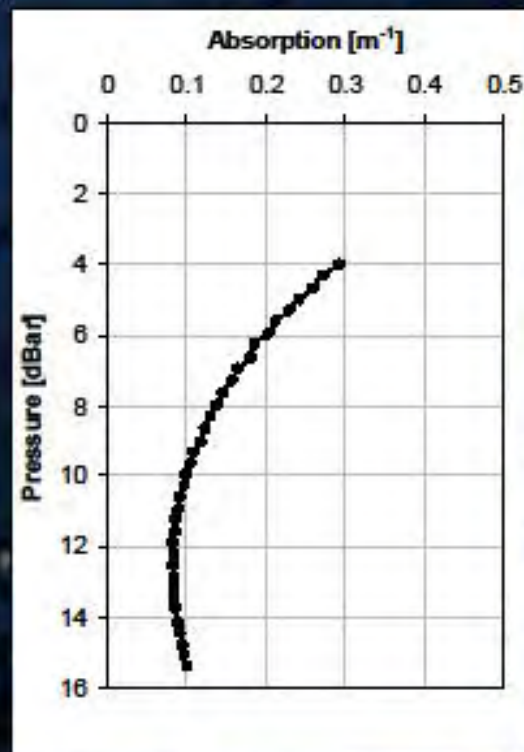
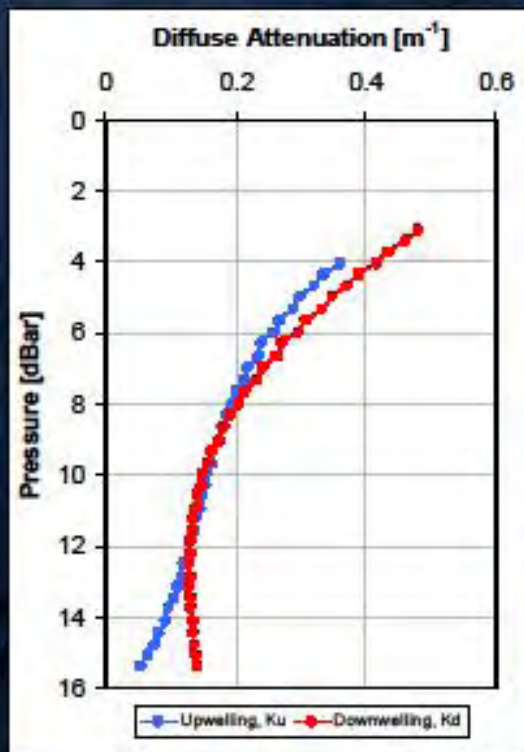
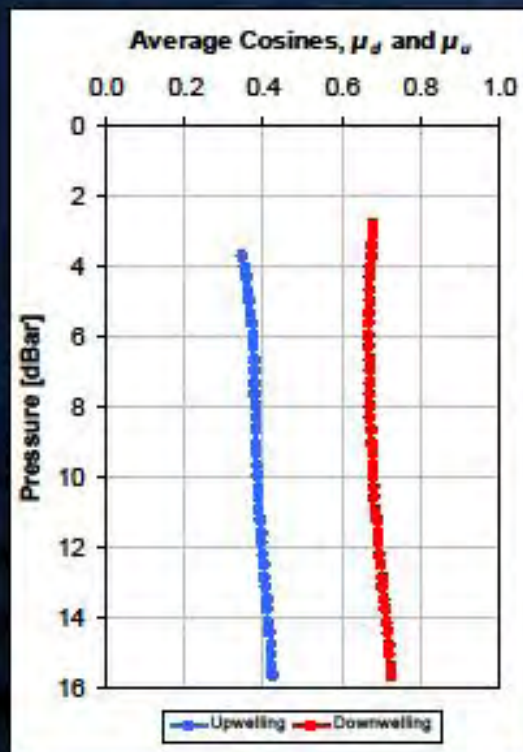


Eutrophic Environment



Irradiances found by integrating radiance fields

Eutrophic Environment



All quantities calculated from radiance fields

Time dependency

Profile, Downwelling



Profile, Upwelling



Even with all of this...can we
invert for $\beta(\theta)$?

$$\cos \theta \frac{dL(z, \theta, \varphi)}{dz} = -cL(z, \theta, \varphi) + \int_{\Xi} \beta(\theta', \varphi' \rightarrow \theta, \varphi) L(z, \theta', \varphi') d\Omega' + \text{Other Sources}$$

Zaneveld and Pak, 1972?

Other (analytical, numerical) approaches?

Or can we do something really
useful???



Avatar II!

Measurement of in-situ optical properties (contd)

Marlon R. Lewis

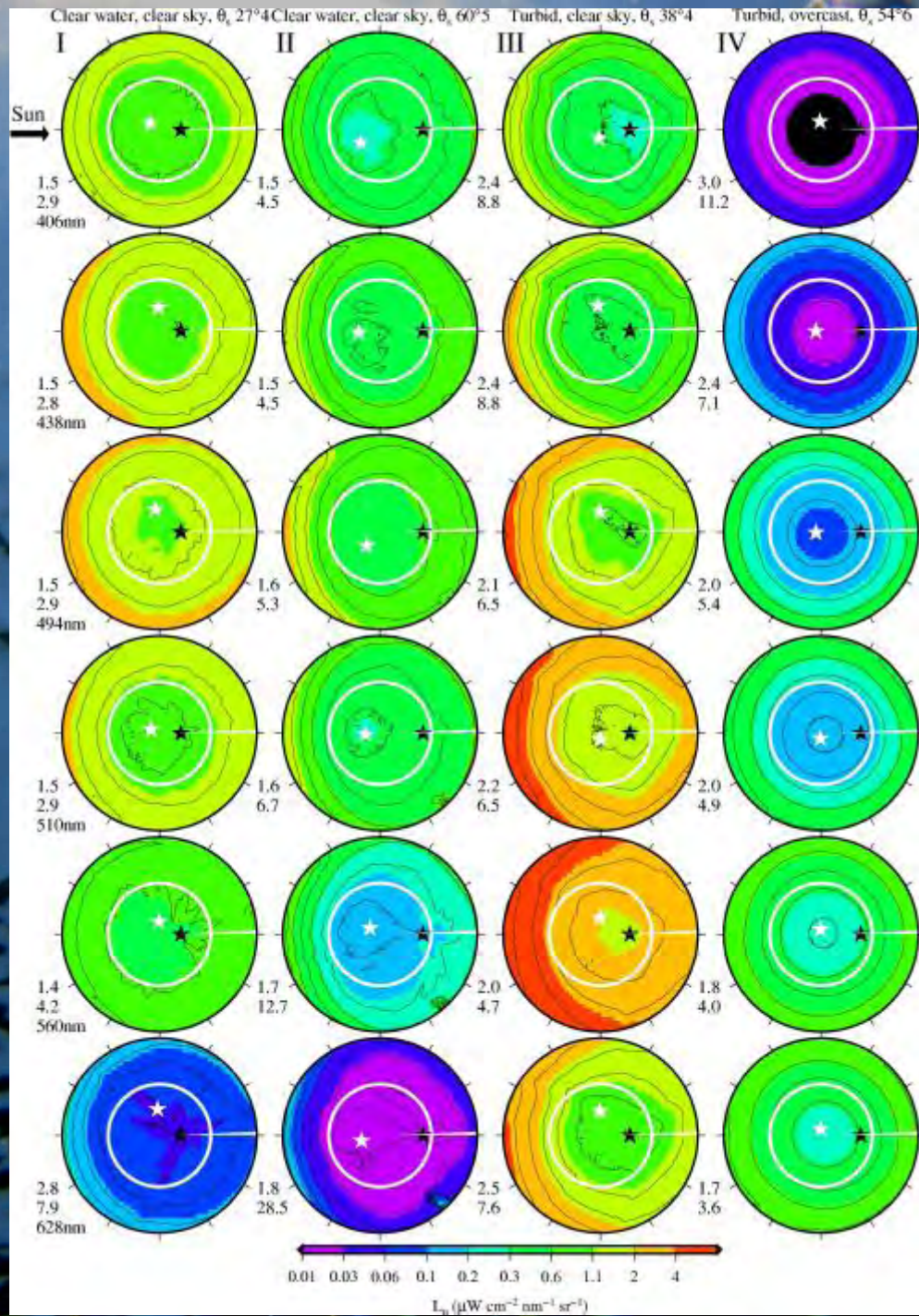
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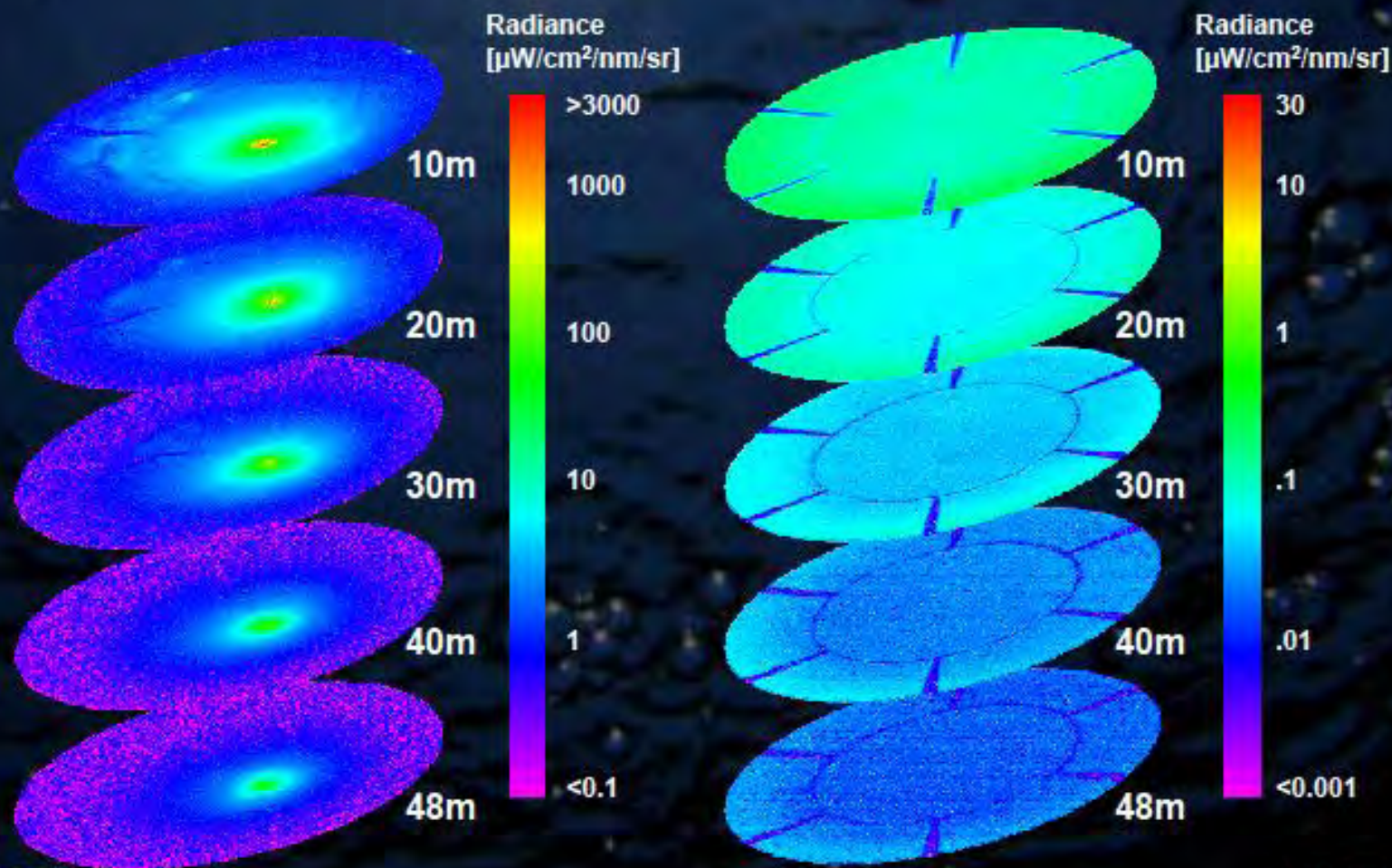
& Founder/Chief Scientist, Satlantic LP/SeaBird Scientific.

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Oligotropic Environment

Hawaii - Clear Sky



So why do anything other than
measure the full radiance distribution??

The RADCAM only has one wavelength.
(LOV has several, but not simultaneous)

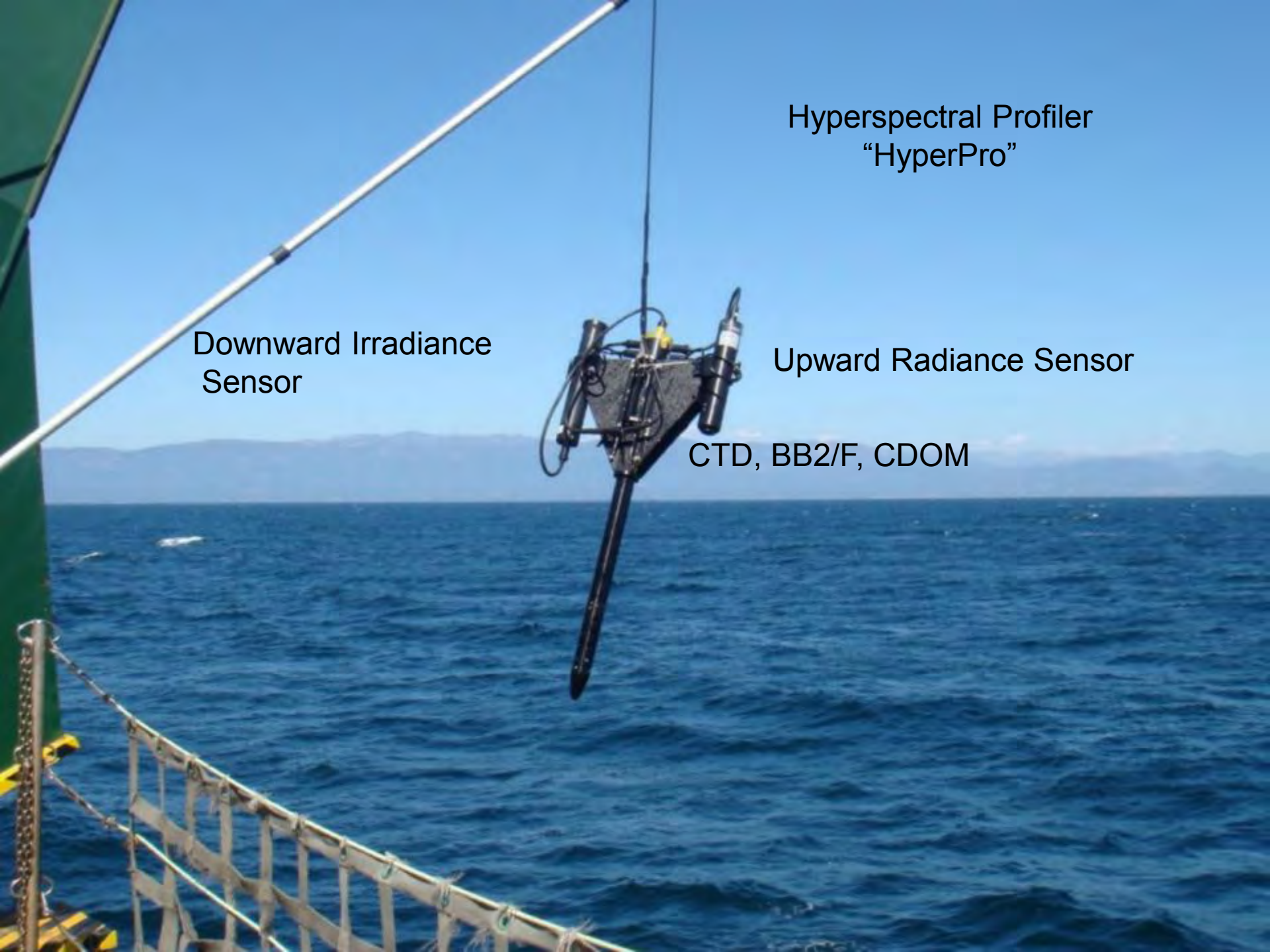
The RADCAM & LOV cam are insensitive to
polarization state (Ken Voss has POLRad with
separate cameras, but long integration times)

And all of these are expensive, and unlikely to
be widely available.

Life consists of tradeoffs.

More Practical Approaches





Hyperspectral Profiler
“HyperPro”

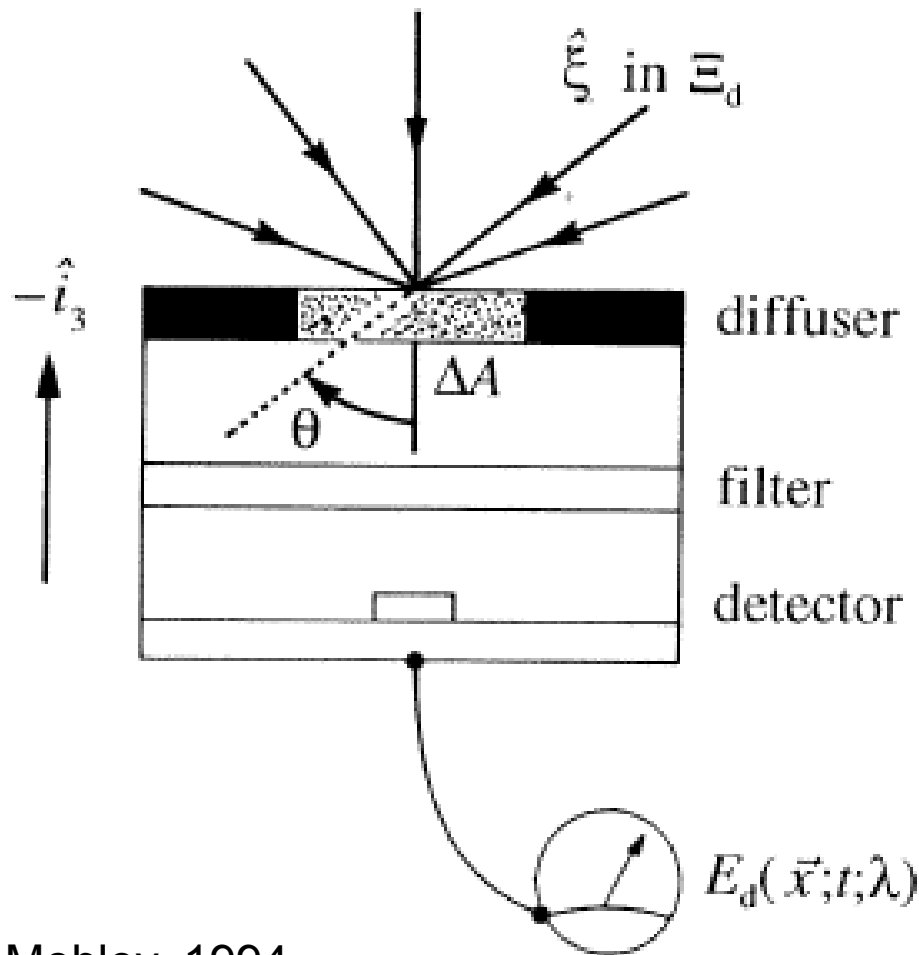
Downward Irradiance
Sensor

Upward Radiance Sensor

CTD, BB2/F, CDOM



Planar Irradiance Sensor – “Built – in” integration



Mobley, 1994

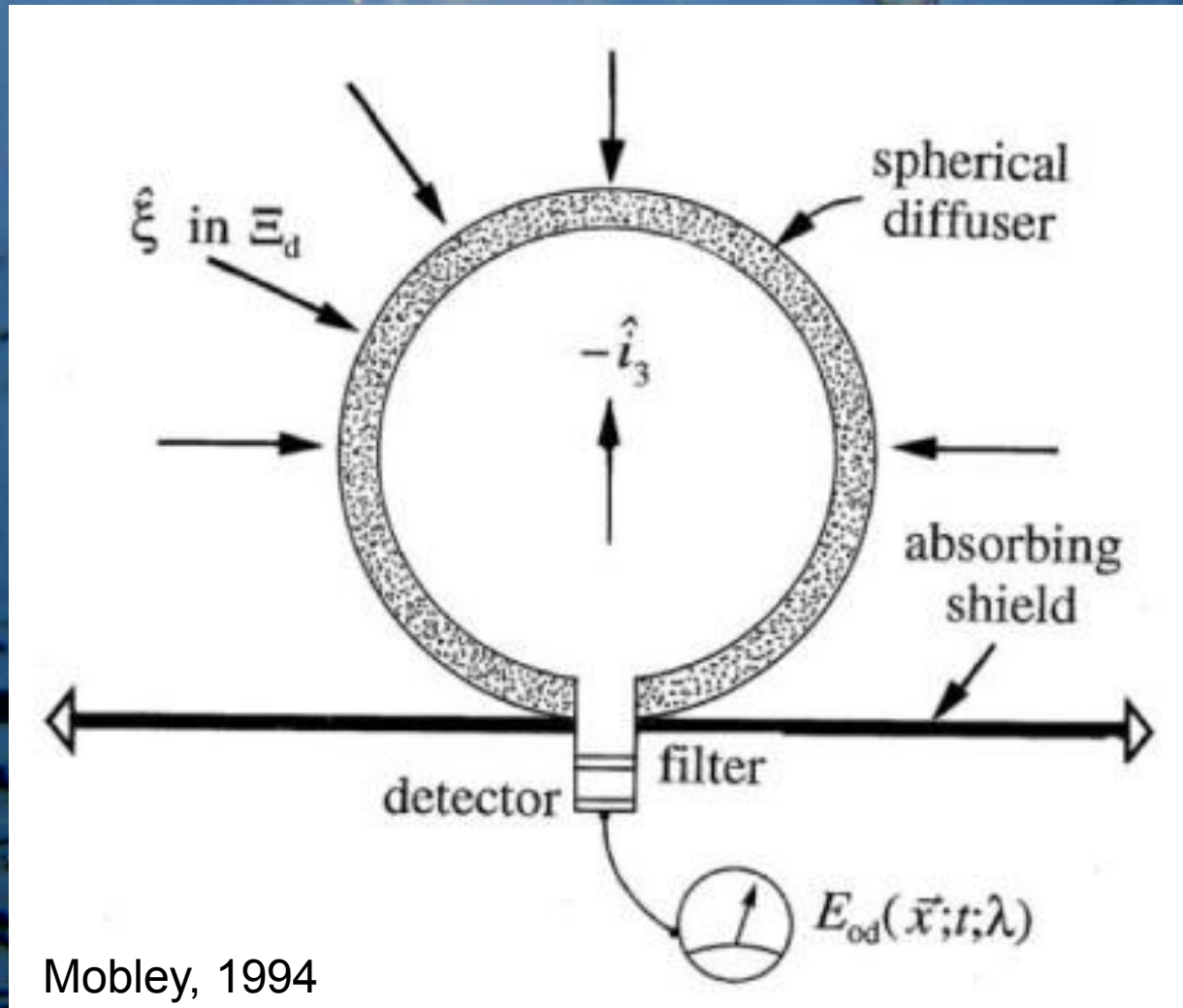
Diffuser weights incoming photons as $\cos(\theta)$

“Filter could be grating or prism or spectrally variable filter

Detector could be 2 or 3 D array, e.g. CCD or CMOS

$$E_d(\vec{x}, t, \lambda) = \int_{\hat{\xi} \in \Xi_d} L(\vec{x}, t, \hat{\xi}, \lambda) |\cos \theta| d\Omega(\hat{\xi}) =$$

Scalar Irradiance Sensor



Mobley, 1994

Irradiance Sensors



Chelsea Inst.



LiCor



Satlantic



Biospherical



Satlantic

Single Direction Radiance Sensors



Satlantic

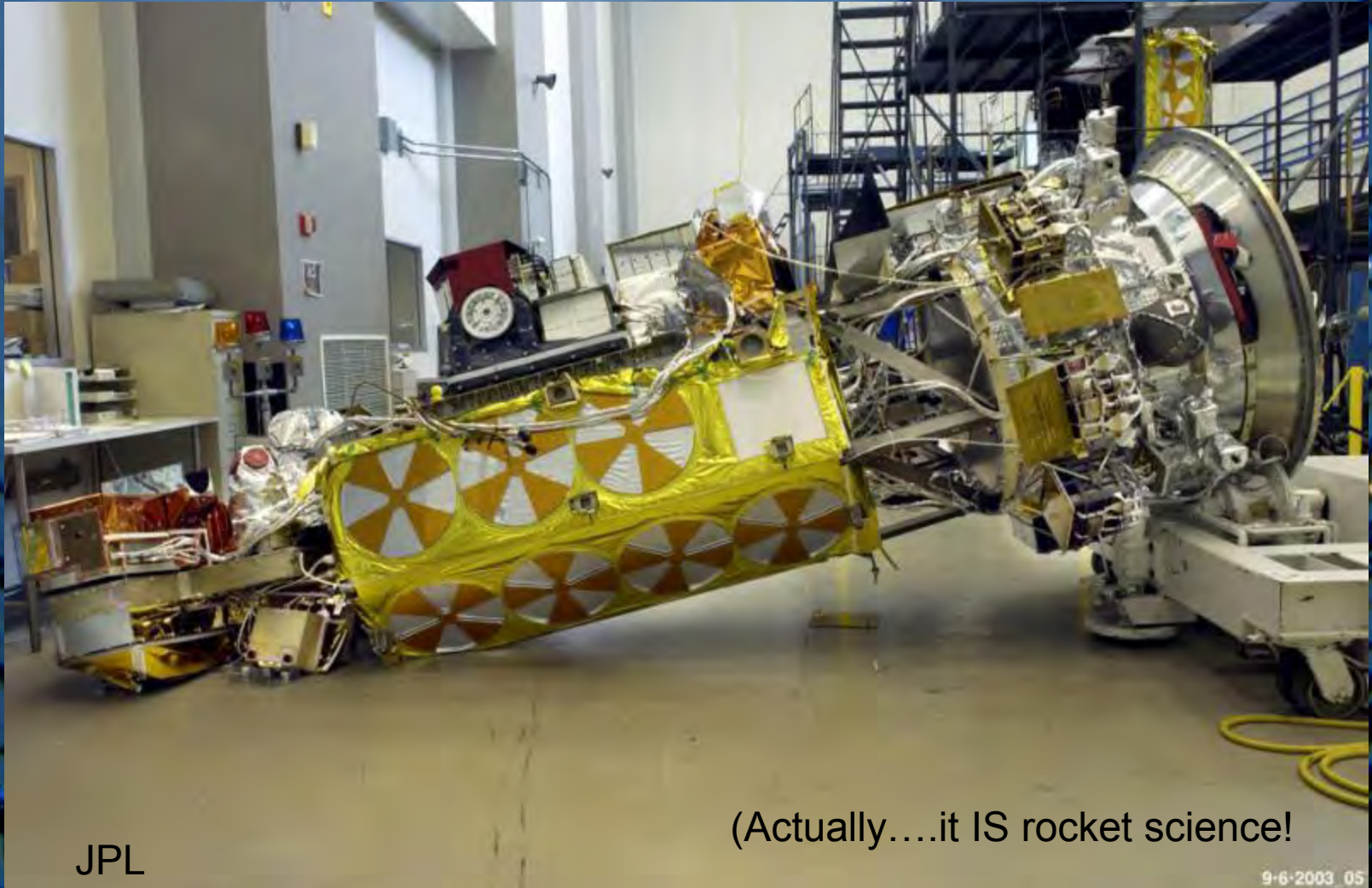


Analytical Spectral Devices



GER

Really big radiance sensors...oops!

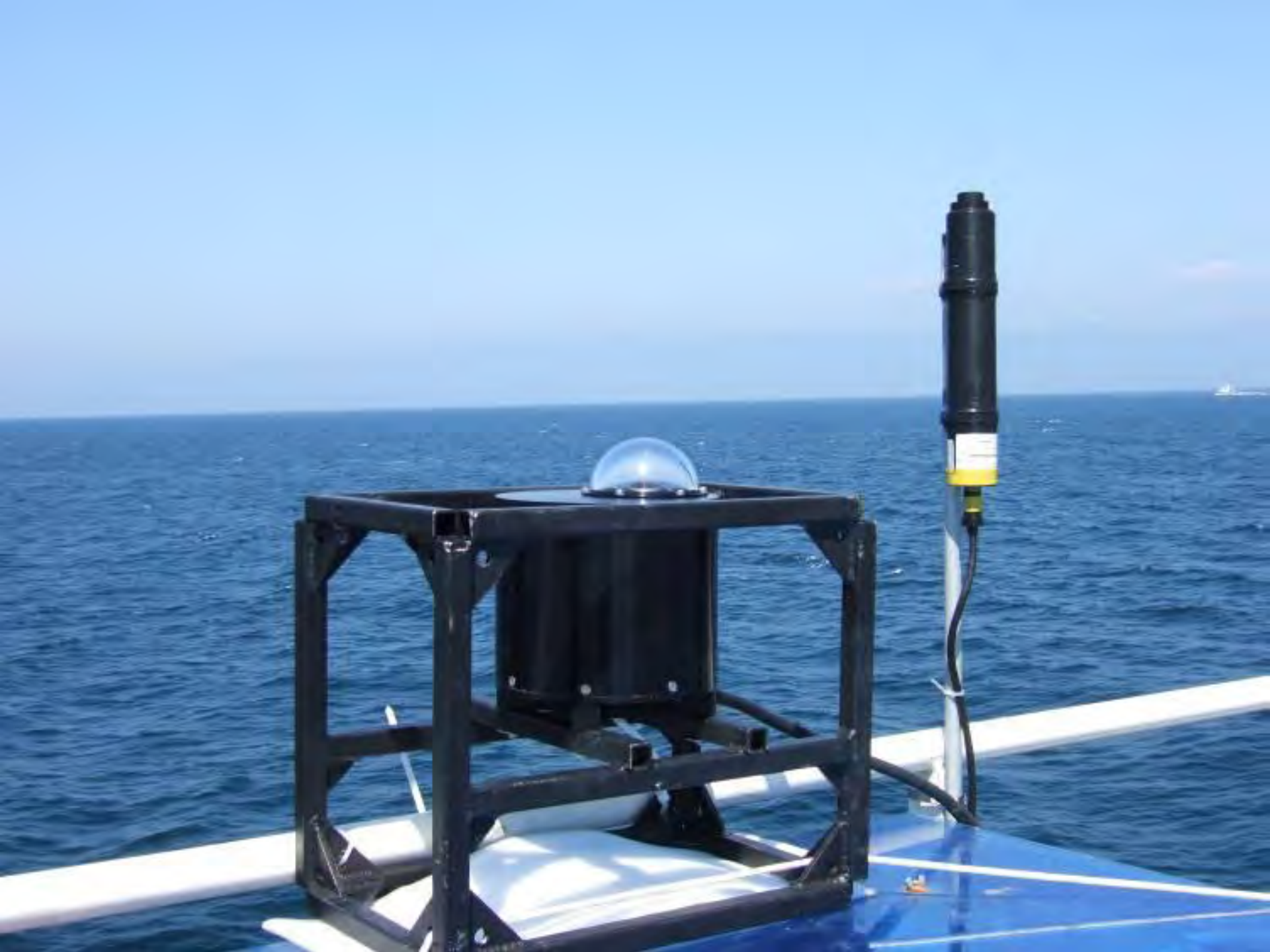


JPL

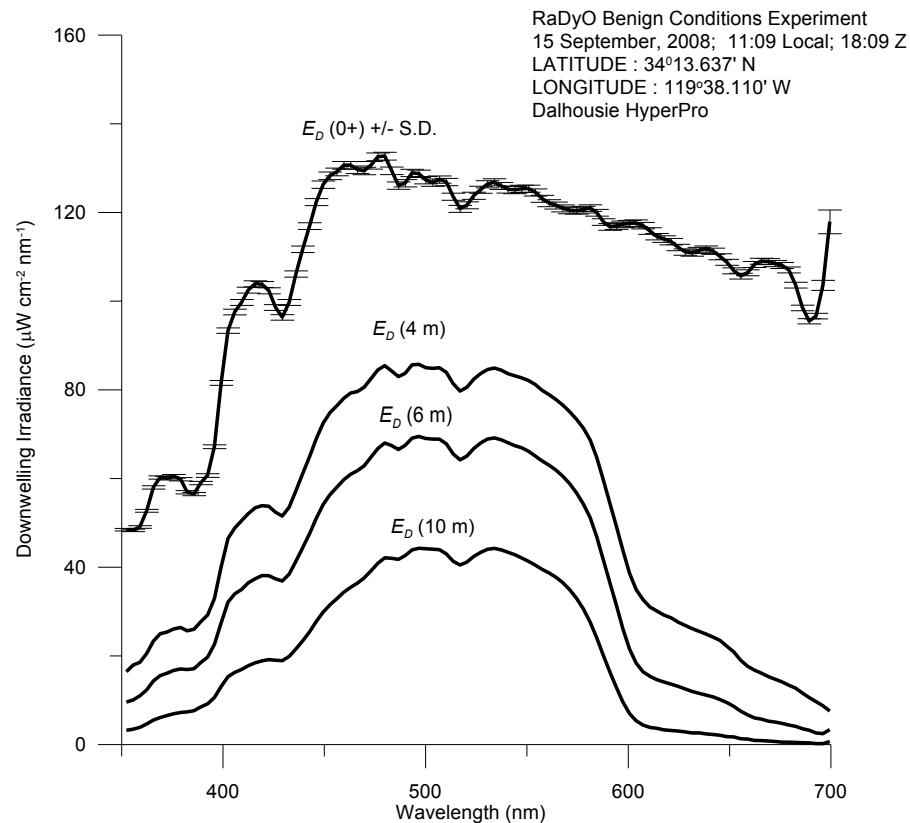
(Actually....it IS rocket science!

9-6-2003 05

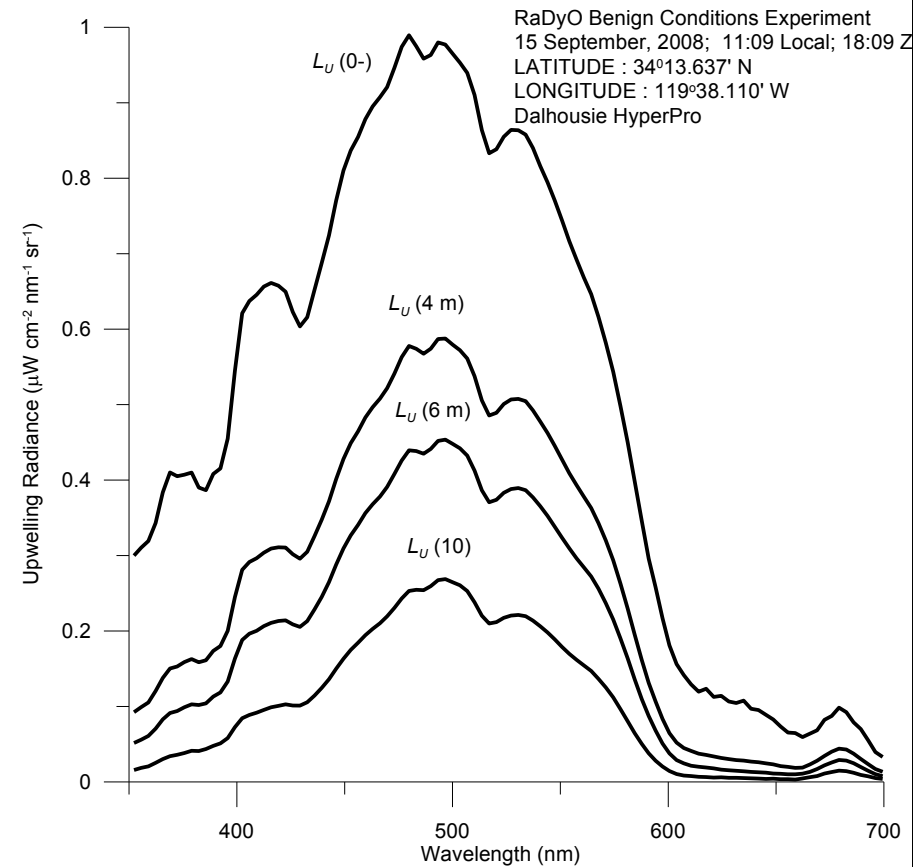
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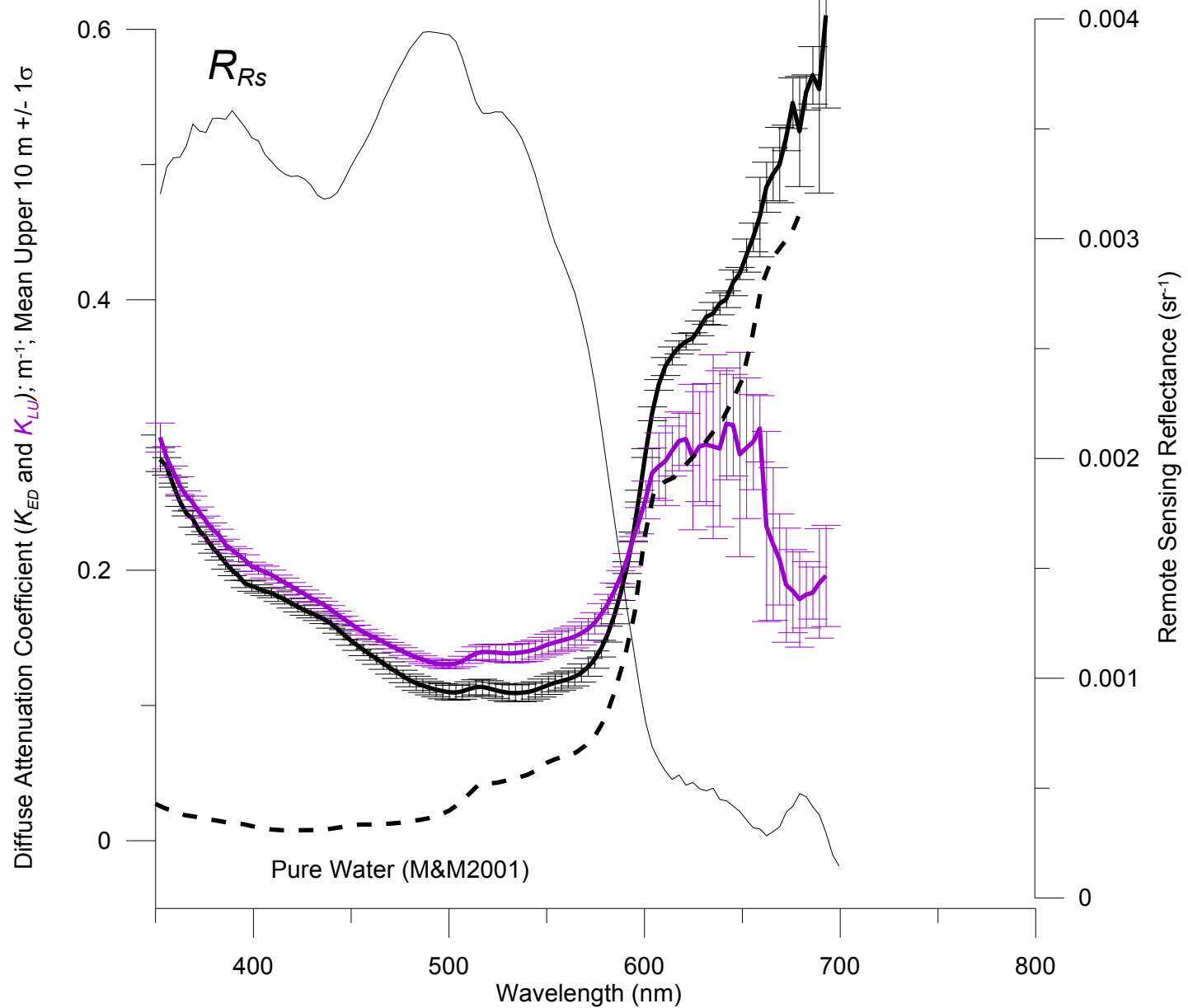
Downwelling Spectral Irradiance



Upwelling Nadir Radiance



RaDyO Benign Conditions Experiment
15 September, 2008; 11:09 Local; 18:09 Z
LATITUDE : 34°13.637' N
LONGITUDE : 119°38.110' W
Dalhousie HyperPro



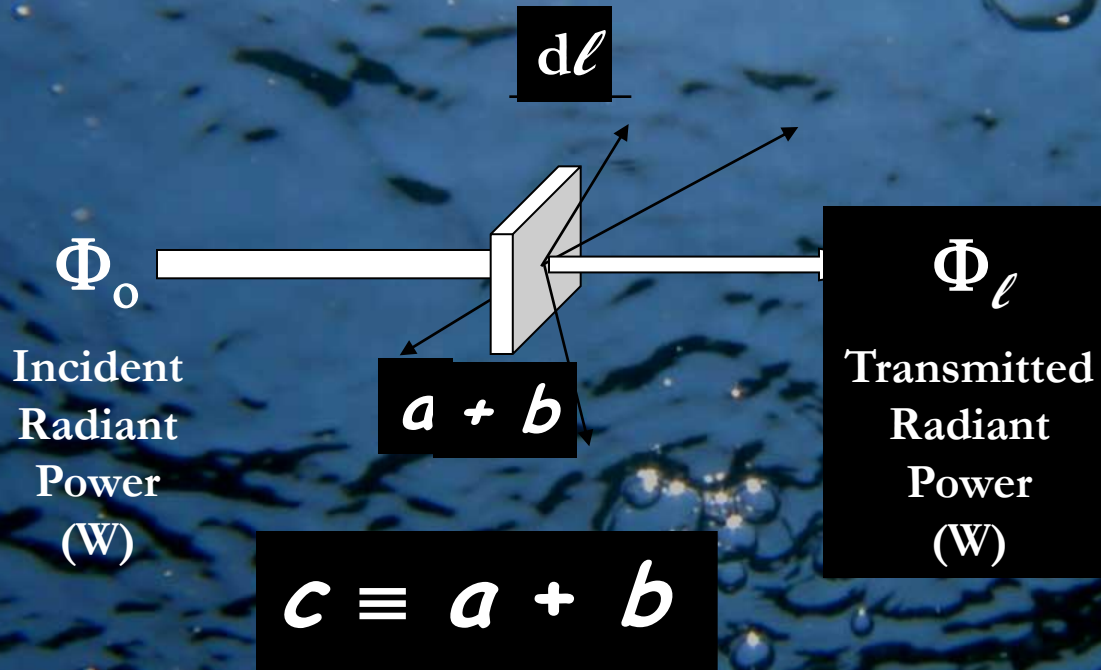
IOP's can be independently measured (“a,b,c’s”)

- Attenuation – c
 - ac meter
 - Transmissometer (BAM, c-Star, c-Rover)
- Absorption - a
 - ac meter
- Scattering - b
 - (bb, Hydroscat, Flntu, VSF)
- CTD
 - Conductivity, temperature, depth



Attenuation: theory to measurement

$$\cos \theta \frac{dL(z, \theta, \varphi)}{dz} = -cL(z, \theta, \varphi) + \int_{\Xi} \beta(\theta', \varphi' \rightarrow \theta, \varphi) L(z, \theta', \varphi') d\Omega' + \text{Other Sources}$$



$$c\Phi = -\frac{d\Phi}{d\ell}$$

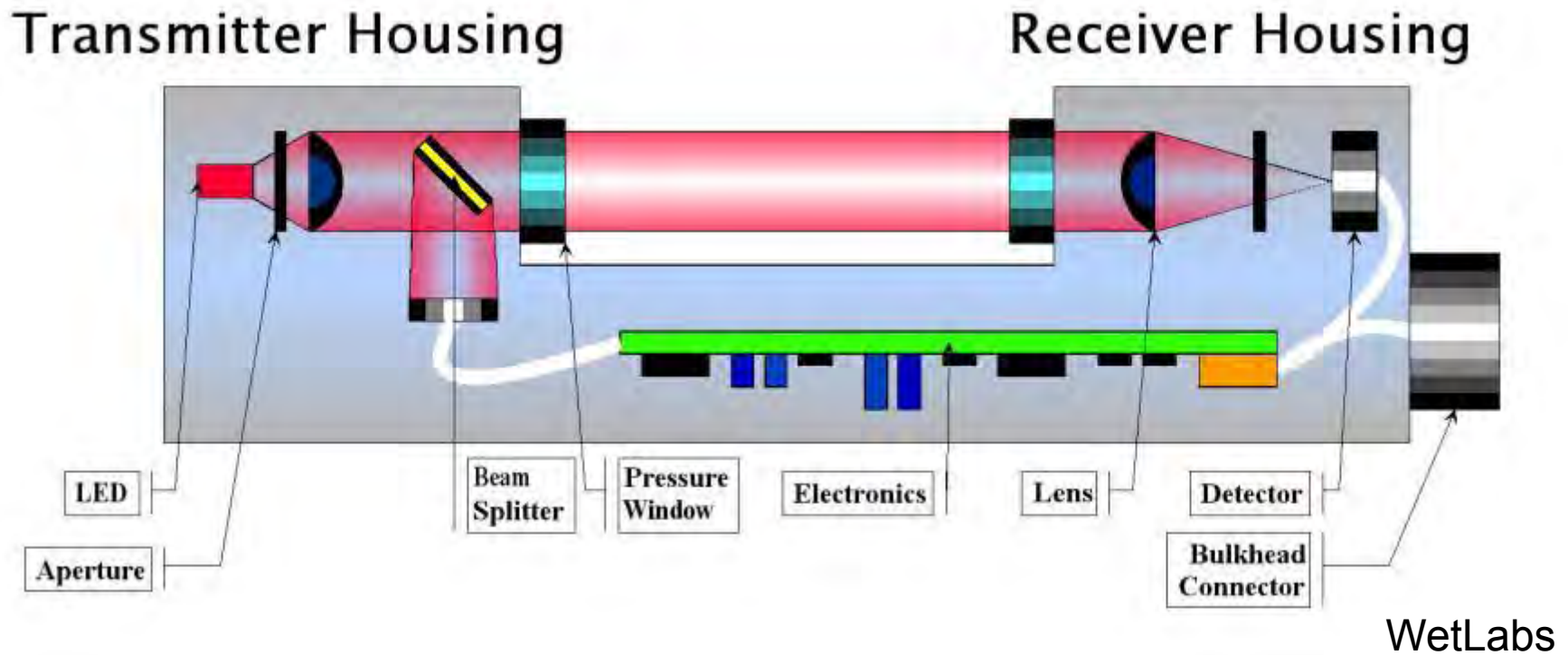
Differential Equation
with solution:

$$\Phi_\ell = \Phi_0 \exp\left(-\int_0^\ell c d\ell\right)$$

After integration:

$$\Phi_\ell = \Phi_0 e^{-\bar{c}\ell}$$

Beam attenuation meter

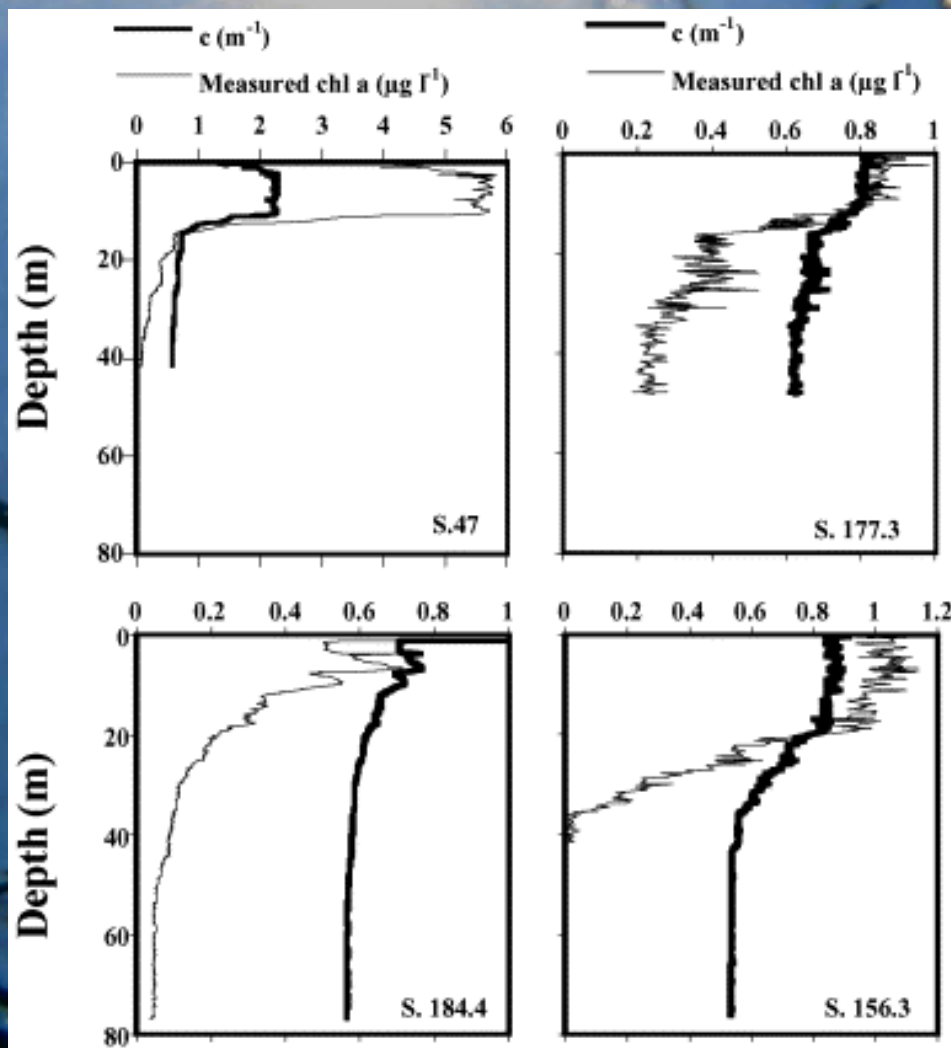


Measure of water clarity, POC, particles

Some things to think about....

- Acceptance angle – for C-Star, 1.2 degrees
- “Reference” or clear-water baseline – clear water is very difficult to “make”, transport, store
- “noise” (signal?) due to individual or aggregates of particles





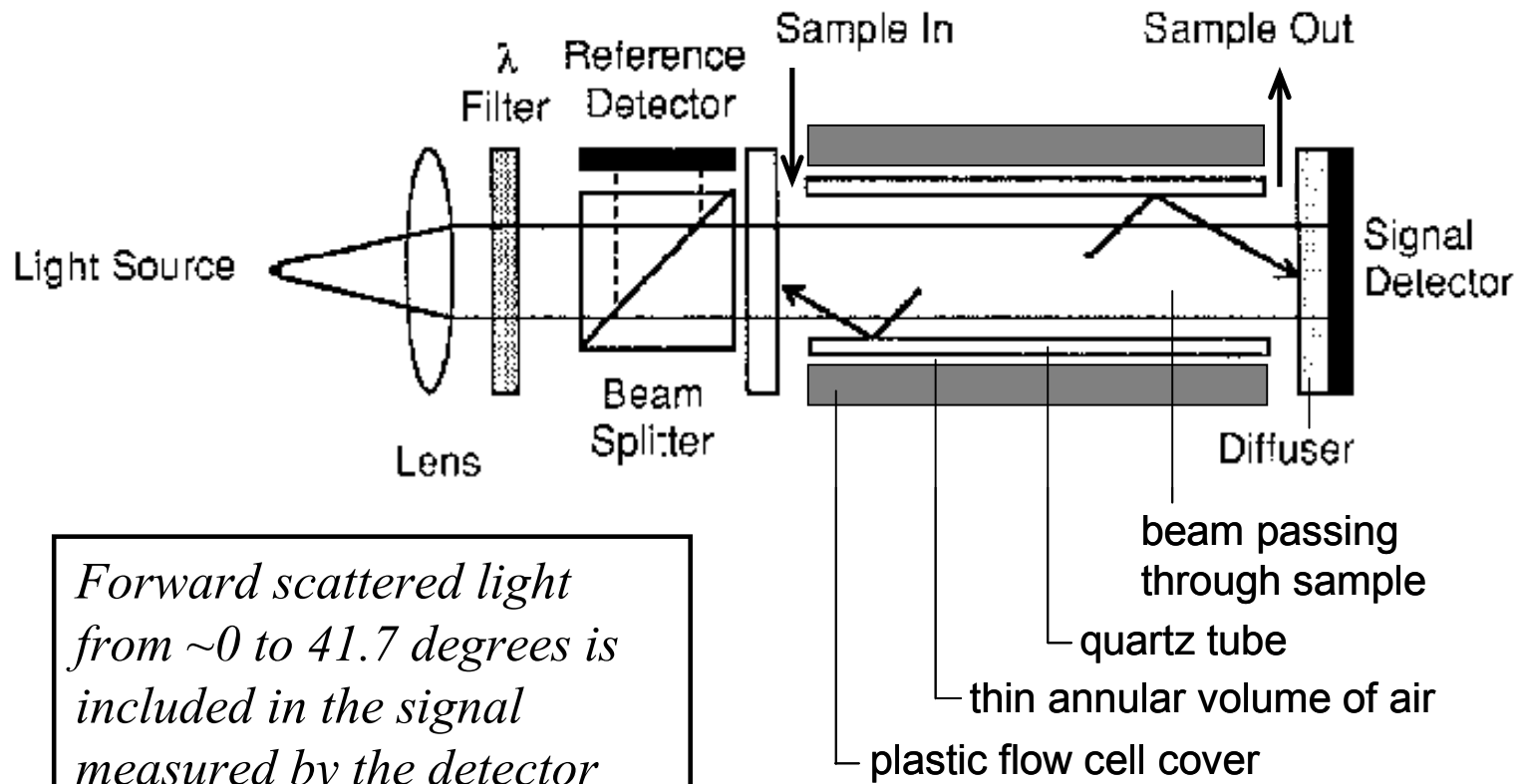
Figuro 2002

Methods of measuring absorption in situ

- Collimated source, reflective sample cell with diffuser in front of wide area detector: WET Labs' ac-s meter
- Capillary waveguide ("breve buster," Kirkpatrick et al. 2000)
- Integrating Sphere, e.g. Hobbi Lab's iSphere

Measuring absorption: Reflective tube method

Reflective tube absorption meter design



*Forward scattered light
from ~ 0 to 41.7 degrees is
included in the signal
measured by the detector*

Practicalities in measuring absorption with a reflective tube

- Calibration and accuracy practicalities same as c measurement
- **Scattered light from $\sim 41^\circ$ - 180° not measured**
 - error usually $\sim 10\%$ of b and there are correction schemes

$$error = b_{\theta_{TIR}:180^\circ} = 2\pi \int_{\sim\theta_{TIR}}^{\sim 180^\circ} \beta(\theta) \sin(\theta) d\theta$$

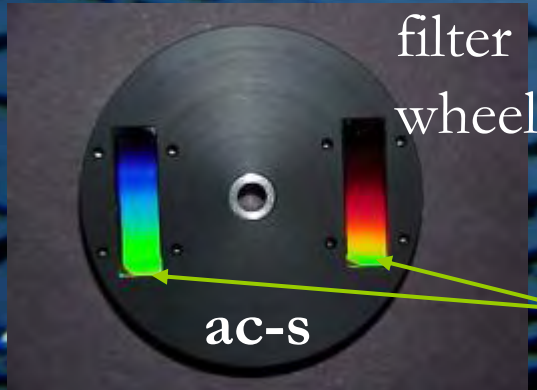
TIR=Total
Internal
Reflection

Or expressed more accurately, there is a weighting function, $W(\theta)$, that defines the scattering error:

$$error = 2\pi \int_{0^\circ}^{180^\circ} W(\theta) \beta(\theta) \sin(\theta) d\theta$$

ac-9 and ac-S

WetLabs



Linear Variable Filters
(LVFs)



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Point-Source Integrating Cavity approaches(Kirk, 1997)



PSI-Cam, Rudiger Rottgers



a-sphere, HOBI Labs

Liquid Capillary Waveguide Approaches

Fiber optic cells that combine an increased optical pathlength (50–500cm) with small sample volumes (125–1250 μ L). They can be connected a spectrophotometer and sensitive absorbance measurements can be performed in the ultraviolet (UV), visible (VIS) and near-infrared (NIR) to detect low sample concentrations.



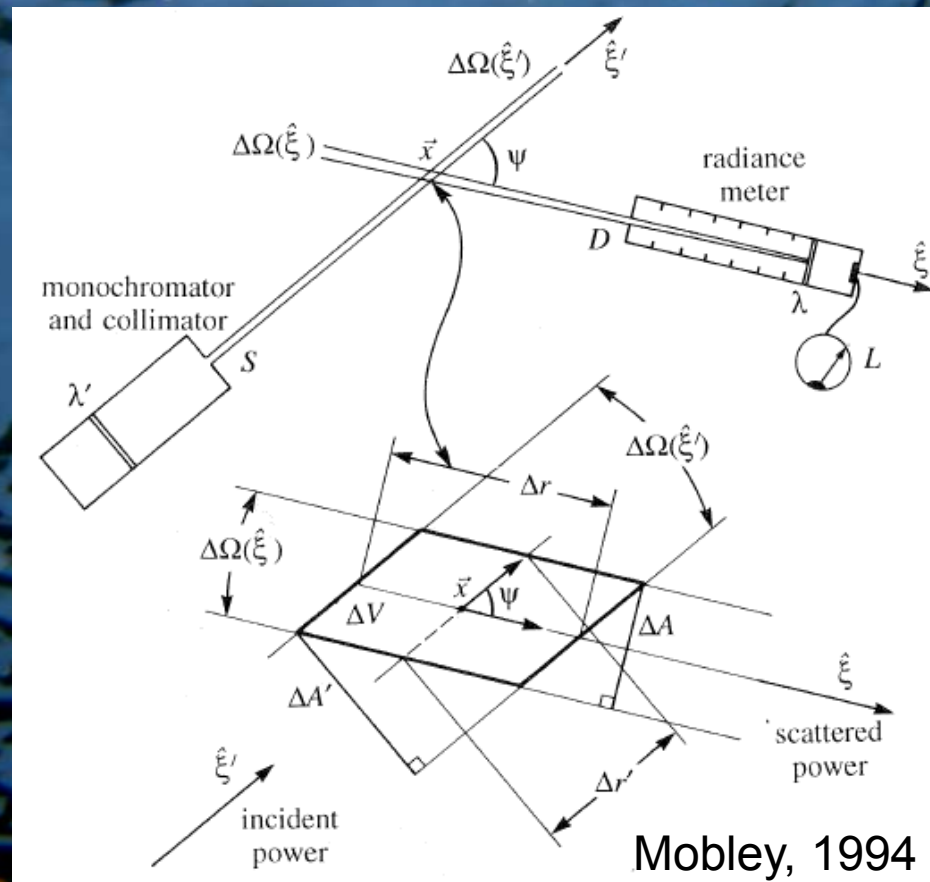
World Precision Instruments

SATLANTIC

Scattering

1. Full volume scattering function

2. Scattering at sub-sets of angles



Volume Scattering Function

Deep-Sea Research, 1968, Vol. 15, pp. 423 to 432.

Scattering of light by Sargasso Sea water

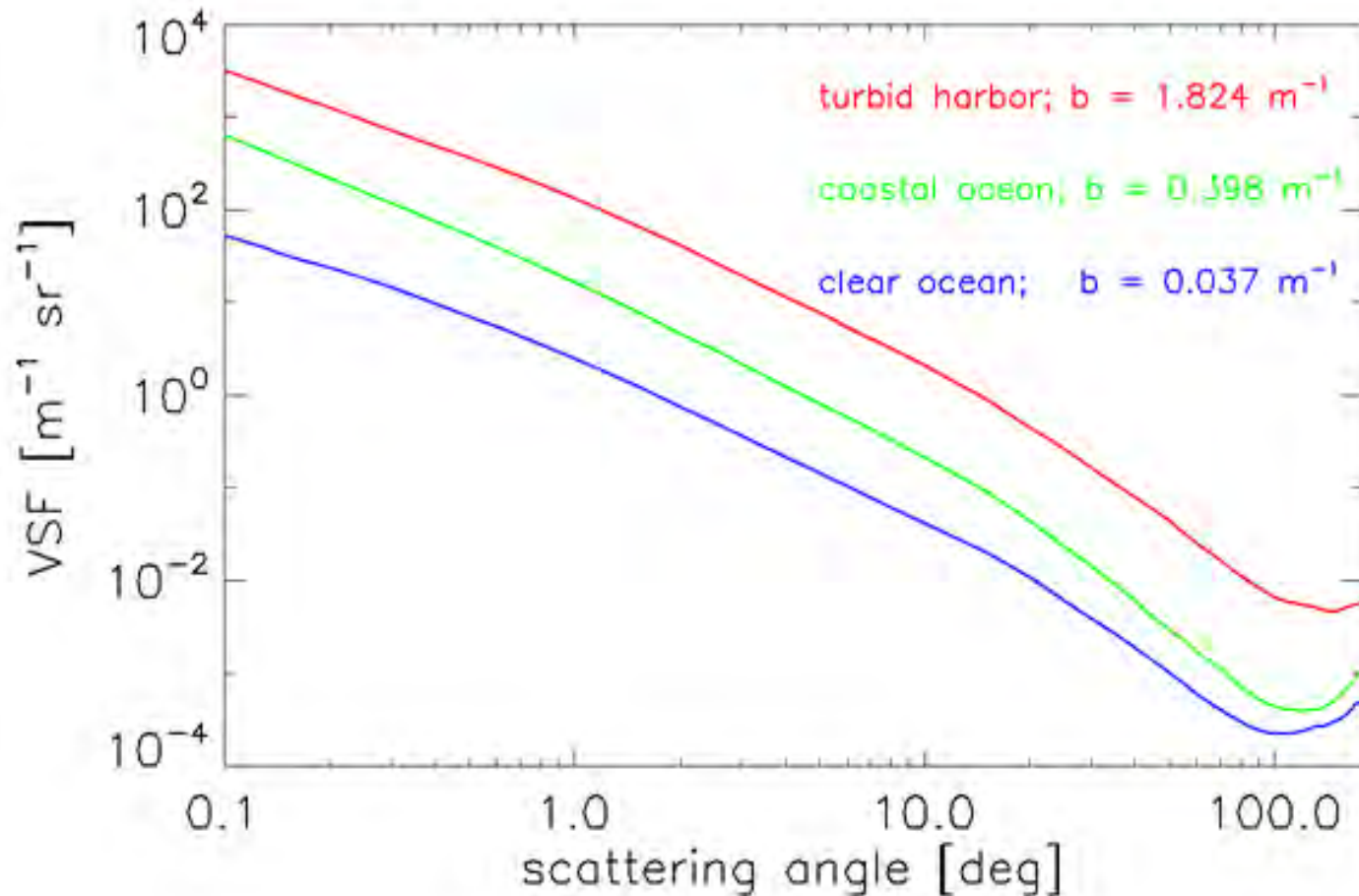
GUNNAR KULLENBERG*

(Received 5 February 1968)

This experimental investigation deals with the problem of the scatterance of light by very clear ocean water. The forward scatterance was measured close to a laser beam using a new measuring device. The forward particle scatterance was found to be virtually independent of wavelength, whereas the backward scatterance was dependent on the wavelength. The water investigated has a high degree of clearness compared with other areas. The ratio of scatterance at 45° to total scatterance over all angles was found to vary within narrow limits for different oceanic areas.



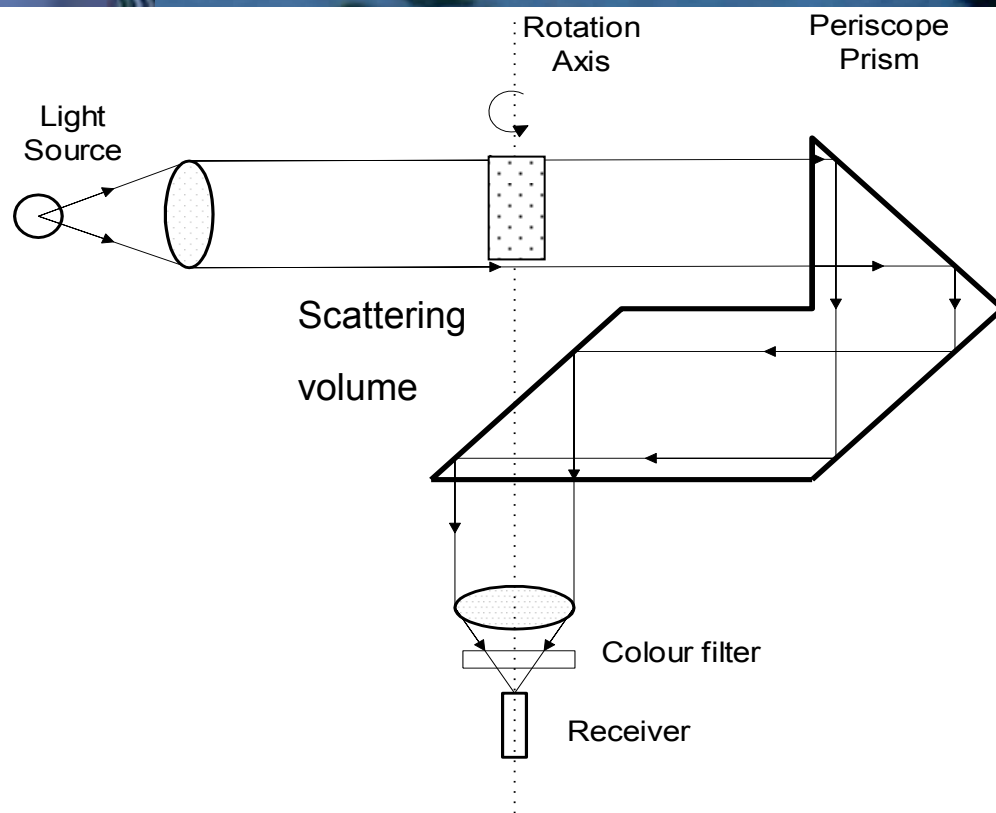
The (in)famous Petzold measurements (1972)

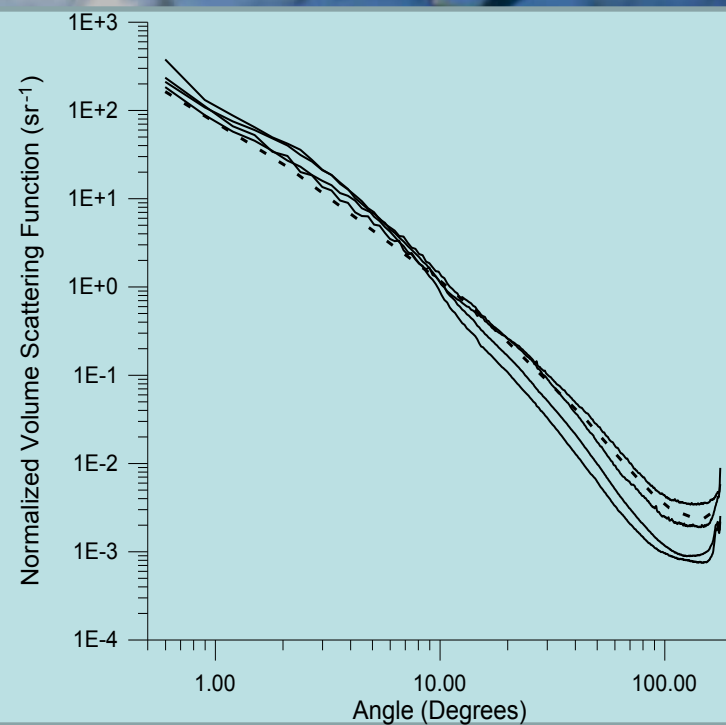
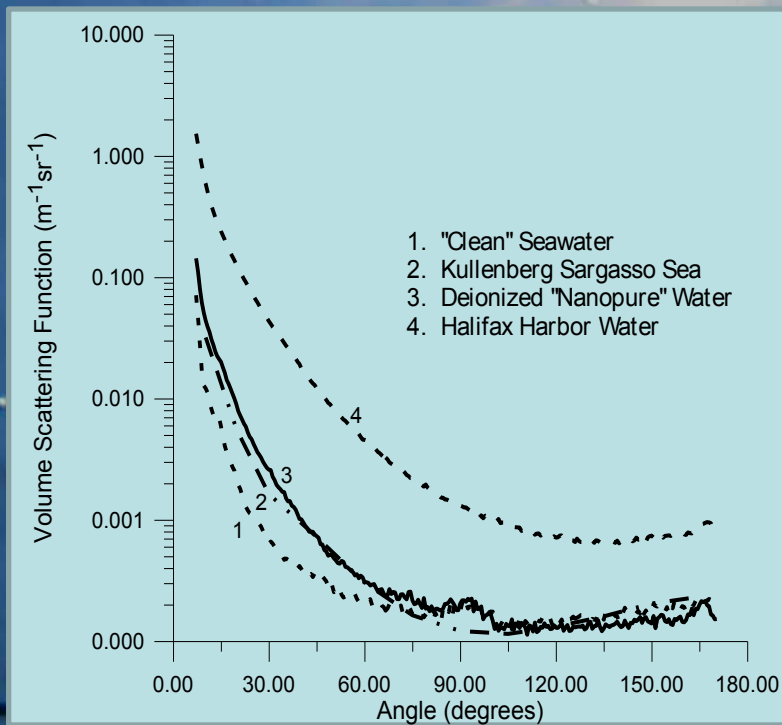


The “Ukrainian Instrument” MVSM

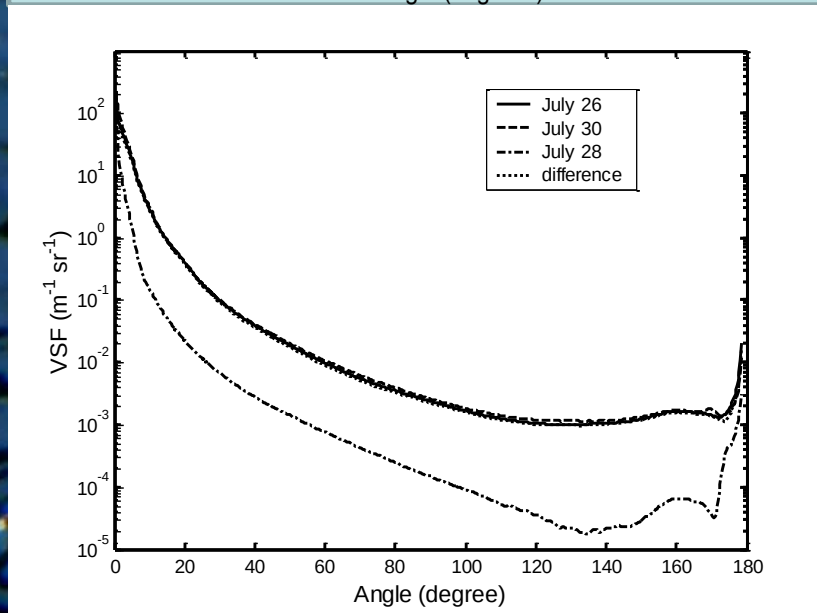


Lee, M., and M.R. Lewis. 2003. A new method for the measurement of the optical volume scattering function in the upper ocean. *J. Atmos. Oceanic Tech.* 20: 563-571



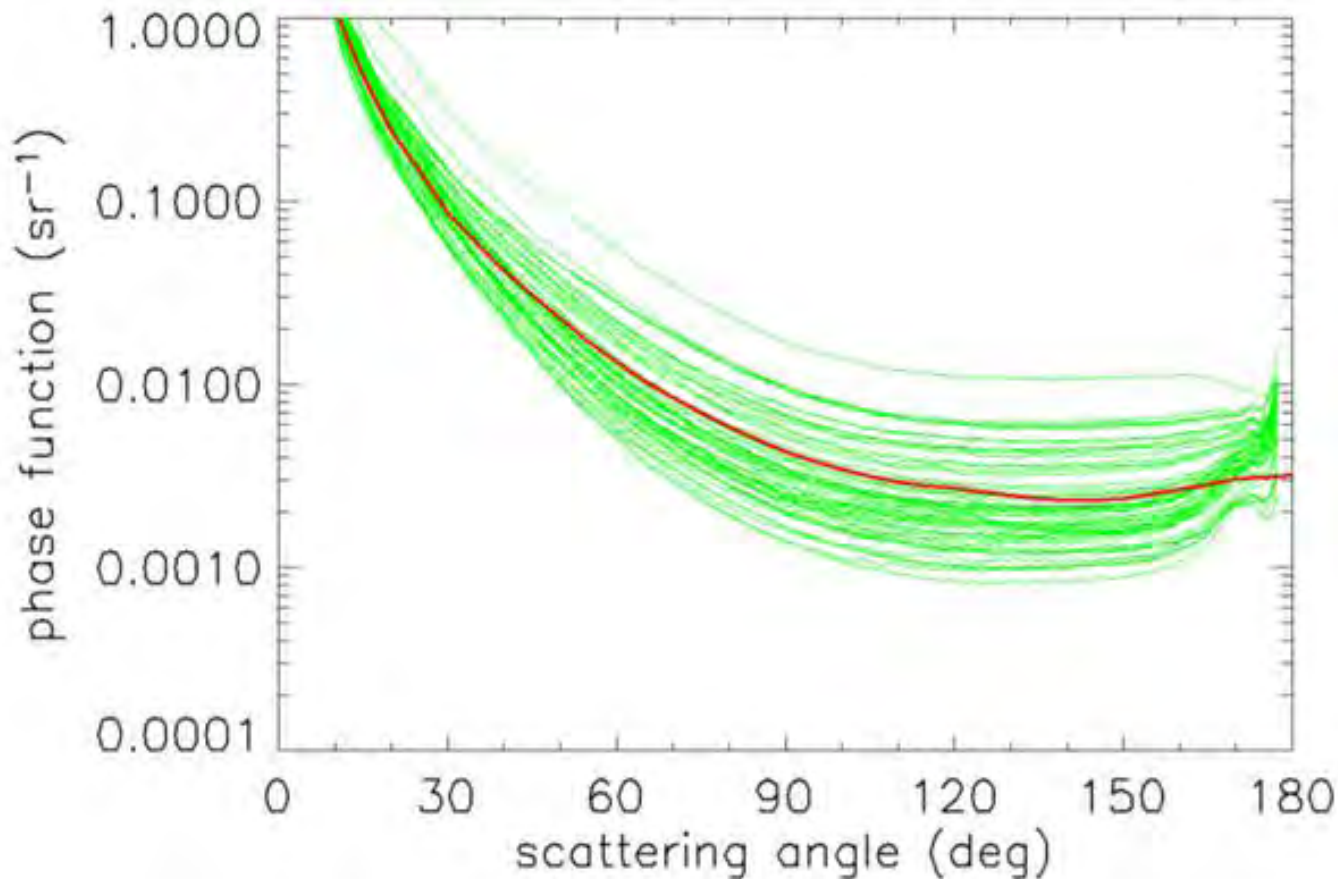


Lee and Lewis, 2003

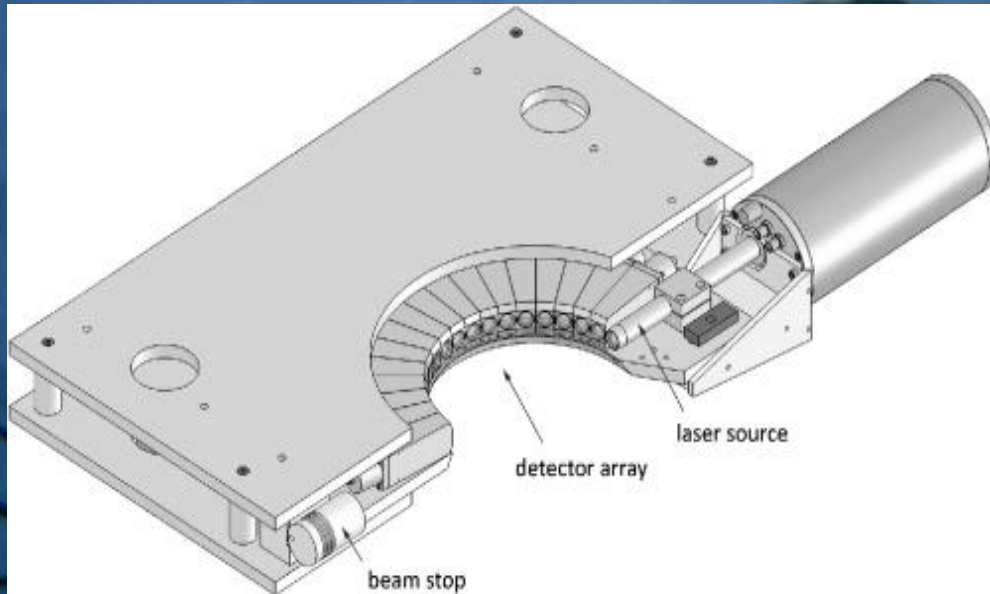


Zhang et al., 2006

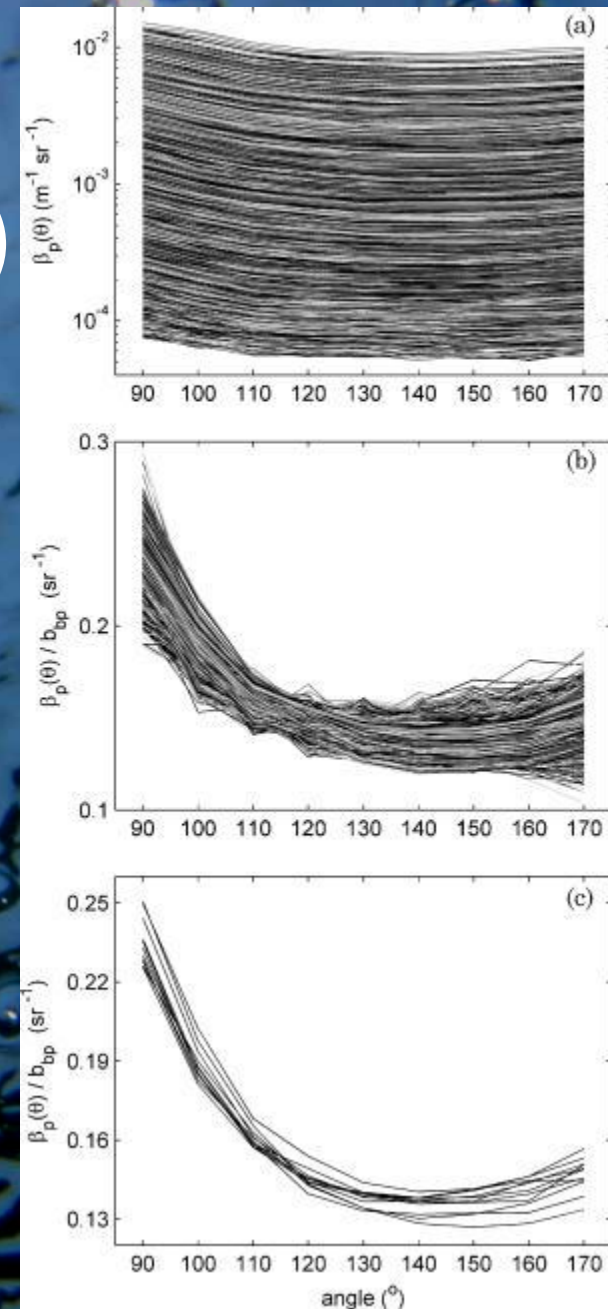
Wide range of variation in
coastal, open ocean waters.



Multi-Angle Scattering Optical Tool (MASCOT)



Mike Twardowski, WETLabs



A new one!

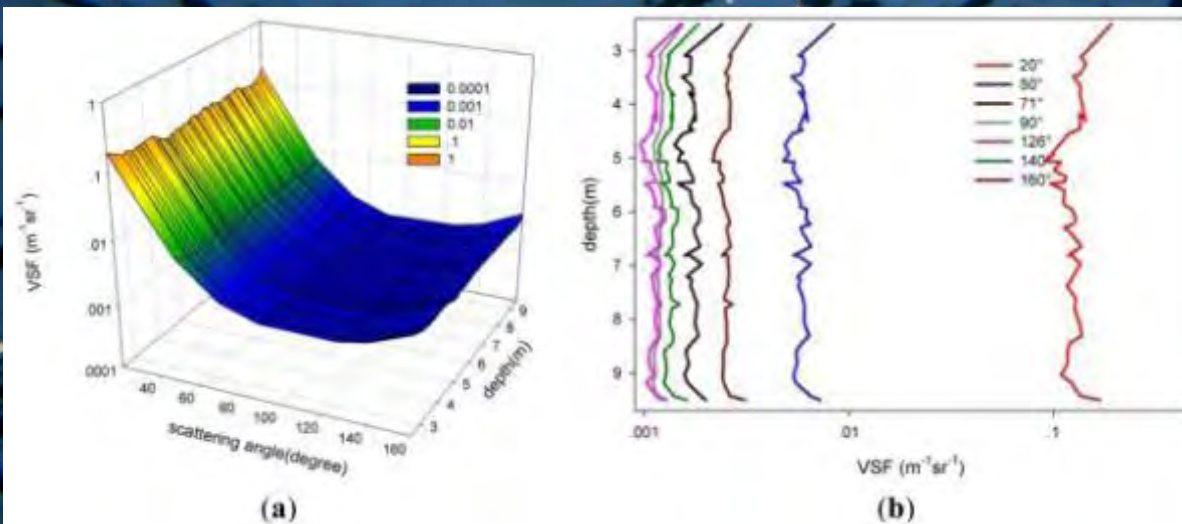
Published online 2012 April 10. doi: [10.3390/s120404514](https://doi.org/10.3390/s120404514)

PMCID: PMC3355425

An Instrument for *In Situ* Measuring the Volume Scattering Function of Water: Design, Calibration and Primary Experiments

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Forward angle scatter



New – forward +
wide angle + pol

LISST instruments are based on the small-angle scattering method that is also known as laser diffraction. Scattering from a laser beam is observed at multiple angles. Particle size distributions are estimated from scattering models.

Sequoia Instruments

SATLANTIC

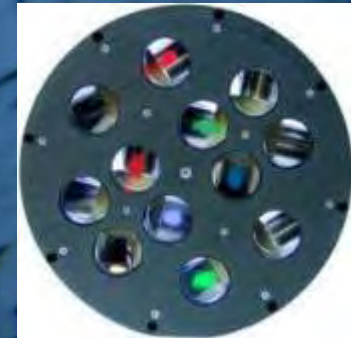
Fixed angles in the backward direction - HobiLabs.



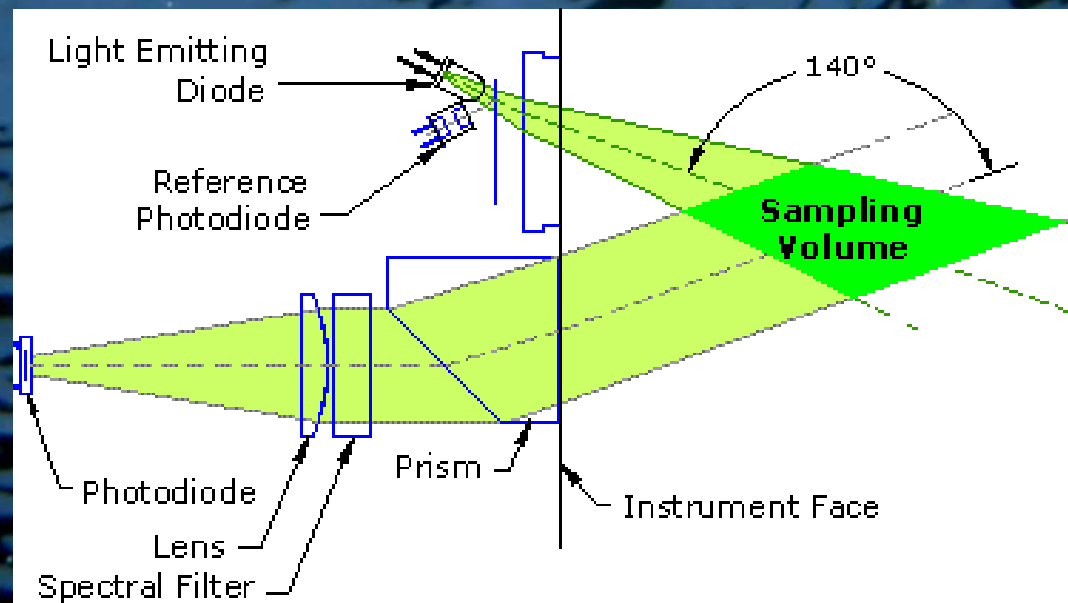
Hydroscat 2



Hydroscat 4



Hydroscat 6



Fixed angles in the backward direction - WetLabs.



BB-2F measures at 117 degrees at both 470 and 700 nm.



ECO VSF 3 measures the optical scattering at three distinct angles: 100, 125, and 150 degrees, and at wavelengths of 470, 530, and 660



BB-9 measures at 9 angles or 9 wavelengths or combinations

How to get backscatter coefficient?

$$b_b \equiv \int_{2\pi}^{4\pi} \beta(\Psi) d\Omega = 2\pi \int_{\pi/2}^{\pi} \beta(\theta) \sin \theta d\theta$$

Oishi (1990) showed from an analysis of measured and modeled VSF's that

$$G(\theta) = \frac{b_b}{\beta(\theta)}$$

changed little from 120 to 150 degrees, with the smallest variation at 120 degrees. Also see: Boss, E. and W.S. Pegau, Relationship of light scattering at an angle in the backward direction to the backscattering coefficient. Appl. Opt., 40, 5503-5507 (2001)

Closure – Bringing it all together

Inverse Problems (“given radiometric measurements of underwater or water-leaving light fields, determine the inherent optical properties of the water. This is very much an unsolved problem. Both conceptual and practical limits are encountered in inverse problems. Unfortunately, remote sensing is an inverse problem.”
Mobley, OceanOpticsWeb

Approach we took

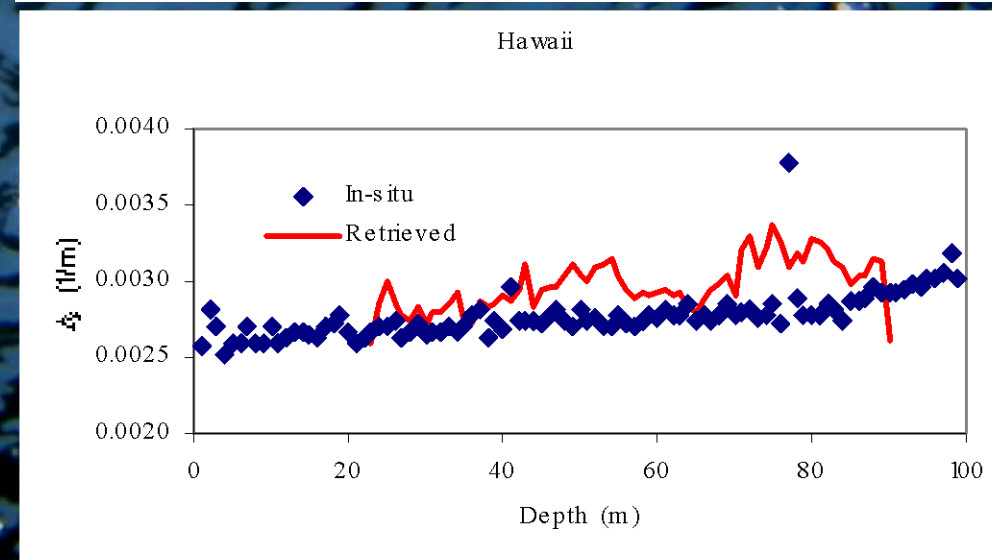
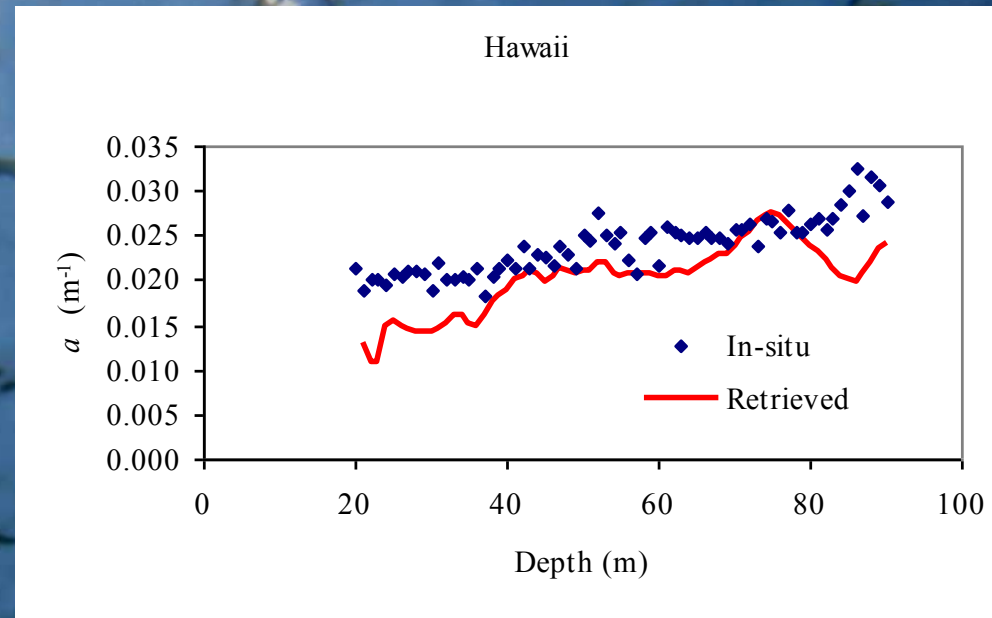
Spectra of particulate backscattering in natural waters.

Howard R. Gordon^{1,*}, Marlon R. Lewis^{2,3}, Scott D. McLean³, Michael S. Twardowski⁴, Scott A. Freeman⁴, Kenneth J. Voss¹, and G. Chris Boynton¹
Optics Express 17: 16192-16208, 2010.

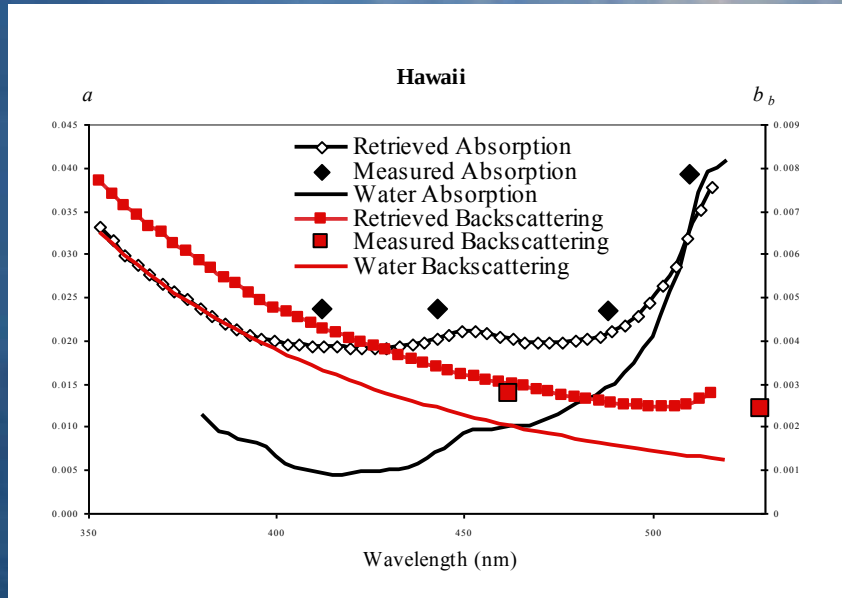
1. Measure, with great care, the vertical profile of hyperspectral downward irradiance, and upward radiance (HyperPro, Lewis and McLean).
2. Measure, with great care, the vertical profile of the absorption coefficient and the backscattering coefficient at several wavelengths (Twardowski and Freeman).
3. Without any tuning or adjustment, assimilate the irradiance and radiance into an advanced Monte Carlo inverse radiative transfer model to obtain high resolution spectra of the absorption coefficient (a) and the backscattering coefficient (b_b) of the water and its constituents. (Gordon, Boynton, Voss).
4. Compare derived IOP's with direct measurements (all).

Results (depth profile)

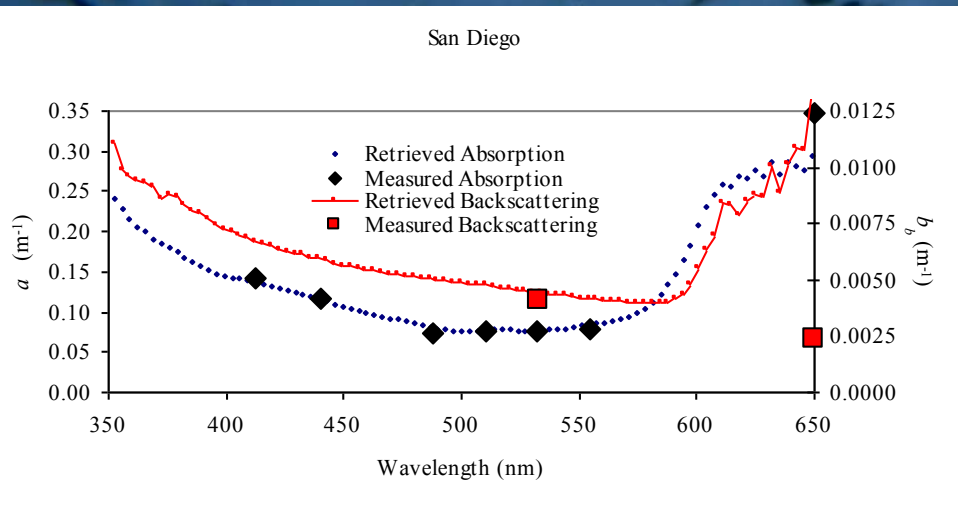
Comparison of retrieved and *in-situ* vertical profiles of absorption (top at 443 nm) and backscattering (bottom at 462 nm) at the station off Lanai, Hawaii.



Results (hyperspectral)



Wow!! “Closure is in many ways is the Holy Grail of hydrologic optics – always sought, never achieved.”
Mobley, 1994



Conclusions, part 1

In situ measurement of the radiative quantities and optical properties of the ocean is really hard to do well.

But through concerted efforts, the community has converged on a common set of standards and protocols for calibration, characterization and field deployments which have significantly advanced the field over the last 15 years.

At the same time, advanced numerical approaches to the solution (and inversion) of the radiative transfer equation have been well developed as well.

What is left to do?

Some thoughts

We still do not know what is responsible for backscattering light in the ocean.

Issues related to variation in the volume scattering function – and its effect on the full angular distribution of the radiance field are open.

In particular, the polarization variation (and its connection with biology) is largely unknown.

The optics of ice-covered seas are complex, and poorly understood.

Much work has gone into demonstrating the utility of optical observations in the prediction of ocean biogeochemical variability – we need to “operationalize” this (smaller, faster, cheaper...power of $n^{-1/2}$) (next).

And don't forget....Life consists of trade-offs!

Part II: Statement of the Problem:

We would like to predict – in a *hindcast* (what did things look like before?), *nowcast* (what do things look like now?) and *forecast* (what will things look like in the future) sense – the three-dimensional fields of ocean biogeochemical properties and processes.

This includes both short (e.g. ocean weather) and long (climate) scales, and over a range of spatial scales. An example of the former might be harmful algal bloom prediction; and an example of the latter would be long-term secular changes in surface chlorophyll.

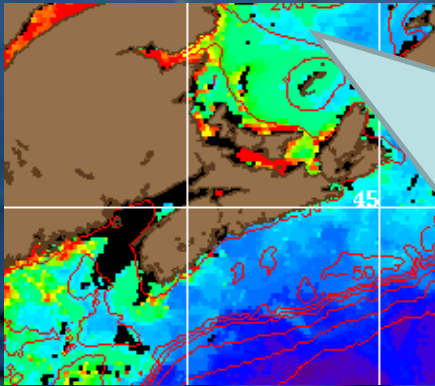
And we would like to do this with significant “skill”, that is, we wish to explain a significant fraction of the observed variance.

What do we need to do this?

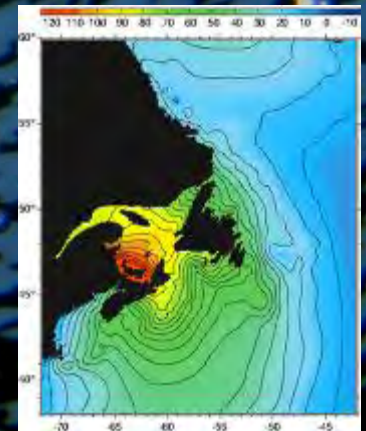
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Marine Environmental Prediction

Observations



Understanding

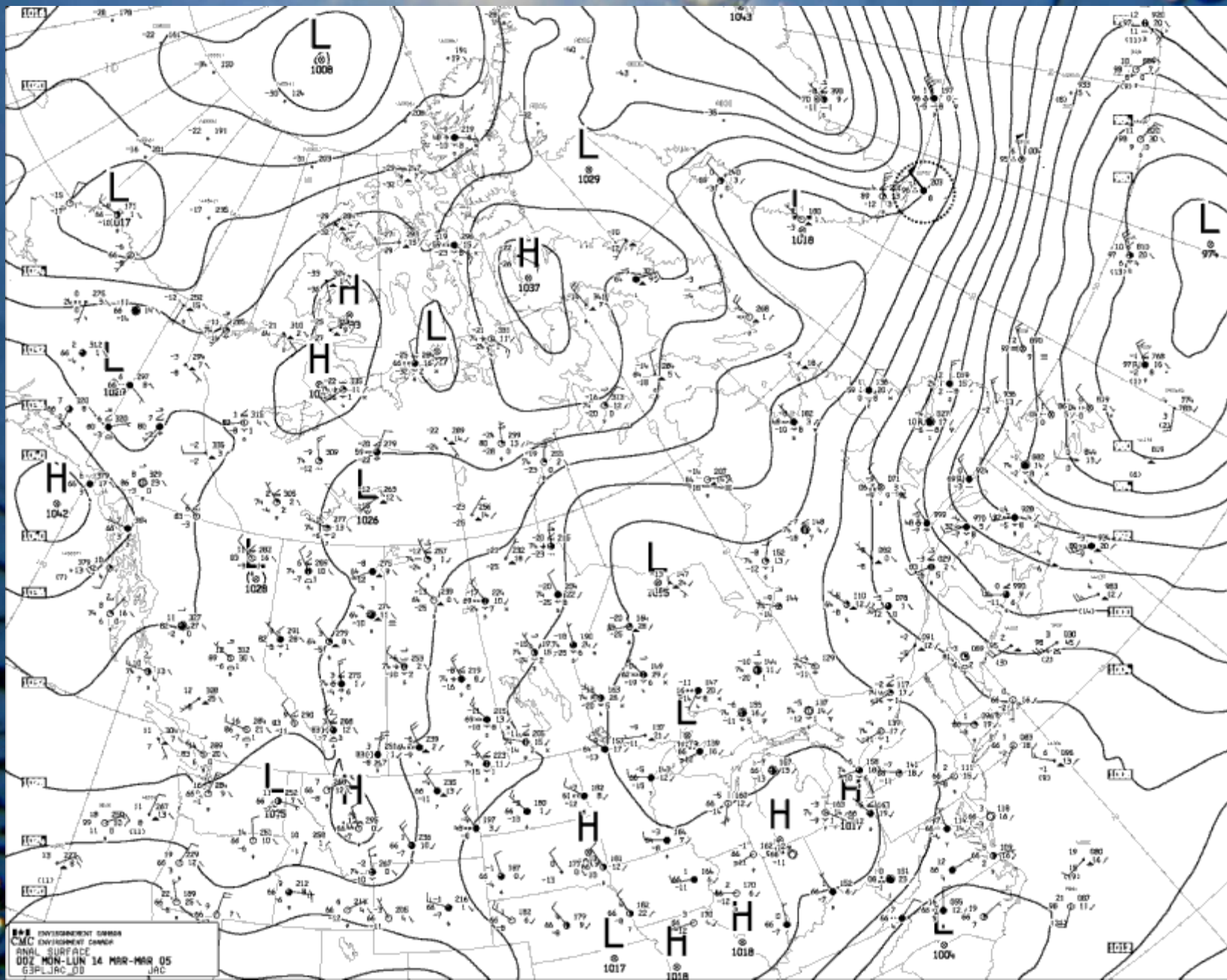


Prediction

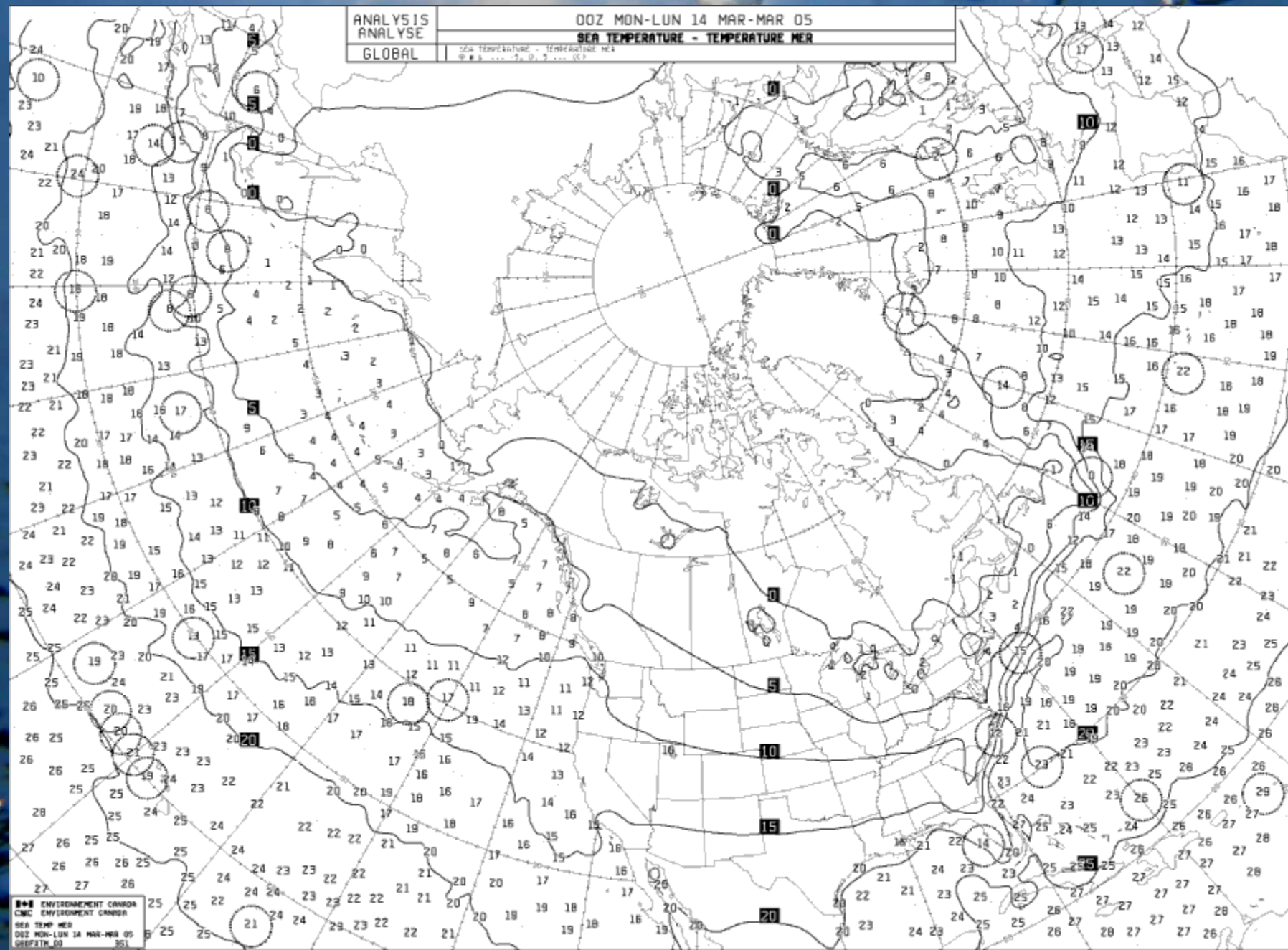
Data assimilation

- The goal is to produce an atmospheric or ocean state as close as possible to reality and at the same time, dynamically consistent, taking into account all the available information: observed data, model, physical constraints, climatology
- The tools: any type of objective (as opposed to subjective) data analysis: Optimal Interpolation, three-dimensional and/or four-dimensional variational assimilation (3D-VAR/4D-VAR), Kalman filter.
- The output is a set of meteorological or oceanographic fields on the model 's geometry (e.g. a geometrically regular grid or spectral coefficients, etc.) – the Analysis.
- Important aspect: cycling i.e. process of permanent assimilation of data

Surface Pressure



Sea Surface Temperature



Sometimes....data is just not enough...nor are models sufficient.

The basic objective information that can be used to produce the analysis is a collection of observed values provided by observations of the true state.

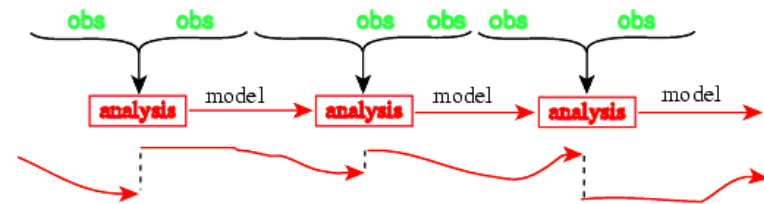
If the model state is overdetermined by the observations, then the analysis reduces to an interpolation problem. In most cases the analysis problem is under-determined because data is sparse and only indirectly related to the model variables.

In order to make it a well-posed problem it is necessary to rely on some *background* information in the form of an a priori estimate of the model state. Physical constraints on the analysis problem can also help.

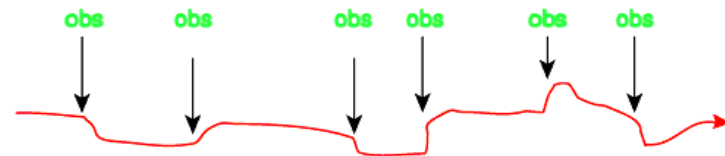
Data Assimilation

Data assimilation : analysis technique in which the observed information is accumulated into the model state by taking advantage of consistency constraints with laws of time evolution and physical properties.

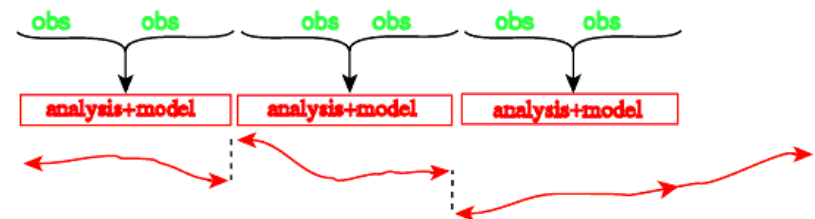
sequential, intermittent assimilation:



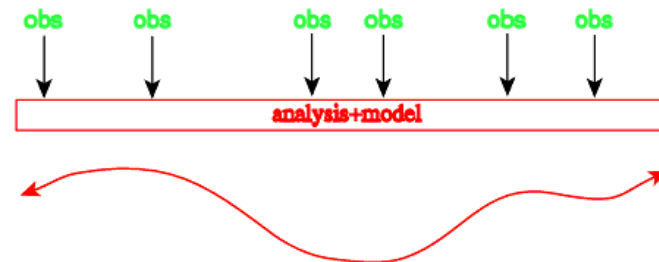
sequential, continuous assimilation:



non-sequential, intermittent assimilation:

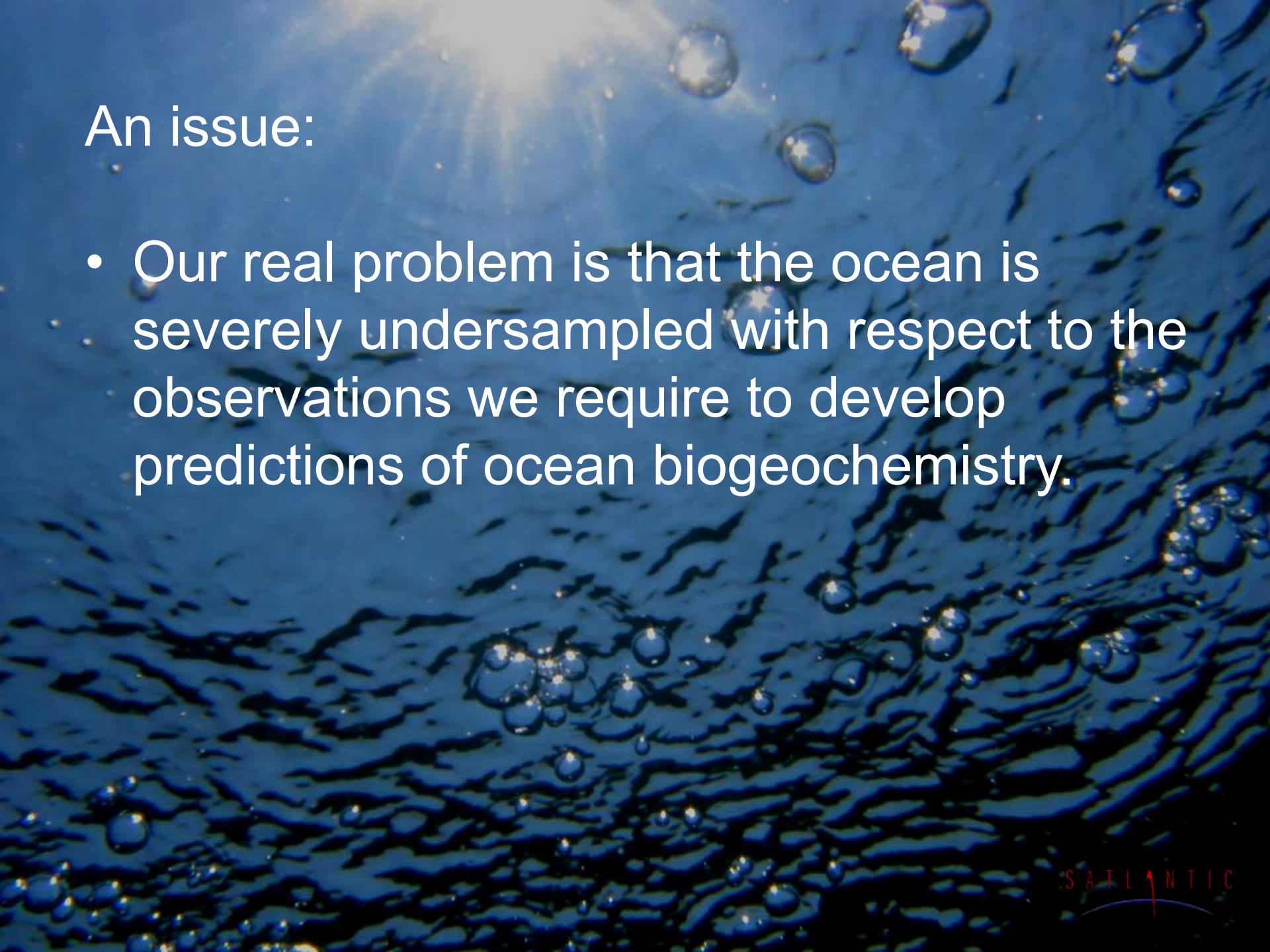


non-sequential, continuous assimilation:



The Cressman approach is a (still used) data assimilation scheme used to merge models and data. Note that more weight can be given to the model (or climatology) by setting the weights less than one for $i=j$ – this is termed the “successive correction method” (SCM). Essentially, this is then a weighted average between the background and the observation. It “works” pretty well.



The background of the slide is a close-up photograph of water. It features numerous small, clear bubbles of varying sizes, some of which are in sharp focus. A bright light source, likely the sun, is positioned at the top center, creating a strong lens flare and illuminating the water's surface. The overall color palette is dominated by deep blues and greens, with highlights from the sunlight.

An issue:

- Our real problem is that the ocean is severely undersampled with respect to the observations we require to develop predictions of ocean biogeochemistry.



But what does this have to do
with optical observations?

We need many more of them.

Observational Approaches

- Observations of relevant biogeochemical properties, at relevant space and time scales, are necessary for prediction.
- Ships are too slow, and cost too much.
- Satellites provide a surface view; however, the dynamics that involve nutrient injection most assuredly involve vertical transport in some fashion.
- Fixed moorings capture the vertical and time domain, but not the synoptic, unless in arrays (\$\$...€ €)
- Models are useful, but require observations for initialization and assimilation.

Autonomous platforms provide the third dimension, and can be deployed for long duration, at reasonable cost. But, few appropriate sensors are available.

Sensors on Autonomous / Lagrangian Platforms

Optical:

active and passive optical sensors
(radiometers, fluorometers, beam c,
backscattering, bioluminescence)

Chemical:

oxygen
nutrients on larger platforms

Other:

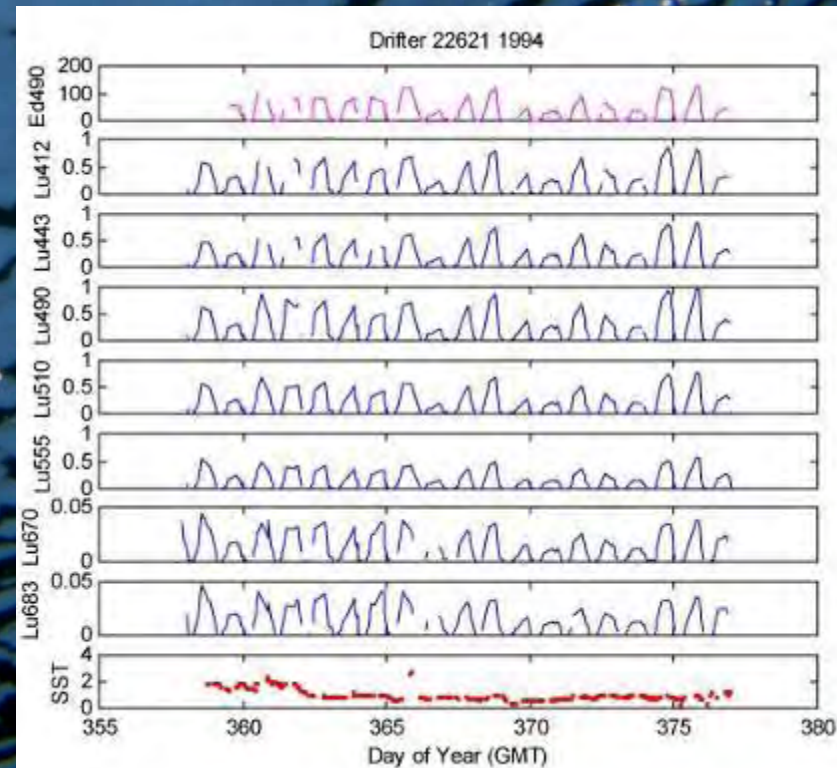
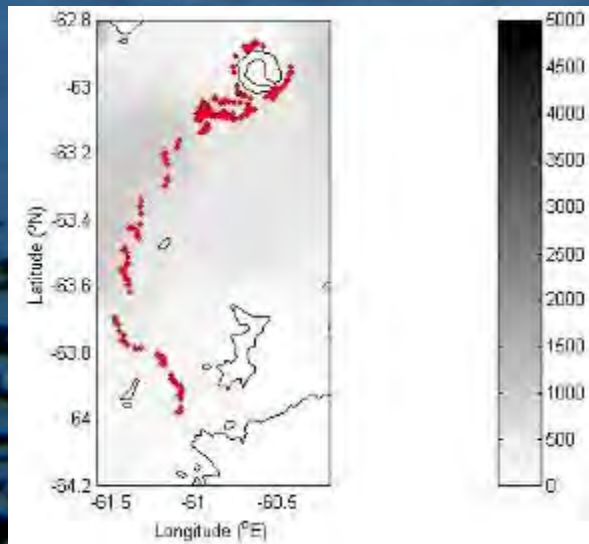
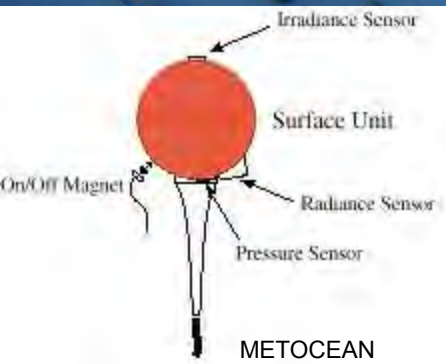
acoustics, turbulence, etc.

Credit: M.J. Perry

1st Bio-optical autonomous drifter...

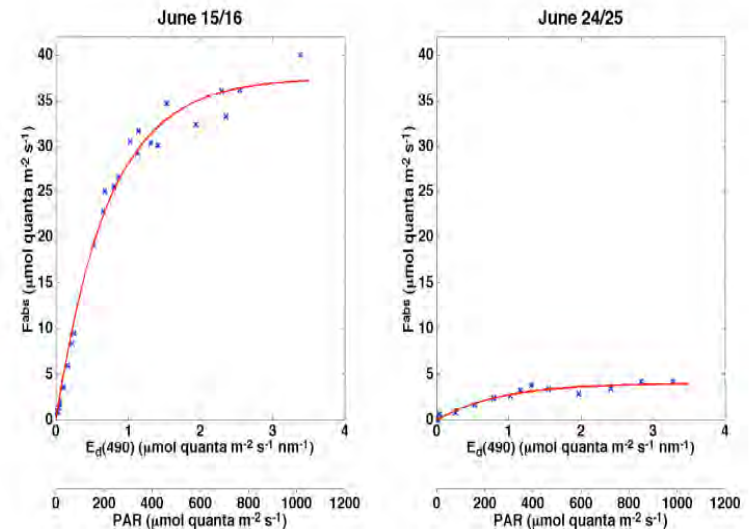
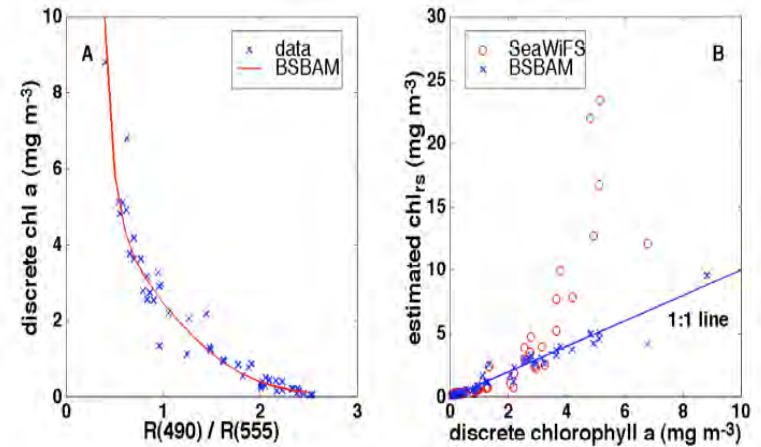
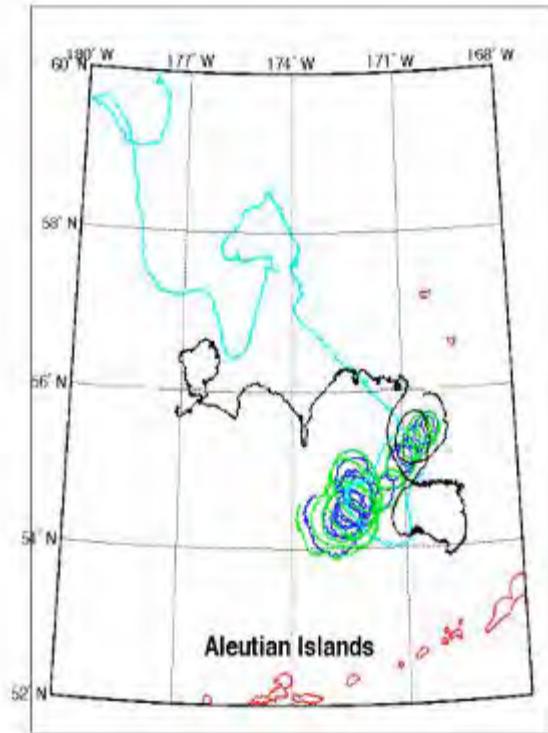


- First deployment, Equatorial Pacific, 1994, dropped from aircraft (Satlantic + MetOcean).
- Lagrangian, surface drifter, ARGOS comms.
- Upwelling spectral radiance (“ocean color”), and downwelling irradiance at 490 nm.
- 100’s deployed now.

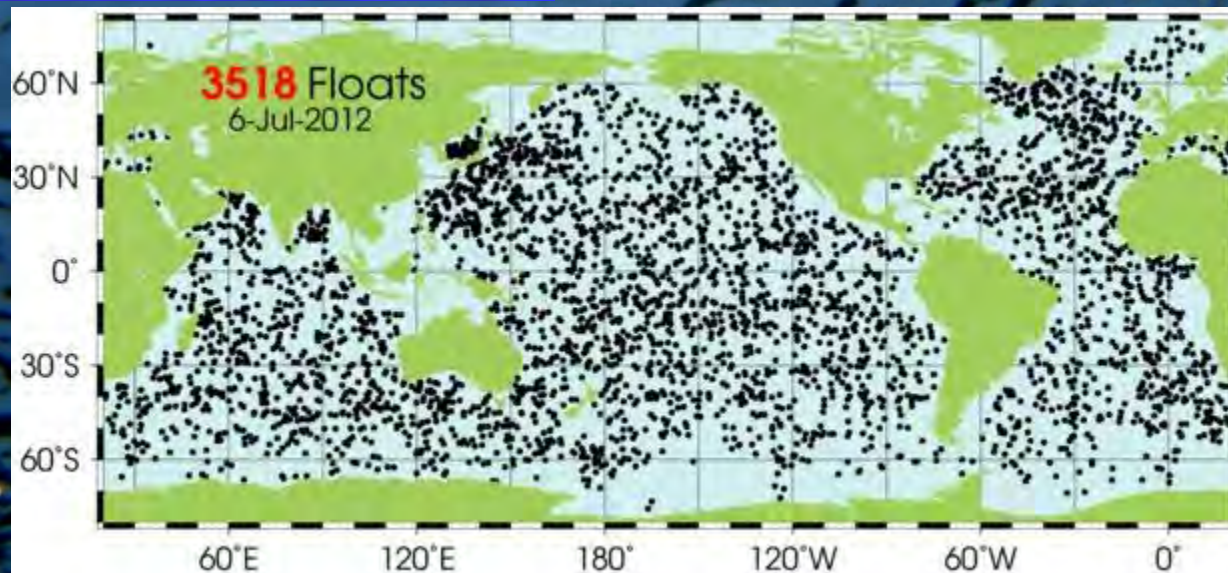
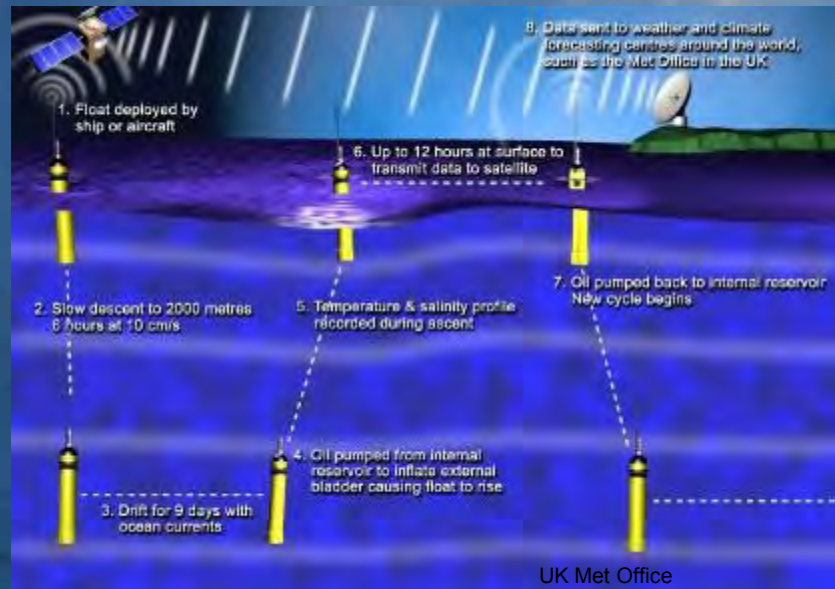


TEMPORAL VARIABILITY IN THE RELATIONSHIP BETWEEN SUNINDUCED FLUORESCENCE AND INCIDENT IRRADIANCE IN THE BERING SEA: AN EFFECT OF NUTRIENT AVAILABILITY?

Christina Schallenberg, Marlon R. Lewis, Dan E. Kelley and John J. Cullen. JGR, 2007

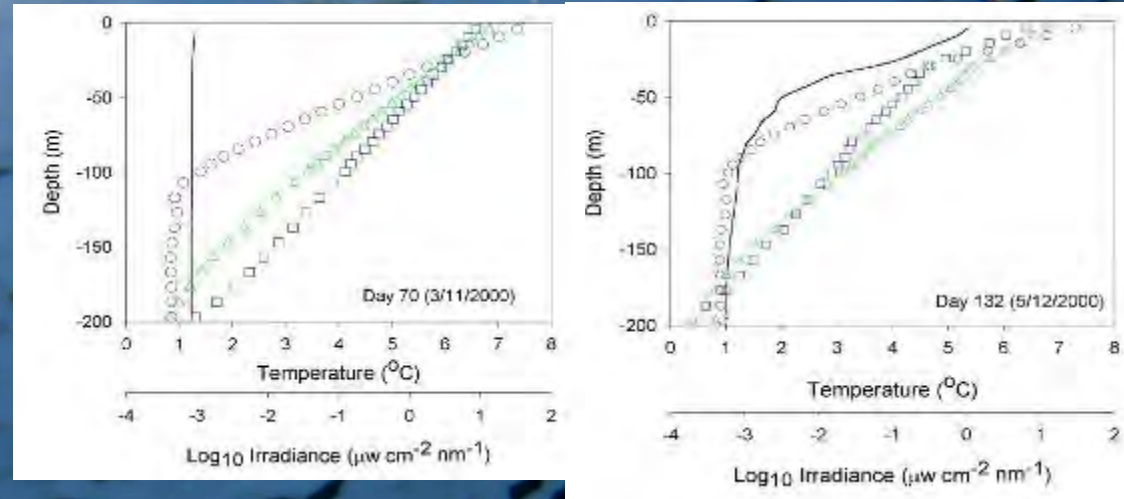


But....such surface drifters do not resolve vertical dimension.
Profiling floats provide this capability.

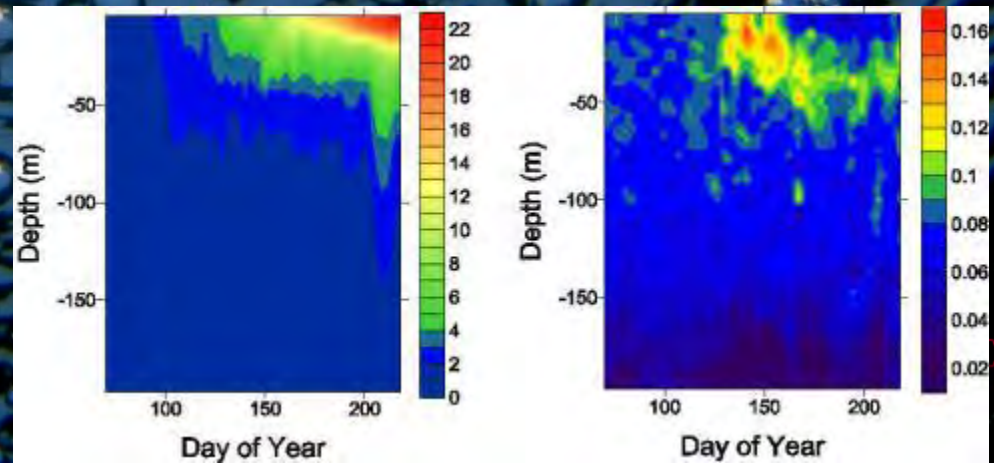


K-solo, Mitchell et al. 2001

Vertical gradient in irradiance (3 wavelengths) used to estimate diffuse attenuation coefficient $\sim$ chlorophyll.

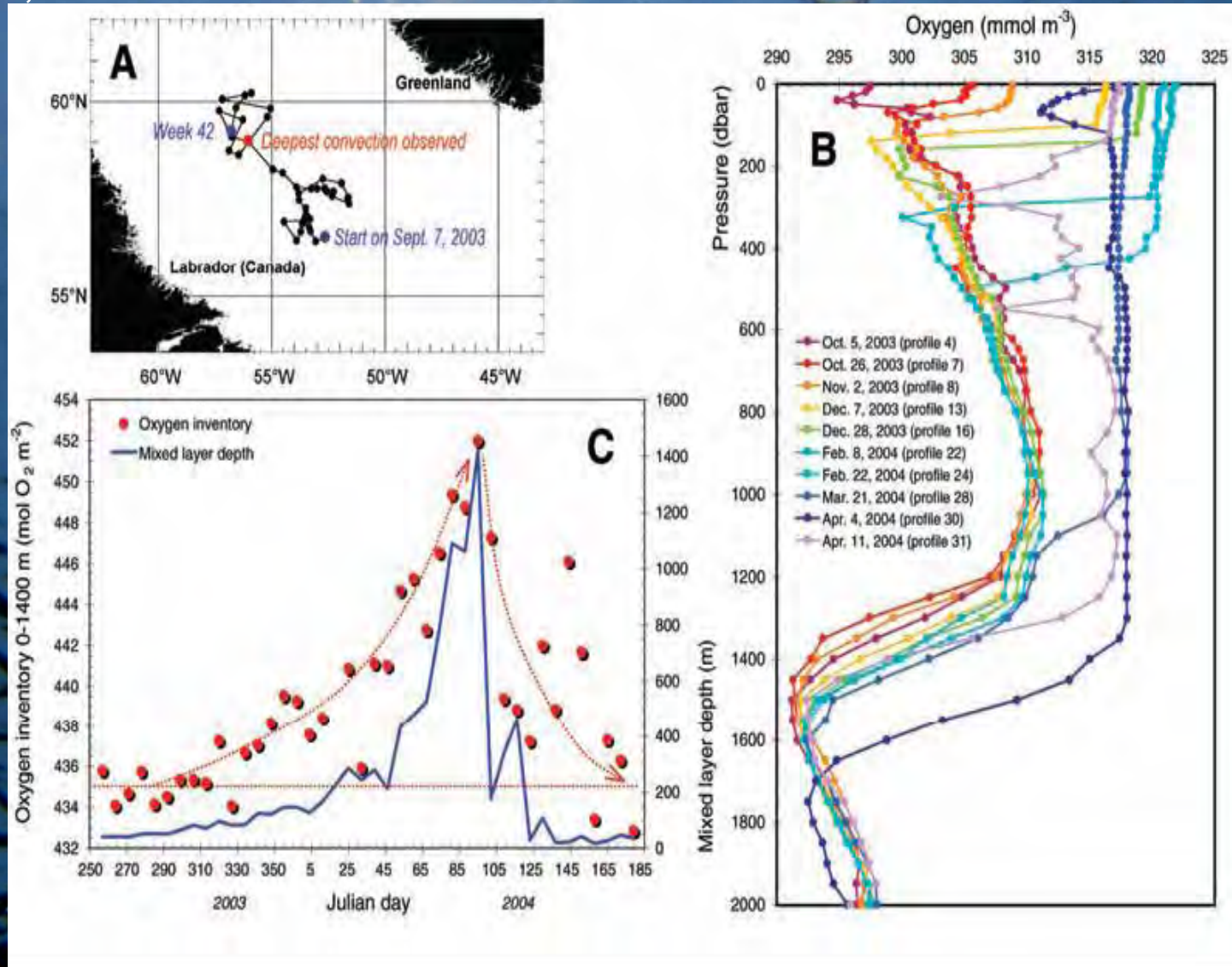


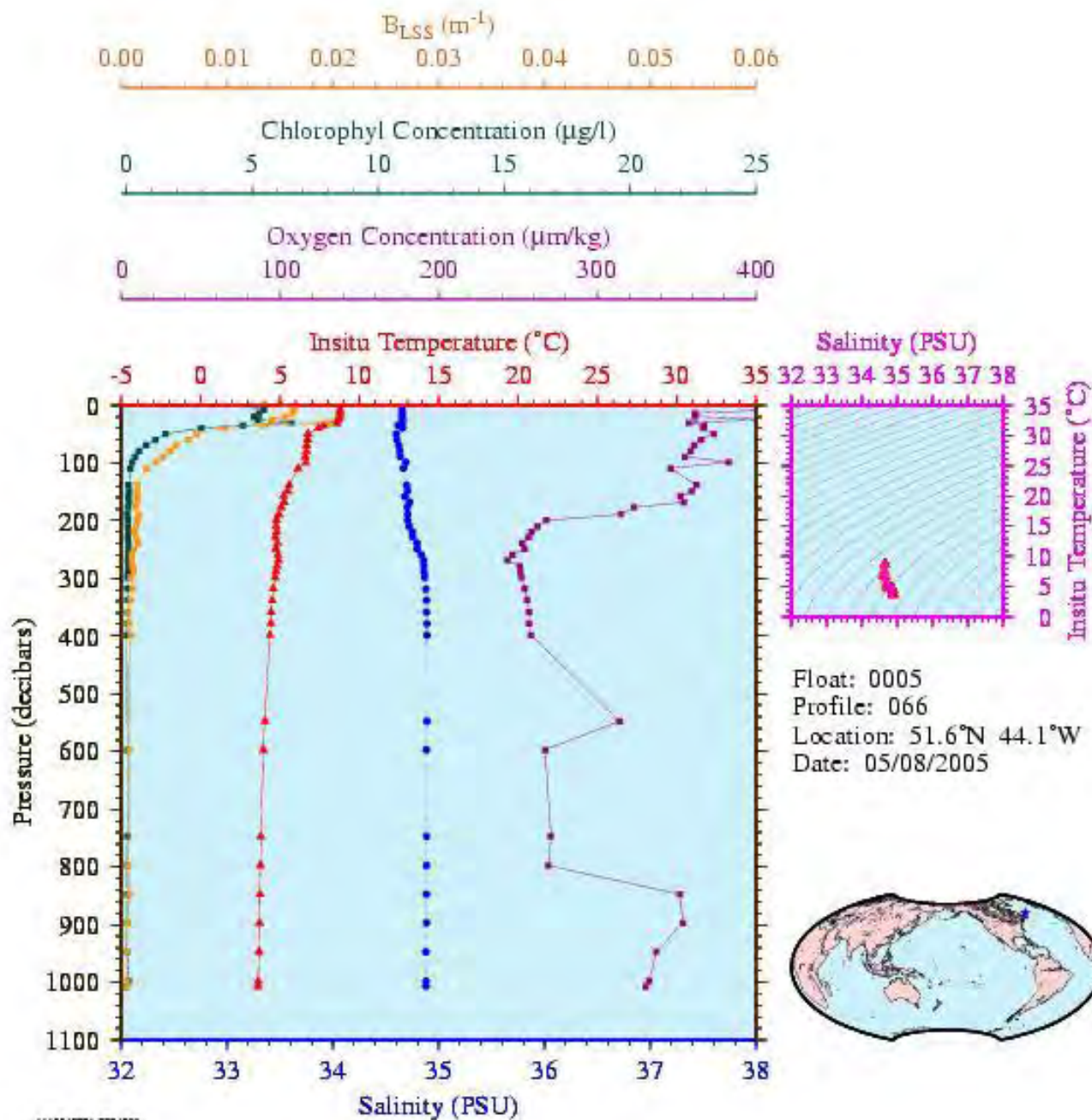
Vertical profiles of temperature (—) and irradiance at three wavelengths (380 nm - ○; 490 nm - □; 555 nm - △) transmitted by KSOLO for A. March 11 and B. May 12, 2000.



The Ocean Takes a Deep Breath

Arne Körtzinger, Jens Schimanski, Uwe Send, Douglas Wallace
Science, 2004





Emmanuel Boss
SANTLANTIC

PRO-BIO (Satlantic + MARTEC + IFREMER + CNRS)

- 3-channel irradiance, beam-c, for chlorophyll, carbon, irradiance distribution.
- Requires Iridium satcomms solution.

+ radiomètre

$Ed(\lambda)$



+ Transmissiomètre

$c(660)$



PROVOR

Copyright, SHOM

Float Development w/LOV



SUNA Nitrate Sensor



Cal-Val Sensor Suite

Float Development w/U Maine



BIOGEOCHEMICAL SENSING SYSTEMS FOR AUTONOMOUS PROFILING FLOATS

Keith Brown¹, Diego Sorrentino², Marion Lewis², Andrew Barnard³, John Koegler³, Casey Moore³,
Mathew DeDonato¹, Emmanuel Boss², Greg Gerbi³, Hervé Claustre²



ABSTRACT

A bio-optical sensor system for profiling floats to be used for ocean color satellite calibration and validation and ocean carbon studies was developed. The challenge of realizing the biogeochemical float is in augmenting the proven Argo float with an expanded sensor system that is robust, efficient, and economical so as to achieve satisfactory mission duration. SATLANTIC and WET Labs jointly developed the sensor system and collaborated with Teledyne Webb Research to integrate it with the APEX float. The sensor system includes an integrating hub that manages up to six additional instruments. The hub controls power switching, implements sampling strategies, and logs data minimizing energy consumption and data size thus maximizing float mission duration. The modular sensor system design allows for building user specified variants. The initial system provided upwelling and downwelling radiometry at four wavelengths, scattering at three wavelengths, beam attenuation, chlorophyll, and CDOM measurements to complement core float sensors for pressure, temperature, salinity and dissolved oxygen. The system architecture and performance are described with emphasis on data quality and the impact on float energy budget and thus mission duration. Initial deployment results are presented.



Figure 1. Sea Trial in Bedford Basin, Nova Scotia, 10 February 2011
Greg Gerbi, Emmanuel Boss, Diego Sorrentino, Keith Brown, Matt DeDonato

DESIGN GOALS

Sensor Performance. Proven instruments are adapted to operate in Argo service conditions (depth, extended duration, no maintenance) without compromise of fundamental performance qualities of accuracy, sensitivity and stability, particularly for the calibration and validation mission.

Robust. The Biogeochemical Profiler consisting of the core APEX float with CTD and Oxygen Optode combined with the bio-optical suite is designed with the goal of being as reliable as a traditional Argo CTD float.

Operational. The system is designed to withstand deployment forces, retain satisfactory float dynamics despite the addition of external sensors, and provide conditions for bio-optical sensor operation such as field of view requirements.

Modularity. The bio-optical sensor system is a sustained product, not a one-of-a-kind research project. The flexible, modular design minimizes engineering to tailor the system to differing requirements.

Economical. The integrated system must be practical to manufacture, delivering the enhanced qualities of the individual sensors required for this application, without making assembly, test and delivery economically impractical.

Incremental Development. The bio-optical sensor system builds on the experience of previous developments and adapts to the current APEX float. In particular aspects of its mechanical, electrical and control configuration. Adaptations of the float are required as well, including selection of hull and battery options, ballast and trim management, development of sensor mounting arrangements, and extensive software development, see Ref 2.

ENERGY CONSUMPTION

Energy budget modelling will improve with deployment experience. The estimates shown below use average sensor current draws based on measurements of a small sample of sensors at a constant voltage. The profile consists of five segments described below.

Sample Profile	
1000 m – 500 m, 25 m intervals	
CTD, Oxygen, 1 sample	
OP, 1 sample	
500 m – 50 m, 10 m intervals	
CTD, Oxygen, 1 sample	
OP, Radiometry, 5 samples	
50 m – surface, 2 m intervals	
CTD, Oxygen, 1 sample	
OP, 1 sample per event	
50 m – surface, 4.5 cm (1 s) intervals	
Radiometry 1 sample	
Surface, Sample for 5 minutes	
Oxygen 1 sample every 20 seconds, 15 samples	
OP, Radiometry, 1 sample per second, 300 samples	

Sample Profile Energy Summary	
Data logged	107 KB
Buoyancy engine energy	8.86 KJ
OP, 1 sample	2.07 KJ
Control energy	4.24 KJ
Data telemetry energy	1.81 KJ
OP, Radiometry, 5 samples	16.79 KJ
Expected number of profiles	180
Based on initial reserve	3032 KJ

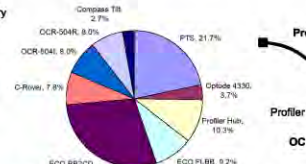


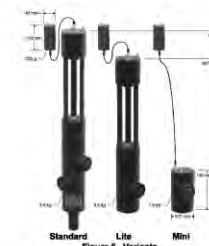
Figure 3. Instrument Energy / Total Data Collection Energy



Figure 4. Bio-optical Sensor System

Table 1. Bio-optical Sensor System Variants

Bio-Optical Sensor System	Std.	Lite	Mini	
COCOM	•	•	•	ECO FLBB
Backscattering B_{λ}	412 nm	•	•	ECO FLBB
Chlorophyll a	440 nm	•	•	ECO FLBB
Beam Attenuation, c	700 nm	•	•	ECO FLBB
Downwelling Irradiance, E_d	555 nm	•	•	OCR ICSW
Upwelling Radiance, L_u	412 nm	•	•	OCR ICSW
PAR	443 nm	•	•	OCR ICSW
Heading, Pitch, Roll	490 nm	•	•	OCR ICSW
	555 nm	•	•	OCR ICSW



RESULTS

See Biogeochemical Profiler data from past and current deployments at the University of Maine, School of Marine Sciences
<http://mrlab.umesci.maine.edu/research/biofloats/index.html>

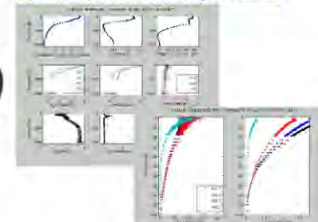


Table 2. BOBS Deployments

SN	Variant	Float	Deployments	Deployed	Recovered	Profiles	Status
1	Std	7054	BOUSOLE	13-Jul-11	17-Sep-11	29	Test deployment complete
2	Std	5293	BOUSOLE	13-Jul-11	17-Sep-11	29	Test deployment complete
9	Std	7688	MOBY	17-Dec-11		56	Test deployment complete - shipping damage - sensor damaged during deployment
10	Std	7708	MOBY	17-Dec-11		45	Operational
12	Std	MOBY	7-Apr-12				
13	Std	MOBY	7-Apr-12				

REFERENCES

See also:

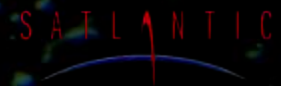
- Gerbi, G. E. Boss, D. Antoine, A. Barnard, K. Brown, M. DeDonato, B. Woodward. Measurements of Solar Radiation from an Autonomous Profiling Float – Opportunities and Results for Validation and Calibration Activities. Session 044 Friday 11:45
- DeDonato, M. B. Wallace, H.E. Fargher. Scheduling Sensors for Biogeochemical Profiling Floats. Poster A0115 Session 041 Wednesday 16:00

ACKNOWLEDGEMENTS

This material is based on work supported by NASA under award number NNX08AP51G through the National Oceanographic Partnership Program.

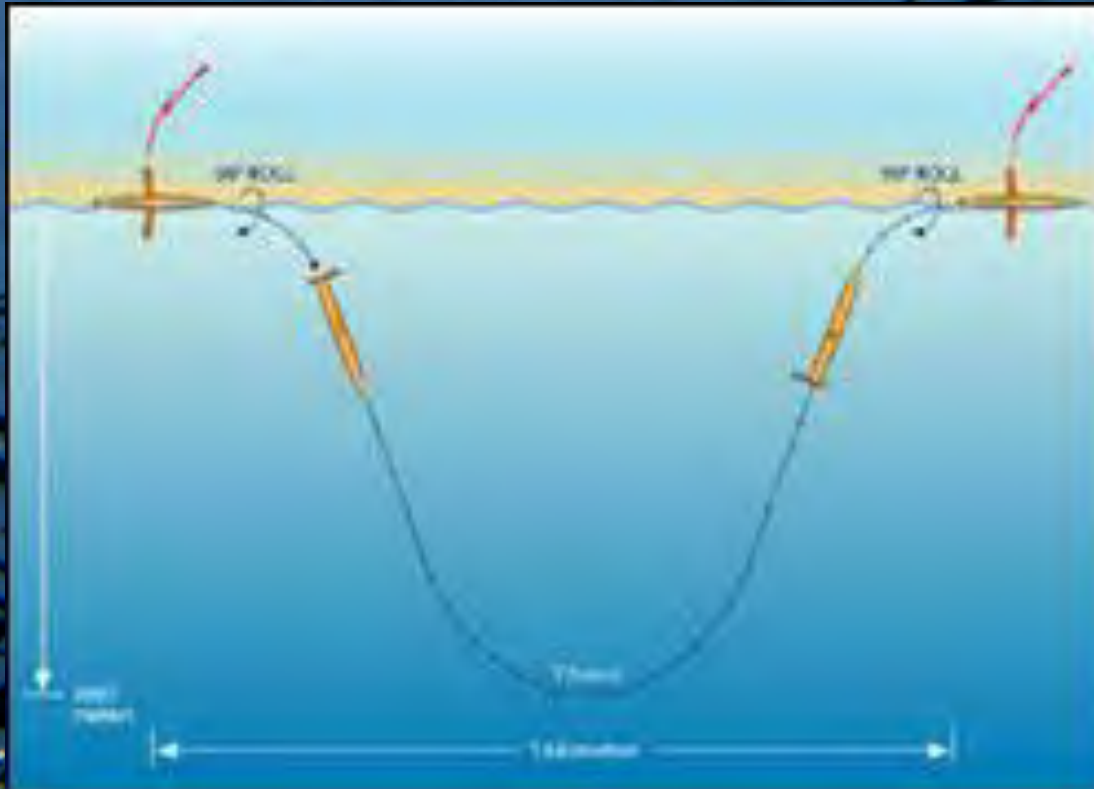
We acknowledge the contributions of colleagues at NASA, CLS America, University of Maine, Teledyne Webb Research, WET Labs, and SATLANTIC.

We also acknowledge the Laboratoire d'Océanographie de Villefranche and MOBY Team from Moss Landing Marine Labs who assisted with deployments.



But....we still need the horizontal spatial dimension...

- Gliders couple the buoyancy regulation of floats with aerodynamics to allow platforms to “fly” horizontally through the ocean.
- Conceived by Henry Stommel based on Joshua Slocum’s (from Nova Scotia!) first solo voyage around the world on sailing ship Spray.



- Currently several variants:

Slocum (Webb Research)



Spray (SIO)



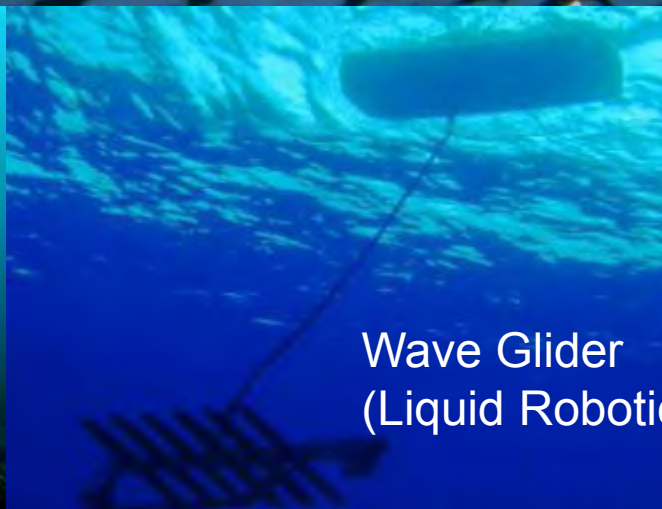
•SeaGlider (iRobot)



Sea-Explorer
(ACSA)



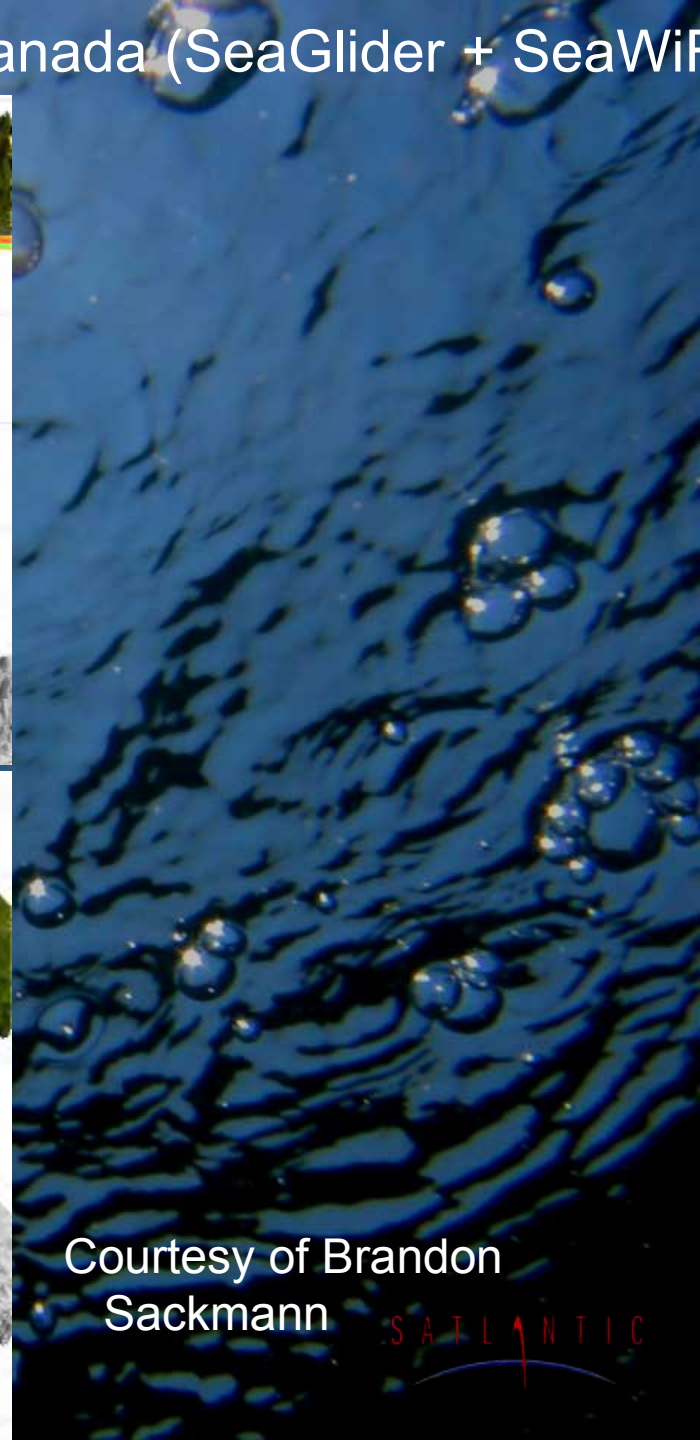
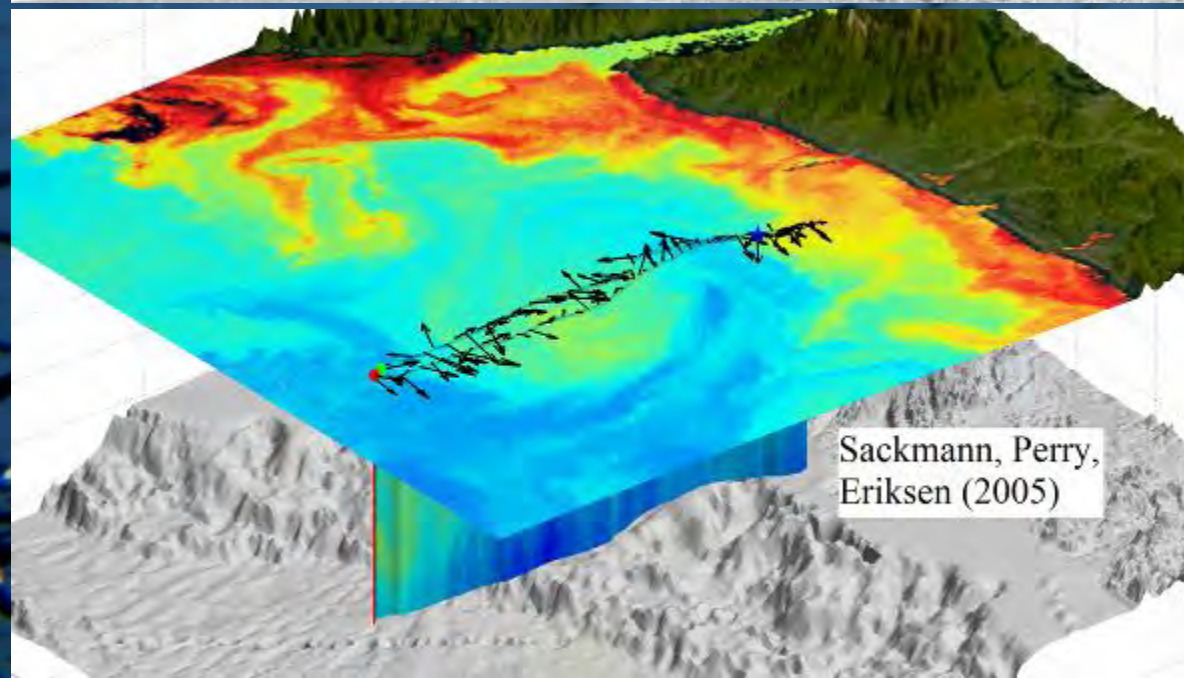
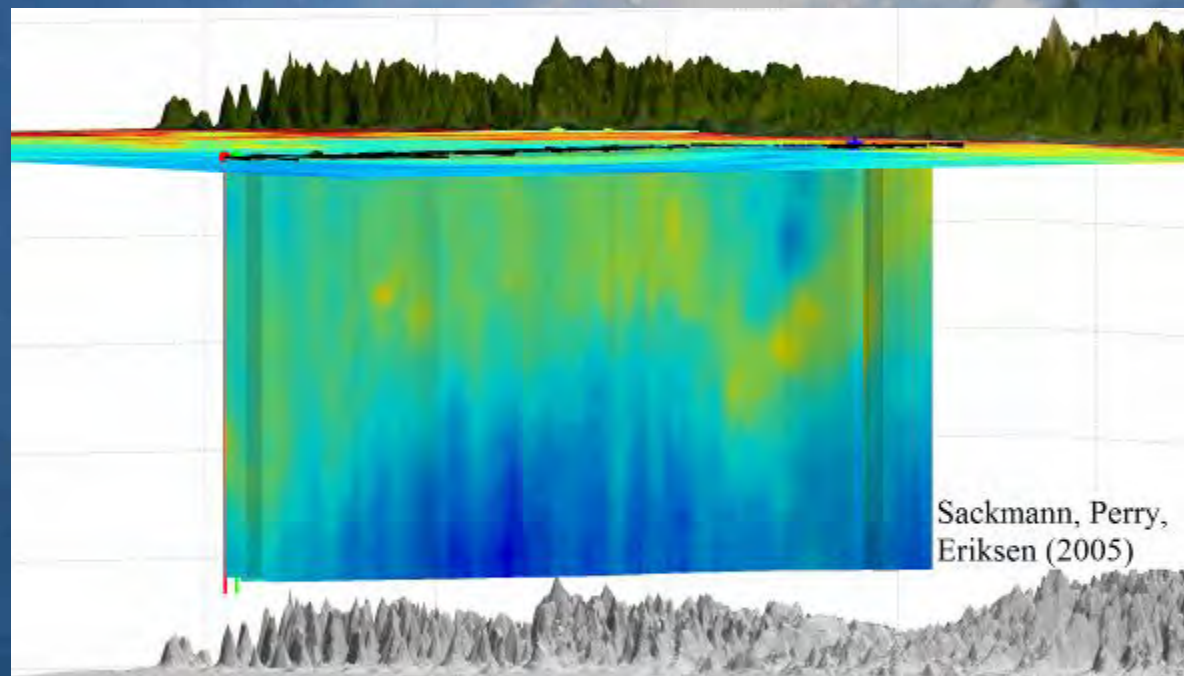
Wave Glider
(Liquid Robotics)



U.S. Navy



Chlorophyll Distribution, West Coast of U.S./Canada (SeaGlider + SeaWiF



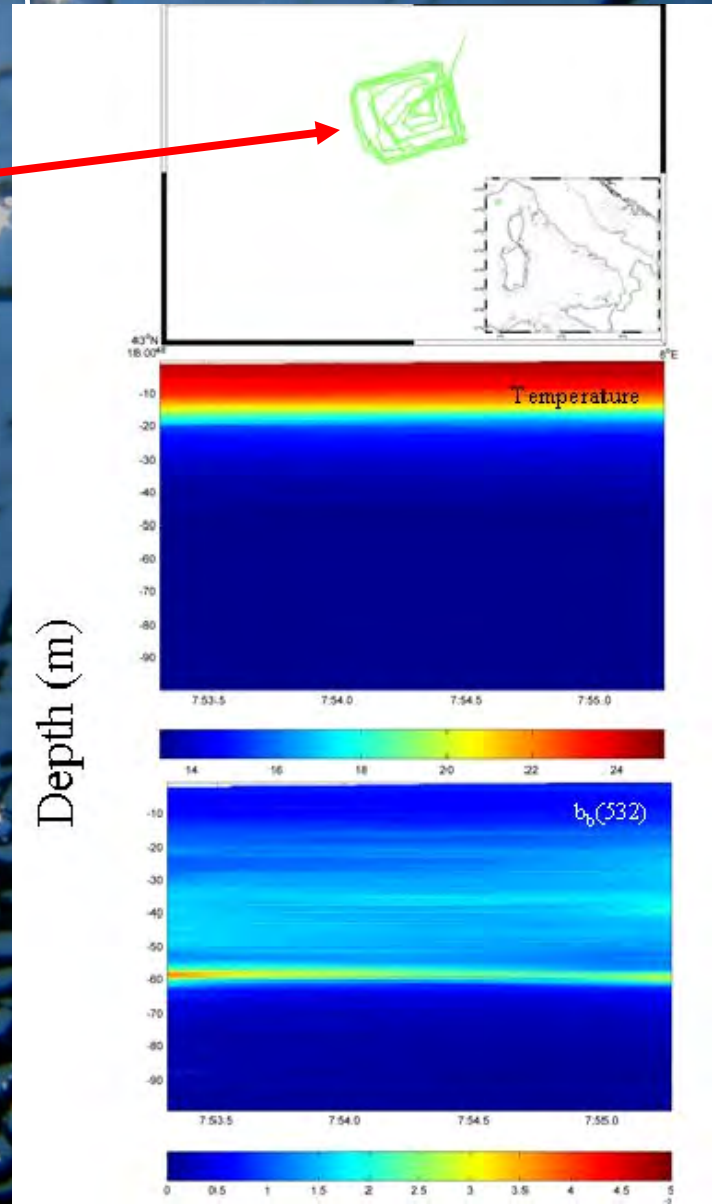
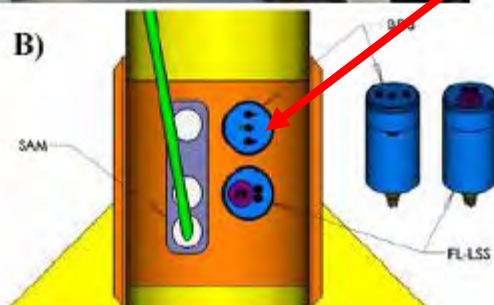
Courtesy of Brandon
Sackmann

SATLANTIC

Webb (Slocum) Glider:



Bio-optical Drifter Deployment at DyfaMed, 2004; Scattering coefficient reveals structure in POC. (Herve Claustre and Katarzyna Niewiadomska)



Powered AUV Platforms: REMUS

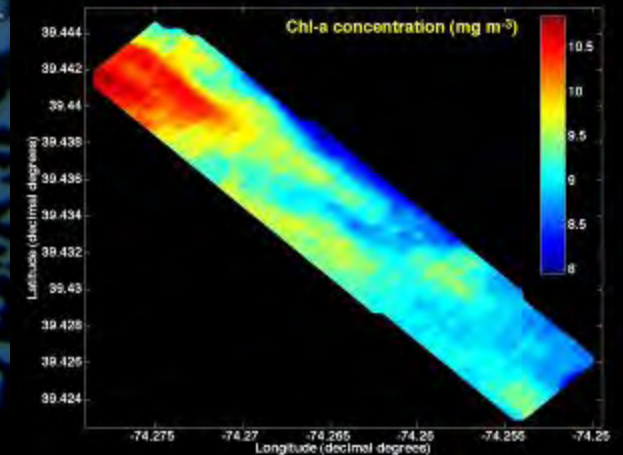
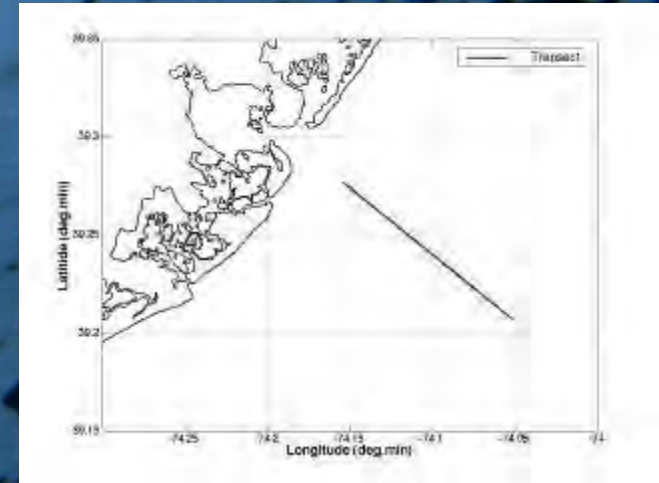
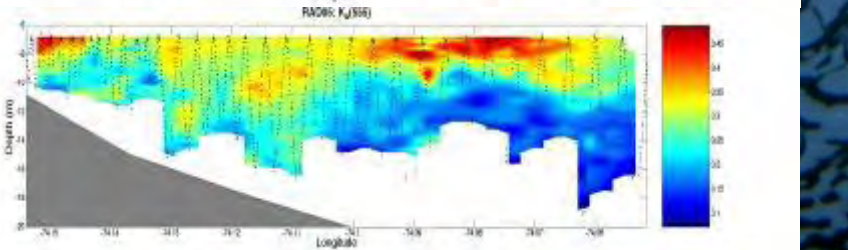
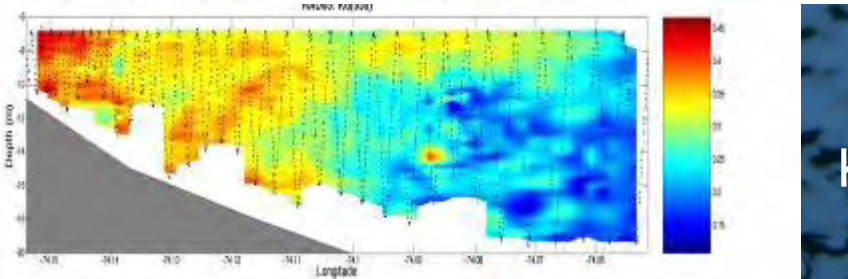
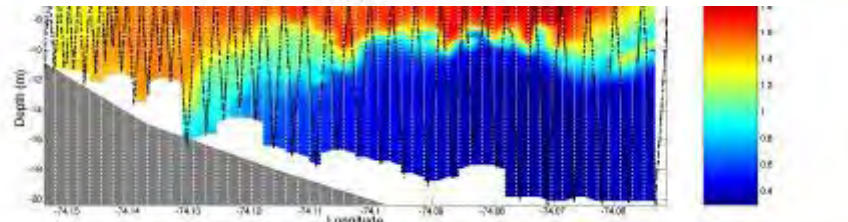
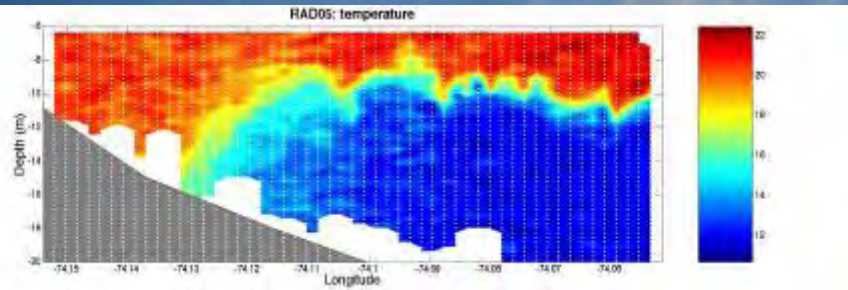
REMUS

Temp.

Fluoro.

$K_D(555)$

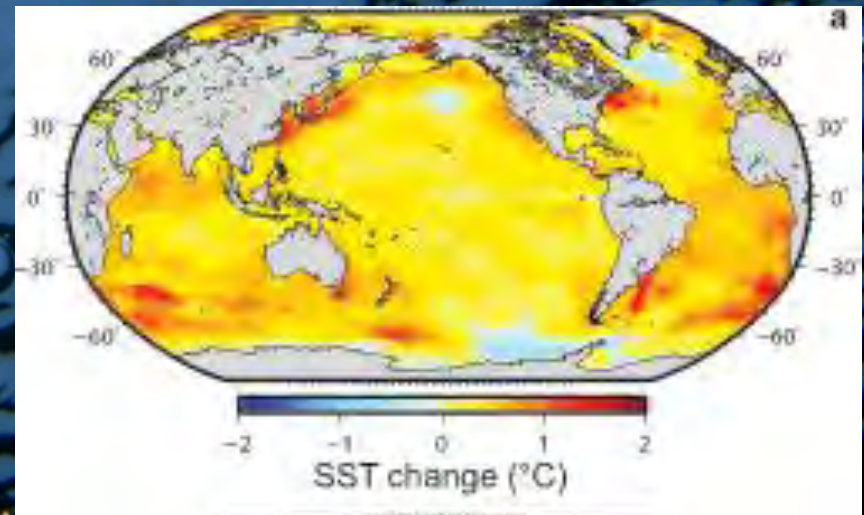
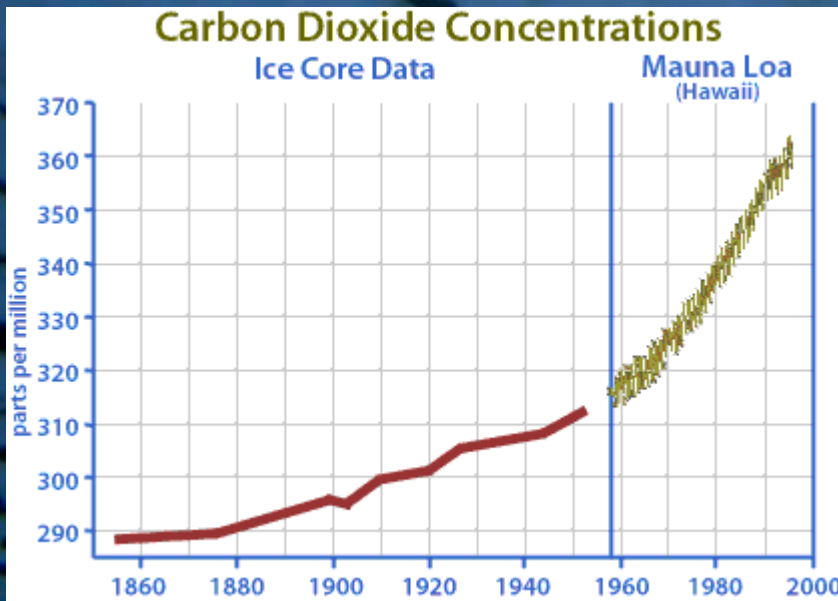
$K_{Lu}(555)$



Brown, Huot, Cullen, Lewis, 2004

A Hindcast Problem: Sea of Change

- The atmosphere and oceans are undergoing a wide range of rapid change on a global basis.
- As phytoplankton are largely at the mercy of their physical environment, there is concern that they are being affected as well – and as a result, changing the nature of marine food webs, upper ocean thermal structure, and geochemical fluxes.



Boyce, Lewis, Worm, 2010

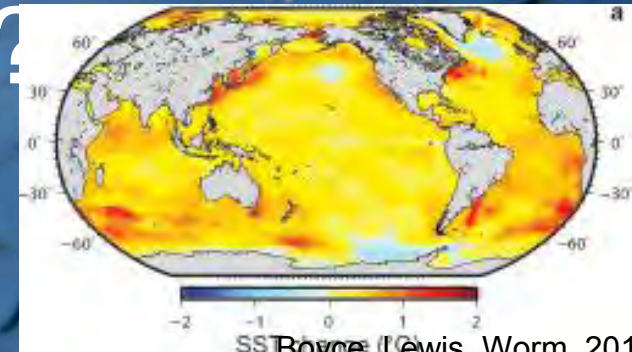
Adapted from an image courtesy of the White House Initiative on Global Climate Change.

What might cause changes in phytoplankton?

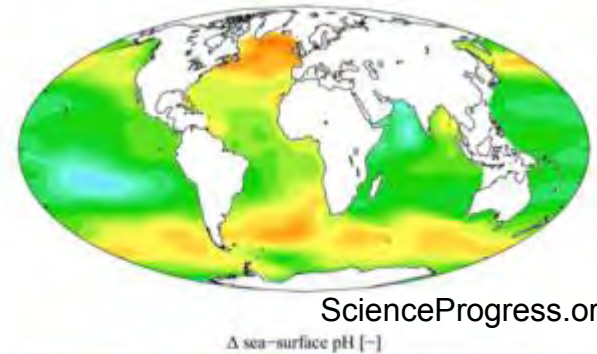
The surface oceans are measurably:

1. Warming as a result of radiative forcing (~0.5-1 degree over the last century)
2. Acidifying as a result of increased CO₂ flux into the ocean (“the other CO₂ problem”; ~ 0.1 unit in North Atlantic)
3. Deoxygenating, perhaps as a result of increased stratification due to surface warming

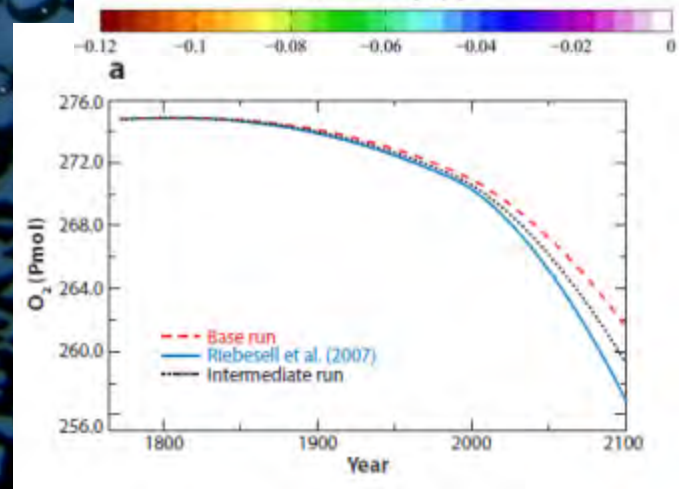
Warm, Sour and Putrid:
The “Angry Ocean” – Ken Denman



Boyce, Lewis, Worm, 2011

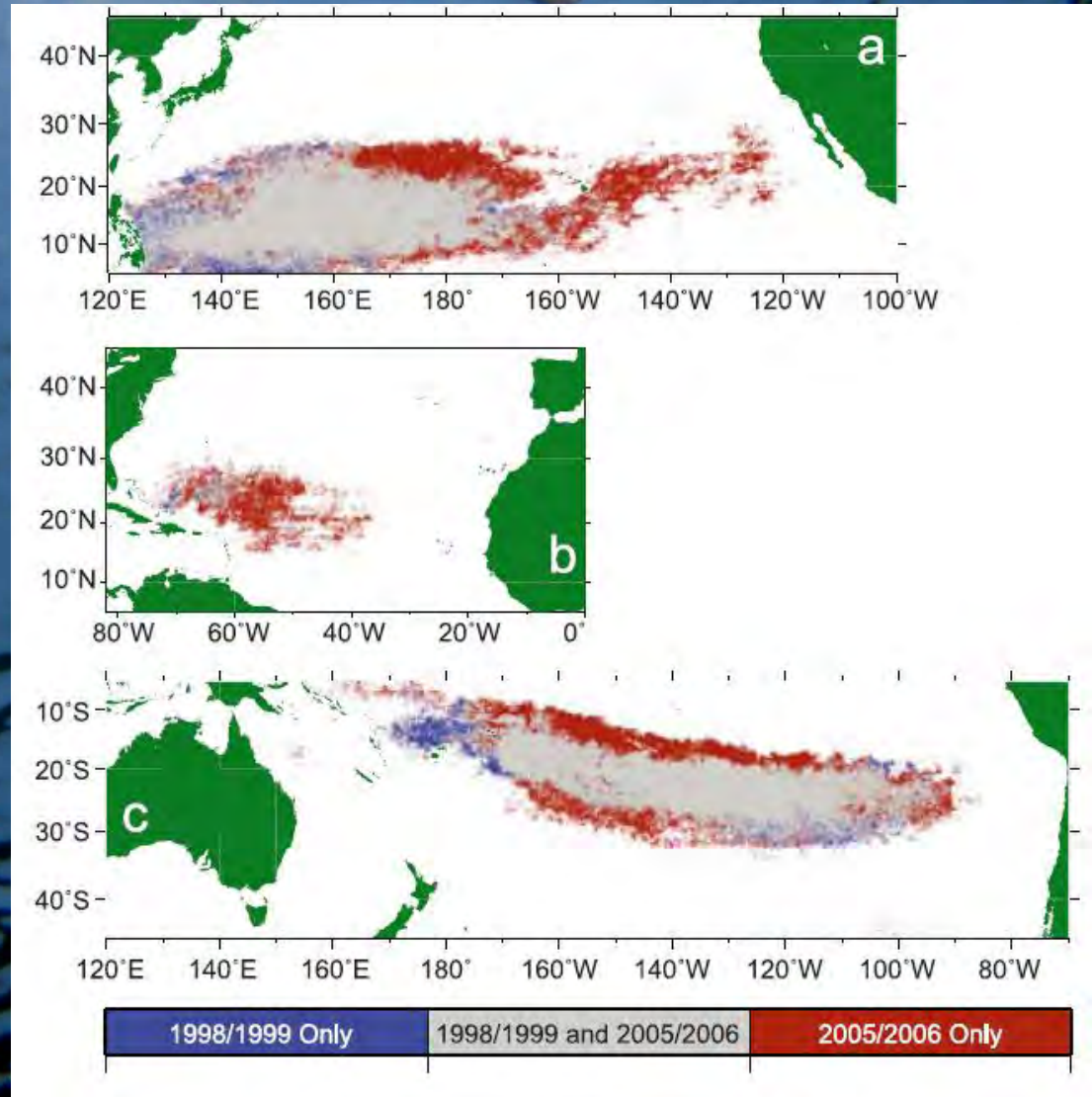


ScienceProgress.org



Expanding ocean deserts?

- 1998-2006 SeaWiFS
- Low-Chl regions expanding at $1-4\% \text{ yr}^{-1}$



Conflicting Results

- “...changes in global ocean chlorophyll from the CZCS (1979–1986) and SeaWiFS (1997–2000) records. Global spatial distributions and seasonal variability of ocean chlorophyll were similar, but **global means decreased** over the two observational segments.” *Gregg et al. GRL 2002*
- “Satellite-in situ blended ocean chlorophyll records indicate that **global ocean annual primary production has declined more than 6% since the early 1980's**. Nearly 70% of the global decadal decline occurred in the high latitudes.” *Gregg et al. GRL 2003*
- “The analysis of decadal changes from the CZCS to the SeaWiFS era **shows an overall increase of the world ocean average chlorophyll** concentration by about 22...” *Antoine et al. JGR; 2005*
- “The **period is dominated by an initial increase in NPP of 1,930 teragrams of carbon a year (Tg C yr^{-2}), followed by a prolonged decrease** averaging 190 Tg C yr^{-2} .” *Behrenfeld et al. Science 2006*

More...

- “...multidecadal changes in global phytoplankton abundances are related to basin-scale oscillations of the physical ocean, specifically the Pacific Decadal Oscillation and the Atlantic Multidecadal Oscillation...” (*Martinez et al. Science, 2009*)
- “while the ocean's most extreme deserts are increasing at an accelerating rate, some oligotrophic areas are simultaneously shrinking....in phase with the Pacific Decadal Oscillation Index from 1998–2007. (*Oliver and Irwin, GRL, 2009*)

“These results emphasize that it is difficult to draw unequivocal conclusions about long-term trends of biogeochemical properties in the oceans with the current relatively short bio-optical records.”

ZhongPing Lee, Shaoling Shang, Chuanmin Hu, Marlon Lewis, Robert Arnone, Yonghong Li, and Bertrand Lubac, 2010.

Time series of bio-optical properties in a subtropical gyre: Implications for the evaluation of interannual trends of biogeochemical properties. *Journal of Geophysical Research* 115, C09012, doi:10.1029/2009JC005865, 2010

A stronger statement

- “We find that detection of climate change-driven trends in the satellite data is confounded by the relatively short time series and large interannual and decadal variability in productivity. Thus, recent observed changes in chlorophyll, primary production and the size of the oligotrophic gyres cannot be unequivocally attributed to the impact of global climate change. Instead, our analyses suggest that a time series of ~40 years length is needed to distinguish a global warming...”
- Henson, S. A.; Sarmiento, J. L.; Dunne, J. P.; Bopp, L.; Lima, I. D.; Doney, S. C.; John, J.; Beaulieu, C. 2010. Detection of anthropogenic climate change in satellite records of ocean chlorophyll and productivity. *Biogeosciences* 7 (2010): 621-640, doi:10.5194/bg-7-621-2010

A problem

While satellites provide complete global coverage every several days, they have only been operating on a continuous basis since 1997 with the launch of SeaWiFS (the Coastal Zone Color Scanner operated sporadically from 1978 to 1986).

This is too short a record to evaluate climate-scale trends.

What to do?

A possible solution: Secchi Disk

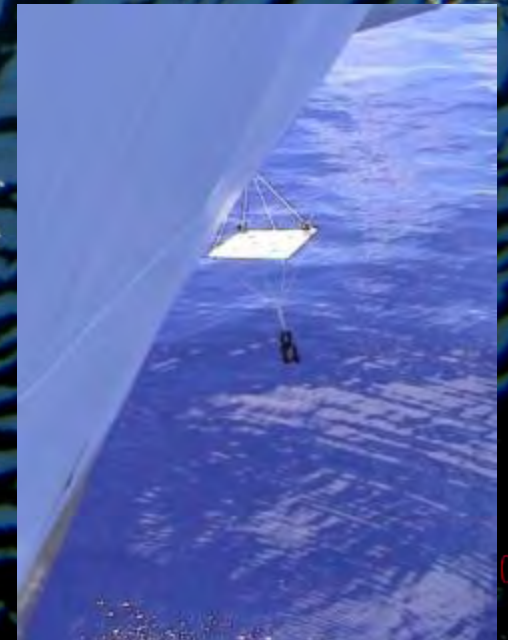


Baltic Sea, $Z \sim 0.5$ m

South Pacific Gyre, $Z \sim 72$ m



Off Halifax, CBC, 2010



Data available since late 1800's! Inversely $\sim$ to chlorophyll

Eyeball Optics

Background reflectance just below surface

Reflectance of disk

Sea surface effects



$$Z_{SD} = \frac{1}{\bar{c} + \bar{K}} \ln \left[\frac{\zeta(A - R(0))}{R(0)C_l} \right]$$

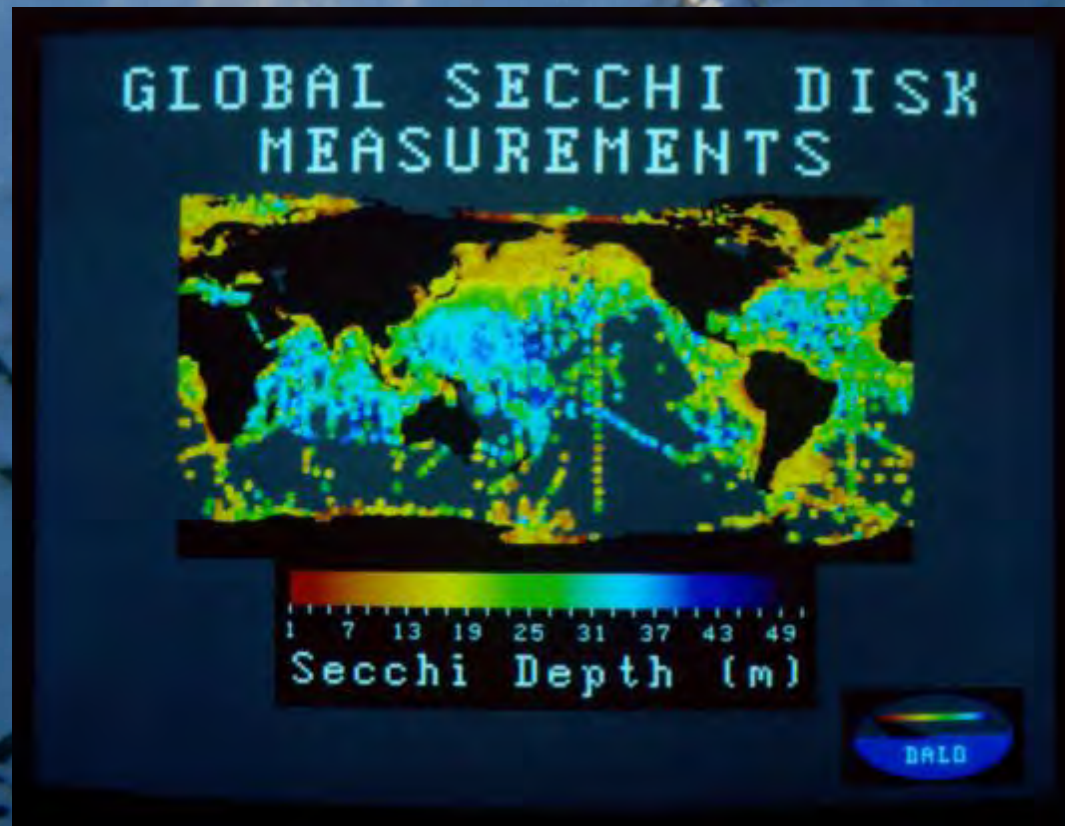
Optical
Properties of the
Sea

Eyeball Response



All of the things that one might think would interfere – the illumination conditions, sea-state, the nature of the disk, and human-to-human variability – actually have little effect since they are all contained inside the logarithm. The primary source of variability in the Secchi disk depth is the optical properties of the sea, specifically the attenuation of light.

Eyeballs are pretty good.



Lewis, Kuring
& Yentsch
1988

$$1/S.D. \sim \varepsilon (c+K) \sim f(Chl)$$

Prediction skill (Case 1) not significantly different than algorithms that use precisely measured upwelling radiances!

Eyeball Optics (2): Spectral Resolution

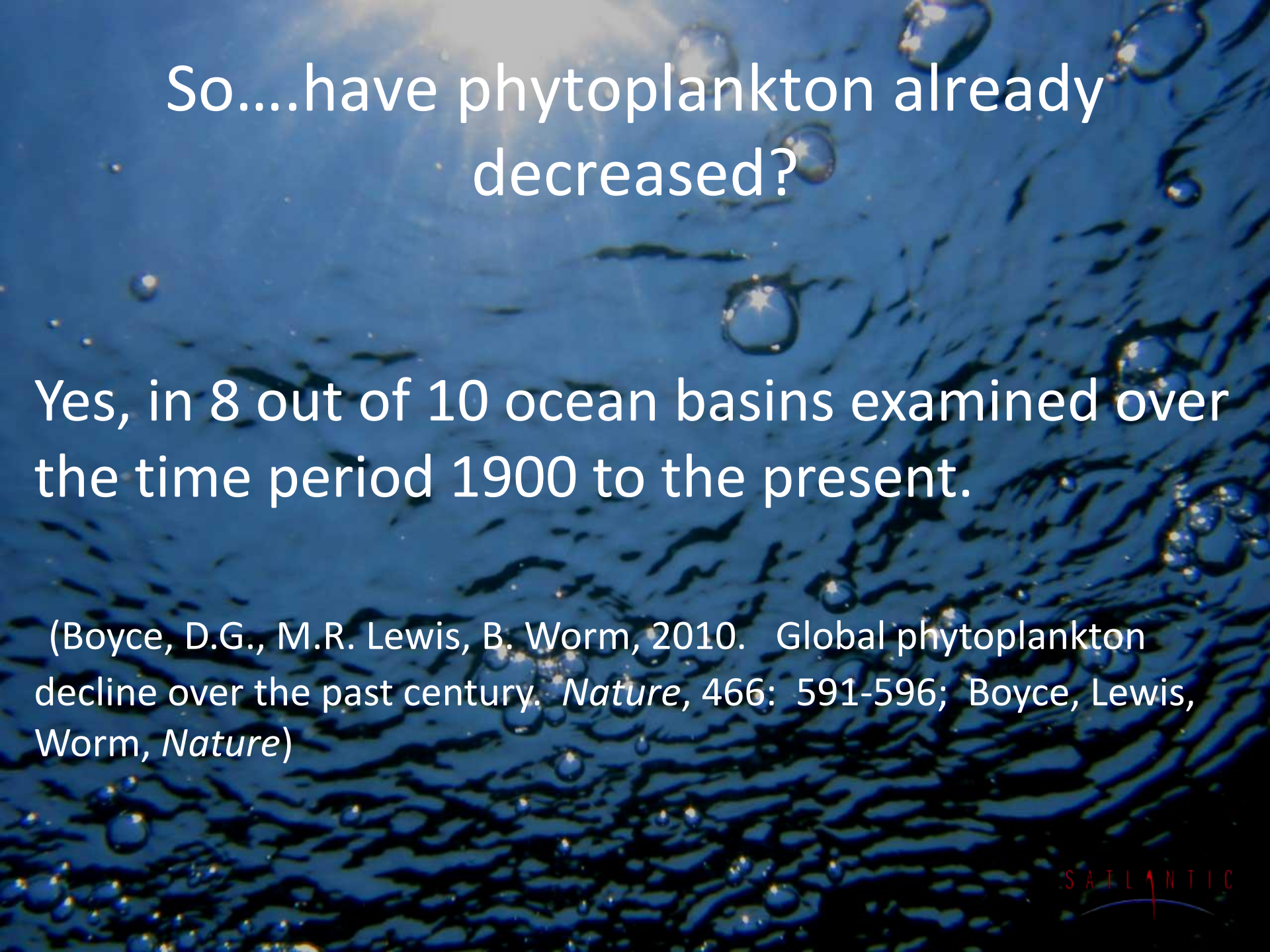


The color of the sea shows a great deal of variability from the deep violet-blue of the open ocean to degrees of green and brown in coastal regions. Before the advent of sensitive optical instruments, color was determined by visual comparison against standard reference standards such as the Forel Ule Color scale.

isolated chlorophyll

<http://www.oxygraphics.co.uk/lfu.gif>





So....have phytoplankton already
decreased?

Yes, in 8 out of 10 ocean basins examined over
the time period 1900 to the present.

(Boyce, D.G., M.R. Lewis, B. Worm, 2010. Global phytoplankton
decline over the past century. *Nature*, 466: 591-596; Boyce, Lewis,
Worm, *Nature*)

Approach: Observational Bases

- Collect all available Secchi disk and chlorophyll observations.
- Carry out comprehensive quality control.
- Remove all records for waters <25 m deep and <1 km from shore.
- Remove all records for chlorophyll observations >20 meters.
- Compute Chl concentration from Secchi disk using established relationships (Lewis et al., 1988, Falkowski and Wilson, 1992)
- Convince ourselves and others that the measurements provide observations that are statistically similar enough to combine.
- Resulted in 450,000 data points (compare to >300,000,000 *per day* with satellite!)

Approach: Analysis

- Used Generalized Additive Model (GAM's) to estimate Chl trends.
- These are extensions of Generalized Linear Models that do not require prior knowledge of the shape of the response function.
- Trends were estimated at local, regional and global scales.

$$\eta(\mu_i) = B_0 + B_1 \text{Year}_i + B_2 \text{Bathymetry}_i + f_2 \text{Latitude, Longitude}_i + f_3 \text{day}_i + \epsilon_i$$

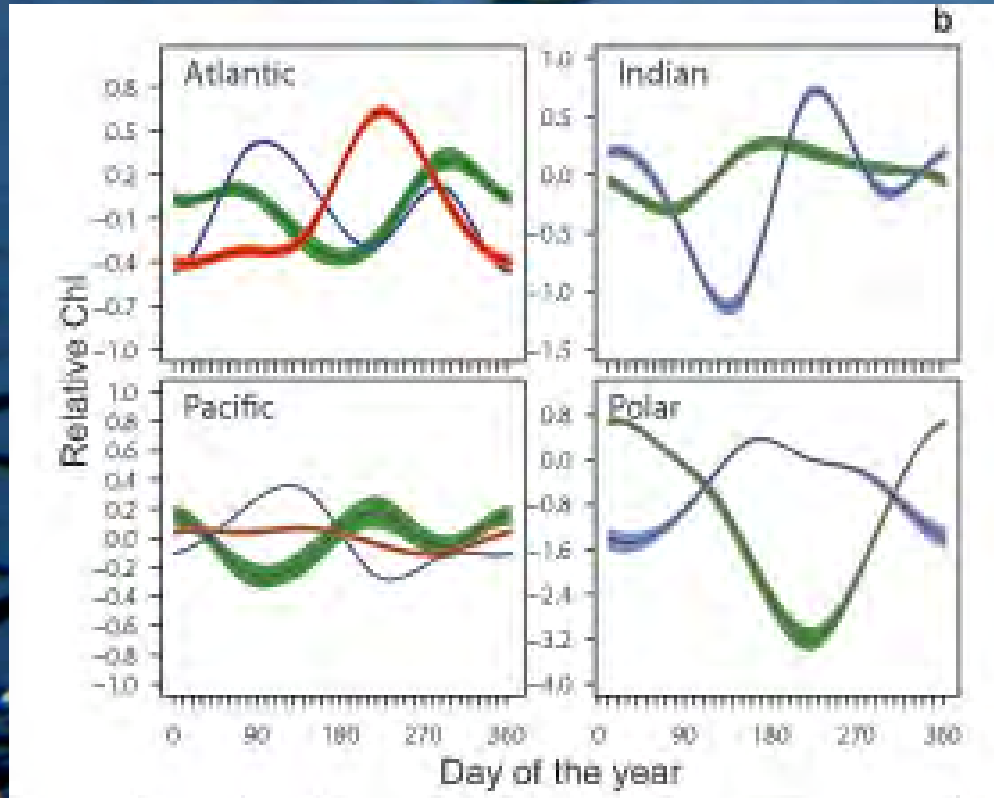
$\eta(\mu_i)$ is the monotonic link function of the expected mean Chl conc.,

B_0 is the intercept

B_i and f_i are parametric and non-parametric effects estimated from the data

ϵ_i is an error term.

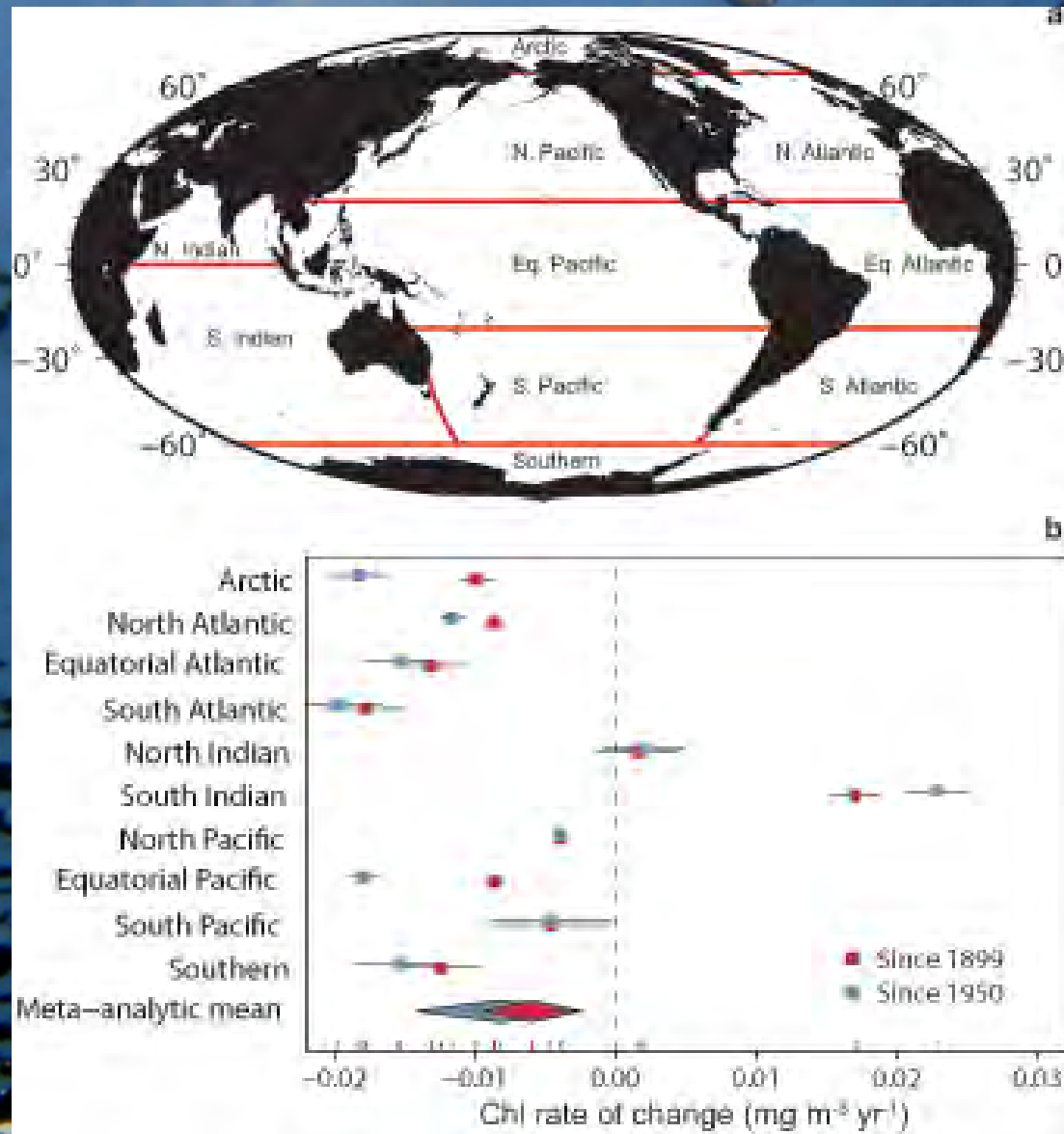
The analysis did a beautiful job of reproducing seasonal cycles at basin scales.



Blue is Northern
Red is tropical
Green is southern

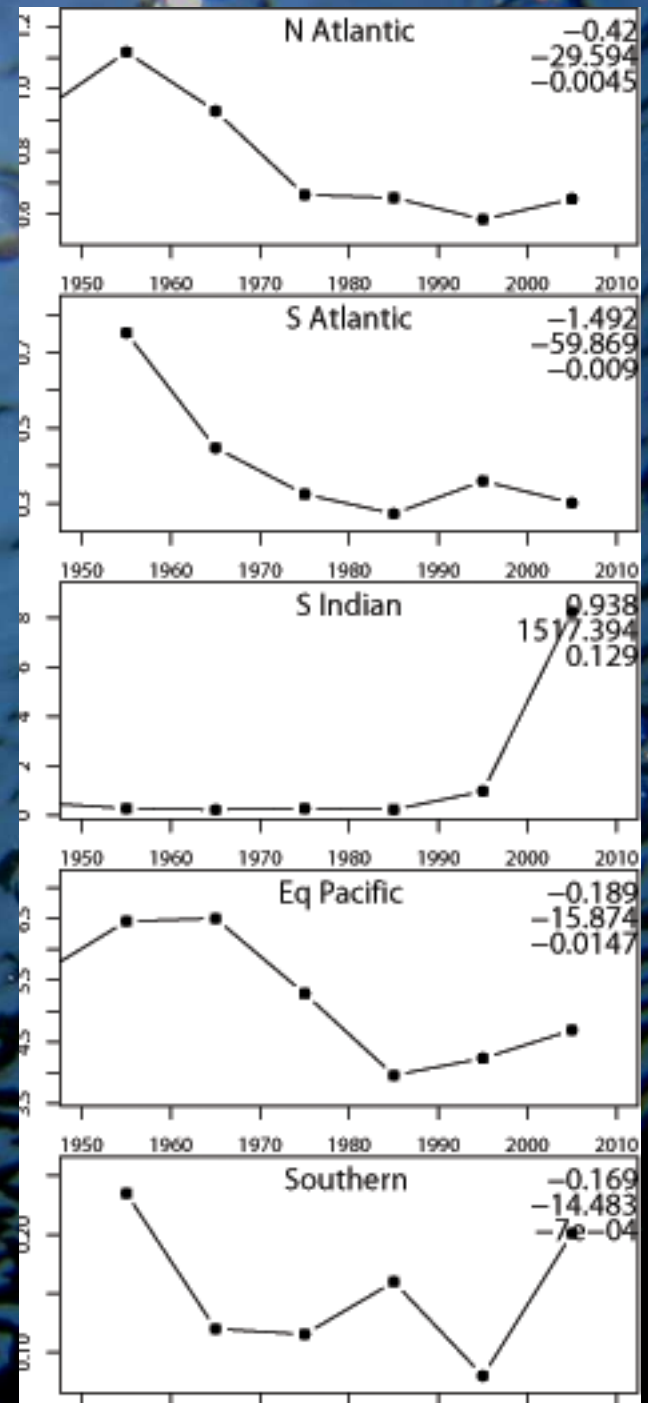
Envelope is approx.
95% Bayesian credible
limits.

But the long term trends are a bit frightening



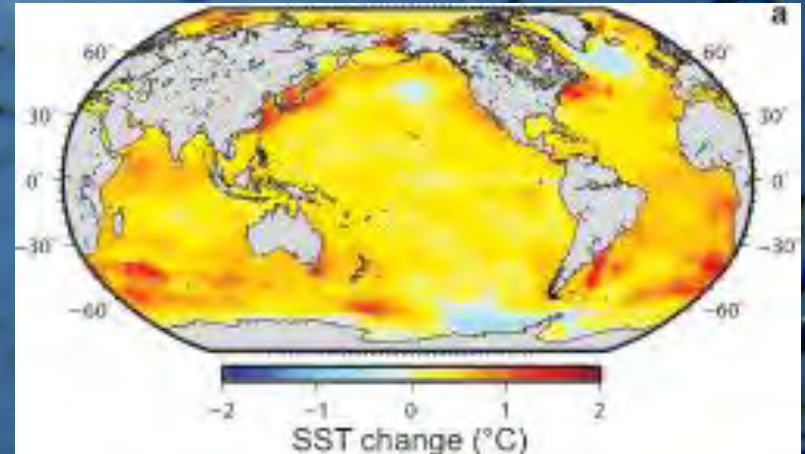
Time trend, decadal means, last 50 years

It is a somewhat complicated, but overall, in a meta-analytic mean sense, concentrations have declined ~40% of the global median over the last 50 years.



Why?

We examined a number of different variables to look for correlates with the observed declines in chlorophyll.

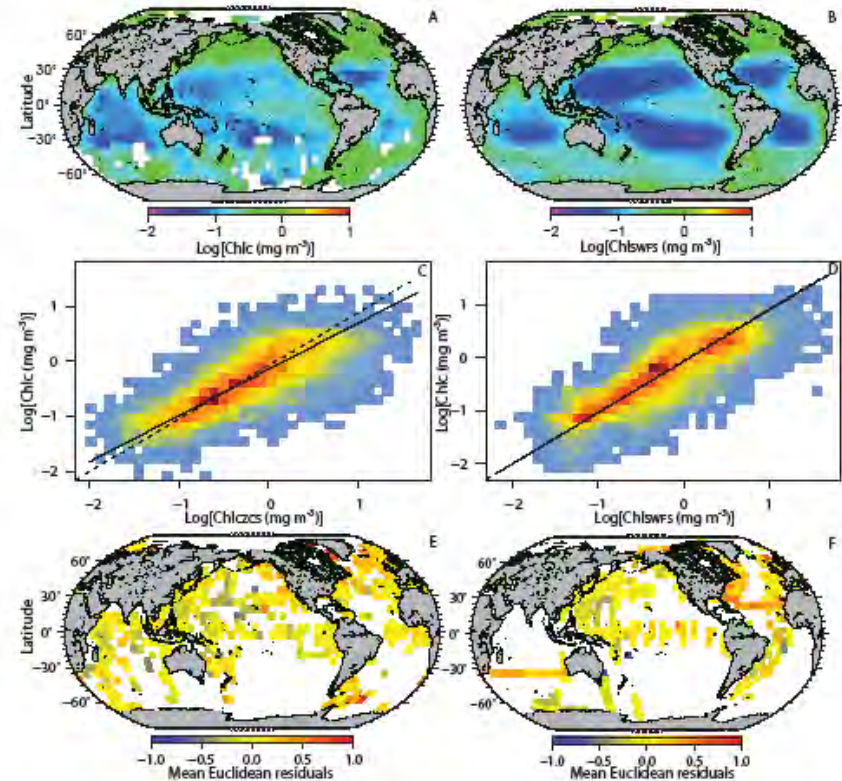
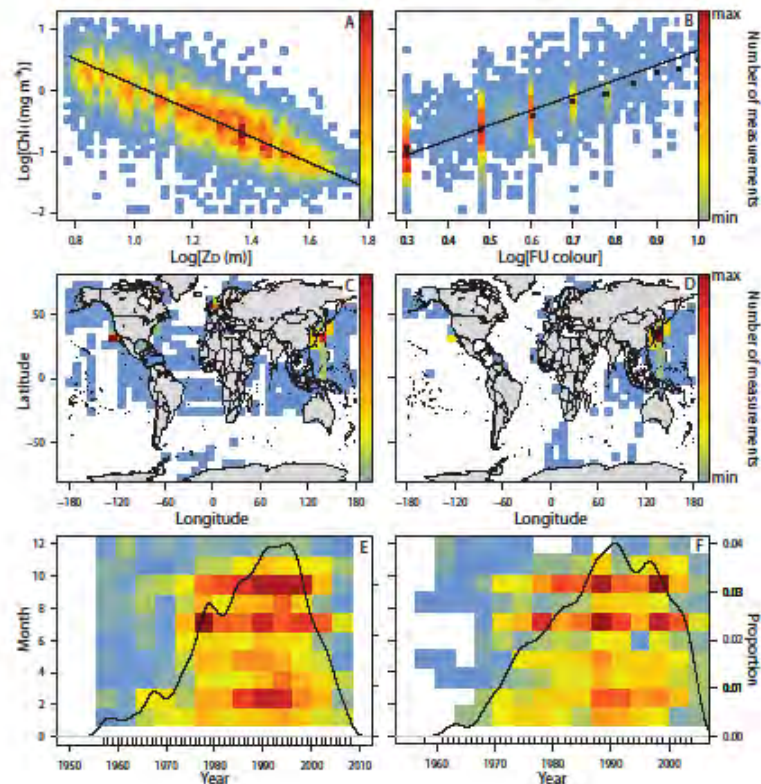


Result from GAM

The most consistent 'predictor' was SST:

Rising SST was associated with declining Chl in 8 of 10 regions examined (-0.21 to $-0.019 \text{ mg m}^{-3}(\text{°C})^{-1}$)

Recent Results



Integrating global phytoplankton data from 1890 to 2010. Daniel G. Boyce, Marlon Lewis, and Boris Worm, *Limnol. Oceanogr. Methods*, in press

Future Goal to establish conclusive climate trends: Climate Data Records

- *“....the committee defines a climate data record as “a time series of measurements of sufficient length, consistency, and continuity to determine climate variability and change.”*

Climate Data Records from Environmental Satellites: Interim Report. National Academies Press, 2004

- Note:
 1. Sufficient Length
 2. Sufficient Consistency
 3. Sufficient Continuity

Can we do this with satellite ocean color observations?

Conclusions (Part 2)

- In order to confirm changes in ocean biology for the future using ocean color satellite data, there is a strong requirement for ongoing vicarious calibration and characterization for all ocean color satellite sensors to ensure the development of long-term climate data records.
- Accurate and precise sea-going radiometry is required to achieve this
- As well, sea-going radiometry and in situ IOP observations, coupled with data assimilating models, are essential to provide the third dimension and to bridge cloudy days
- A widely distributed network of observations – encompassing buoys, autonomous profilers and ship observations - are needed, which can be objectively assimilated into a global synthesis for the entire constellation of ocean color satellites.
- And there will always be trade-offs.

But don't trade off messing around in boats!



***Merci, Thank you, спасибо, Danke, Obrigado, Gracias, 谢谢
감사합니다, Aitäh , Asante !***